

Particle-Based Rendering and its applications

2014/3/10

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Particle-Based Rendering and its applications

BACKGROUND

Big Data

From Science Projects to Social Networks to Smart Technology



Finding Answers where there are yet to be Questions...

Source: IDC's Digital Universe Study, sponsored by EMC, June 2011

Shonan meeting 046年間1.8ゼタバイトのデータ生成

Supercomputer

2010

2011

2012

2013

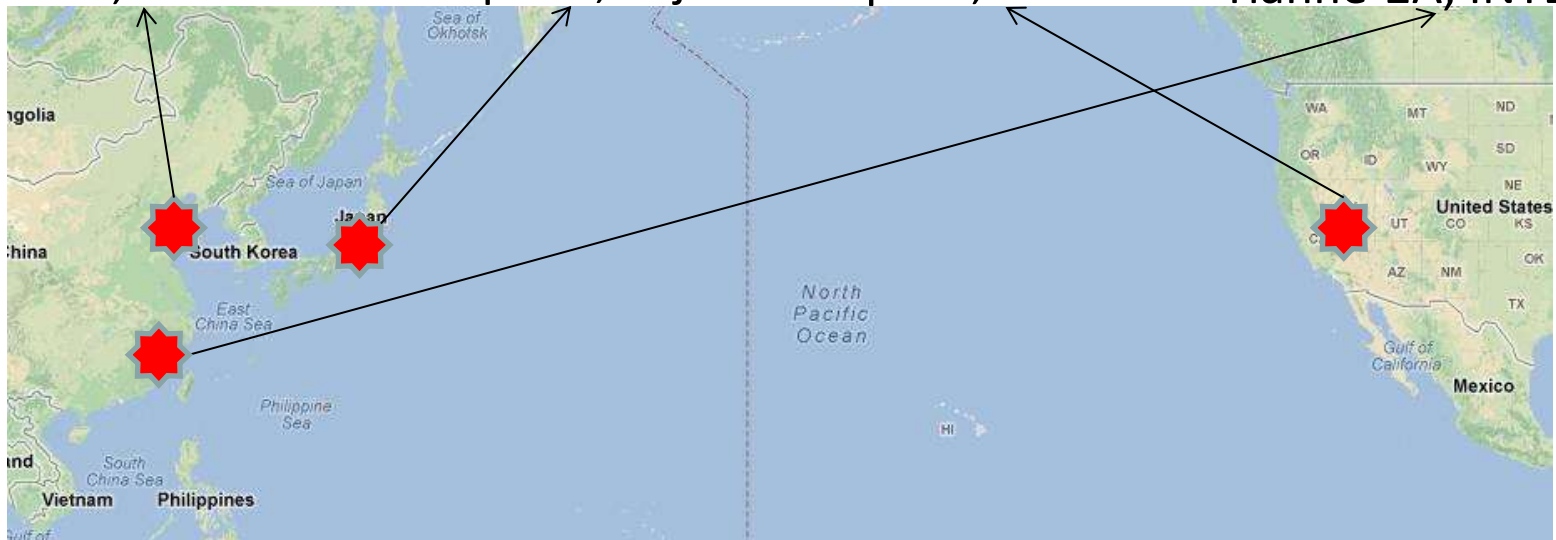


Tianhe-1A, NVIDIA

K computer, Fujitsu

Sequoia, IBM

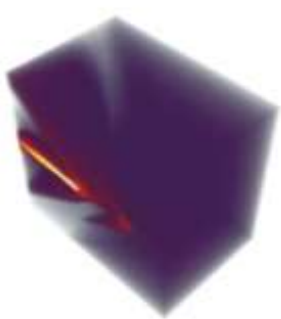
Tianhe-2A, INTEL



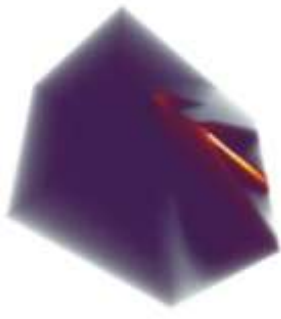
Requirement for efficient volume rendering to shorten the time to inspiration

Related work (1/2)

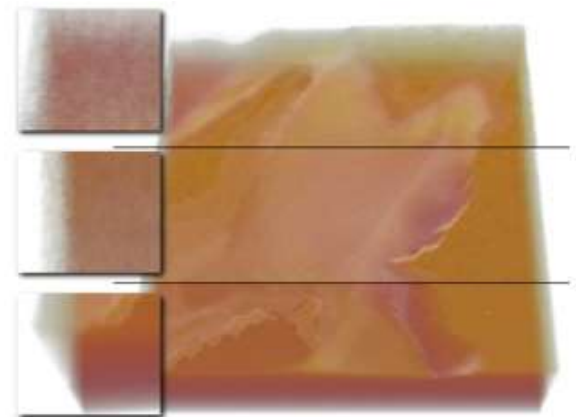
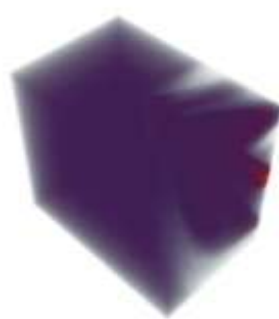
- Performance improvement of visibility sorting
 - HAVS [Steven et. al., 2005]
 - 1.3 fps for 1.4M tets.
 - Point-based technique [Erik.W et. al., 2007]
 - 0.3 fps for 6.3M tets.



HAVS



Shonan meeting 046



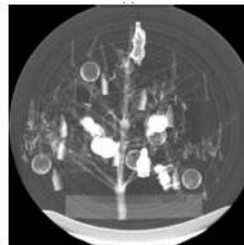
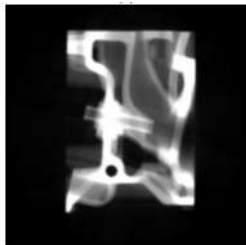
Point-based technique

Related work(2/2)

- Sort-free algorithm by model simplification
 - Only absorption
 - Monte Carlo Volume Rendering [Csselfalvi et. al., 2003]
 - 1.4 fps for 16M points (for regular volumes)
 - Only emission
 - Point-based rendering [Zhou et. al., 2006]
 - 20 fps for 17.6M tets.



Monte Carlo Volume Rendering



Shonan meeting 046



Point-based rendering

Comparison

- Parameters
 - r : Radius of a particle
 - N_c : Number of cells

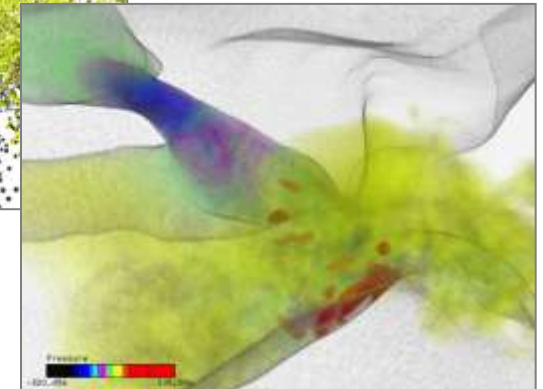
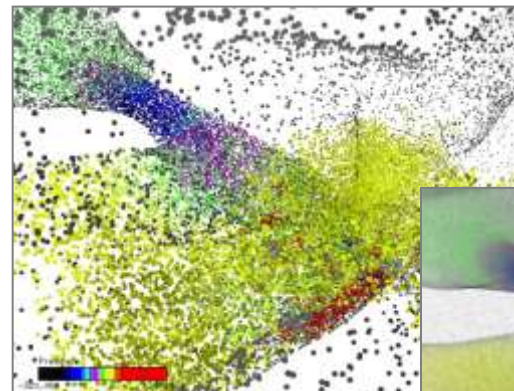
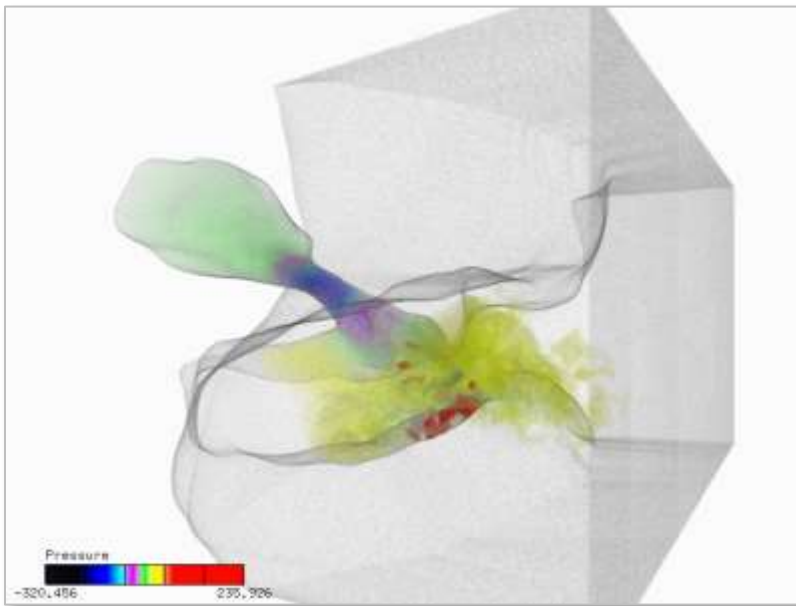
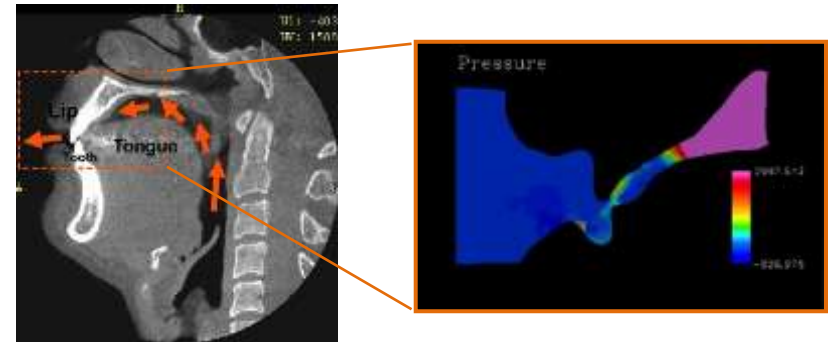
Method	Number of primitives	Visibility sorting
Particle-based	$O(1/r^2)$	Not required
Point-based	$O(N_c)$	Required

Particle-Based Rendering and its applications

APPLICATIONS

Oral Airflow Simulation

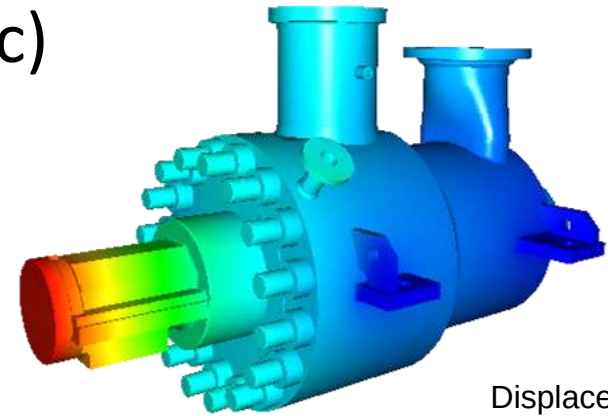
- Cell type: hexahedron
- # of cells: 71 M
- Data size: 3.23 [Gbytes]
- # of particles: 0.73 M
- Particle generation time: 22.0 [sec]



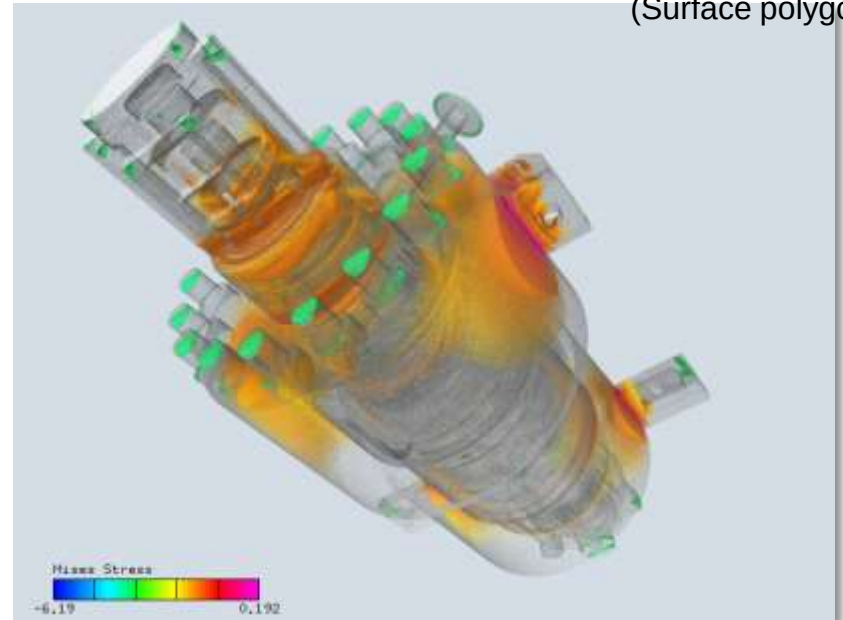
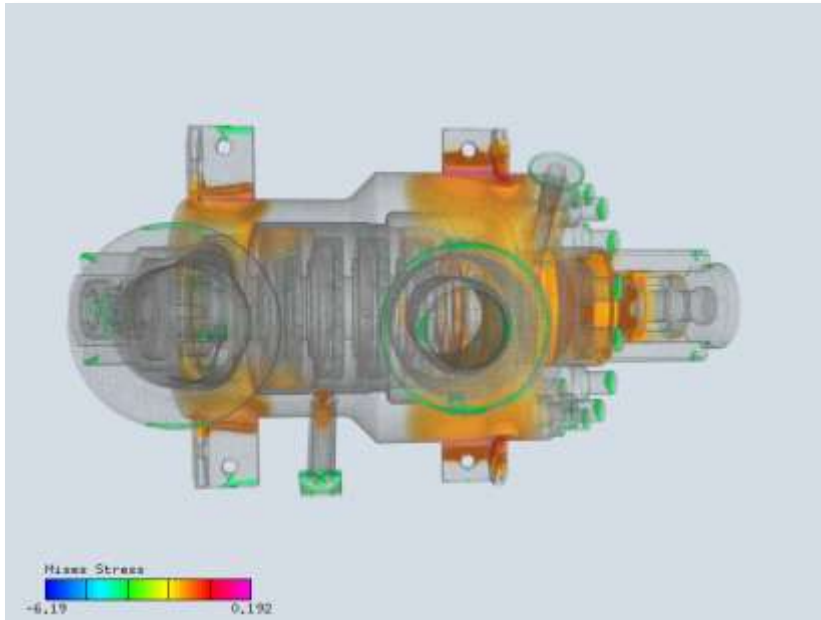
Naohisa Sakamoto, Takuma Kawamura, Koji Koyamada, Kazunori Nozaki: Improvement of particle-based volume rendering for visualizing irregular volume data sets. Computers & Graphics 34(1): 34-42 (2010)y

Structural Analysis on a Pump

- Cell type: tetrahedron (quadratic)
- # of cells: 26 M
- Data size: 1.93 [Gbytes]
- # of particles: 10 M



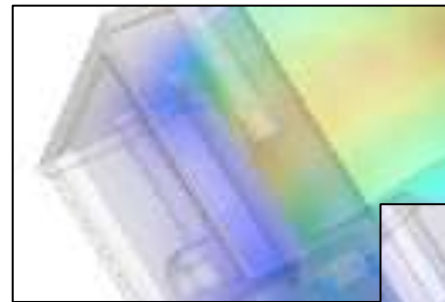
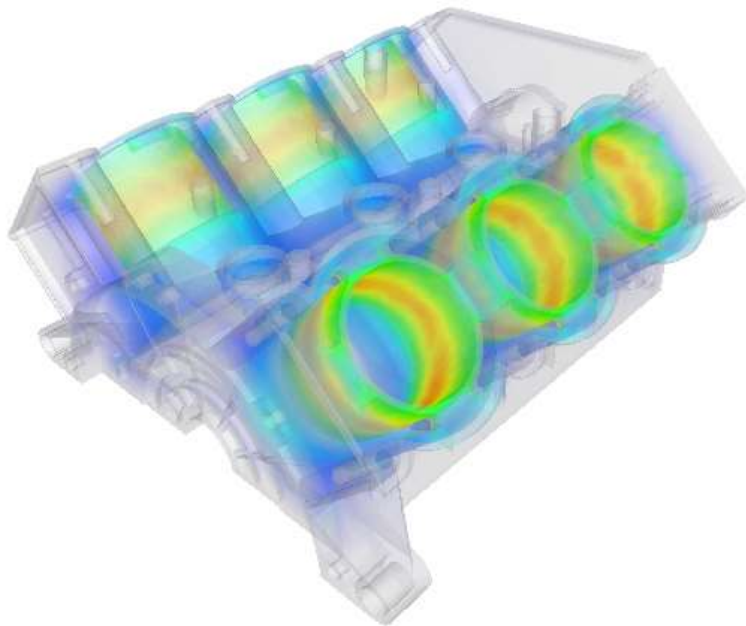
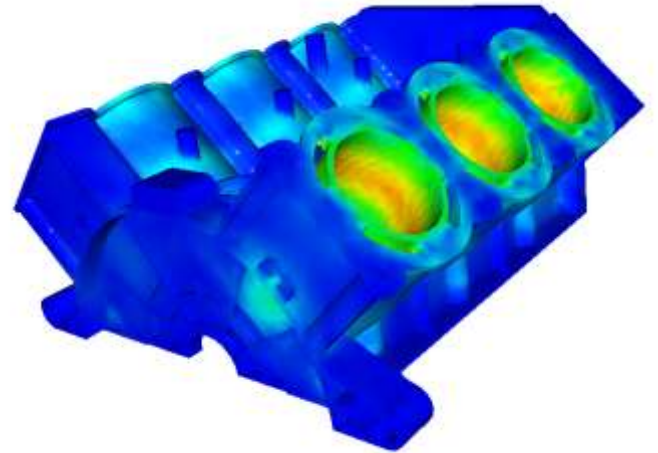
Displacement
(Surface polygon)



Naohisa Sakamoto, Hiroshi Kuwano, Takuma Kawamura, Koji Koyamada, Kazunori Nozaki, "Visualization of Large-scale CFD Simulation Results Using Distributed Particle-Based Volume Rendering", International Journal of Emerging Multidisciplinary Fluid Sciences, Vol.2, No.2, pp73-86,2010,

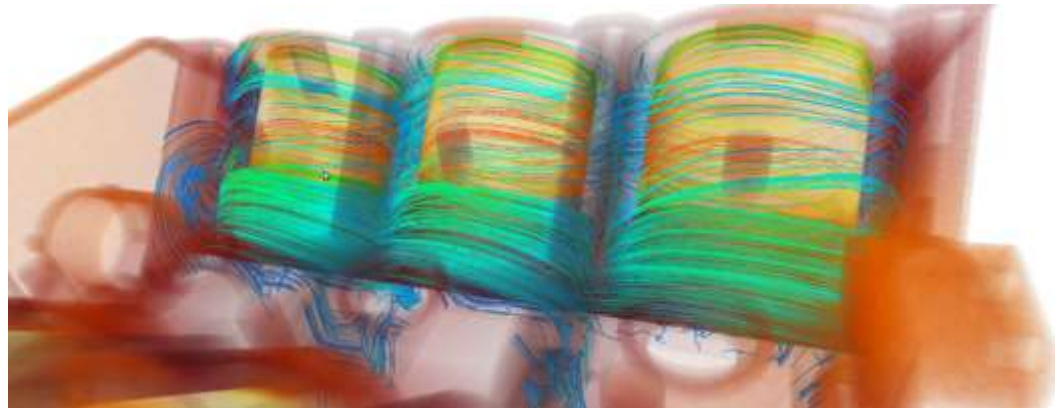
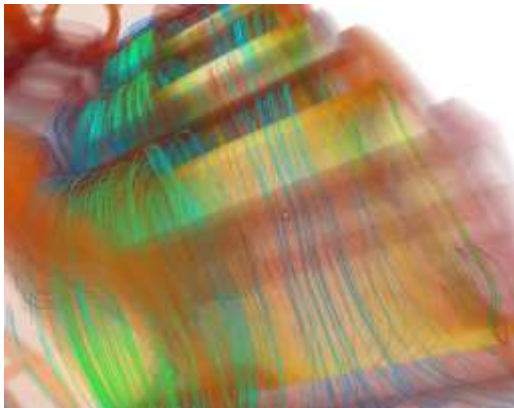
V6 engine data

- Cell type: tetrahedron
- # of cells: 282K
- Data size: 170 [Mbytes]

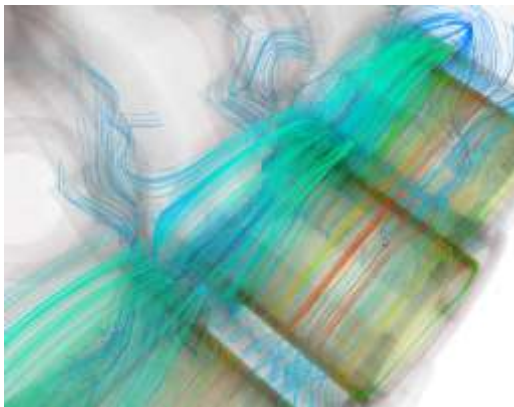


Volumes and hyper streamlines

- Displacement (volume) and stress tensor (streamlines)



- Misses stress (volume) and stress tensor (streamlines)



Rendering results on 40 LCDs

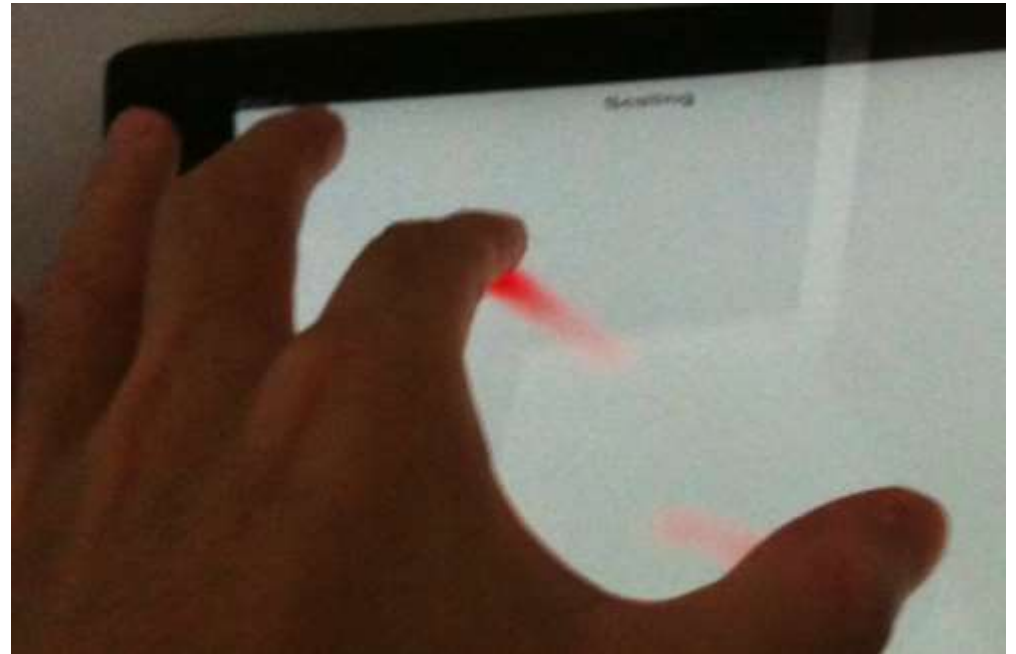
- Volume + boundary surfaces + hyper streamlines



N.Sakamoto, J.Nishimura, K.Koyamada, "Stochastic Approach for Integrated Rendering of Volumes and Semi-transparent polygons on a High-resolution Display System(poster)", The 5th IEEE PacificVis Symposium, 2012, **Best Poster Award**

Multi-touch interface

- Using tablet PC
- Multi-touch operation



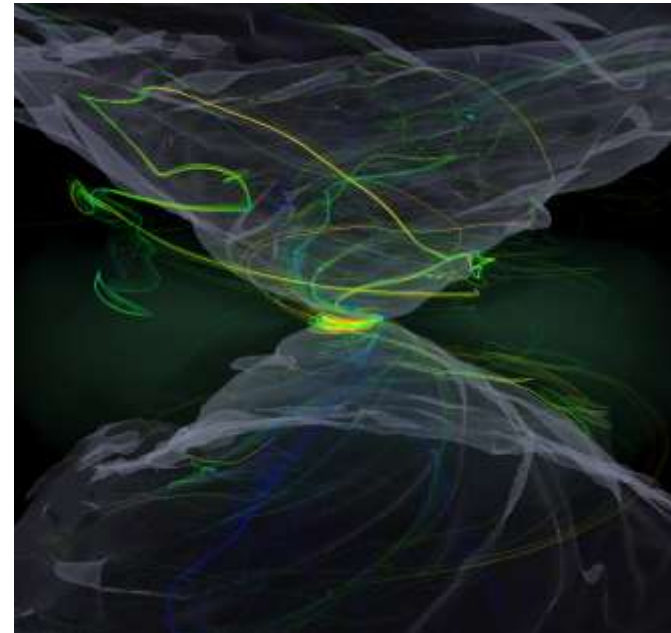
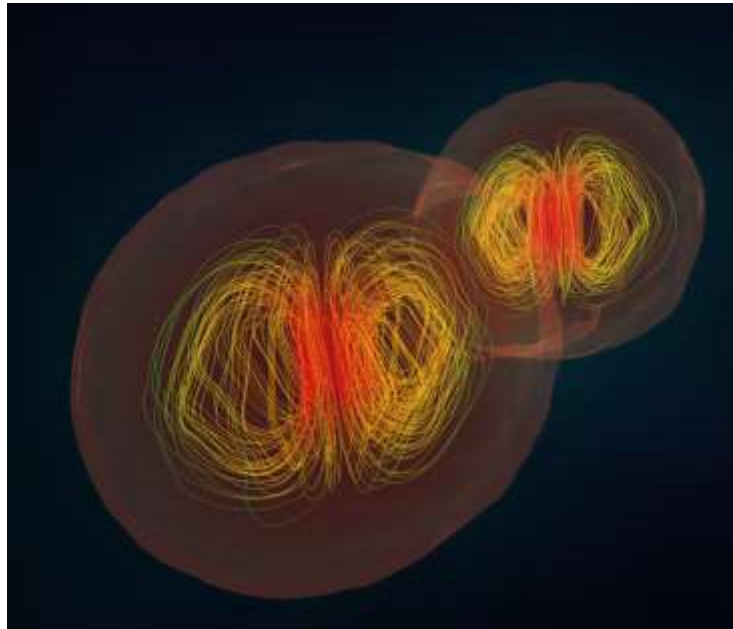
Gesture interface

- Using stereo camera (Microsoft Kinect)
- Gesture operation



Visualization of astrophysics data

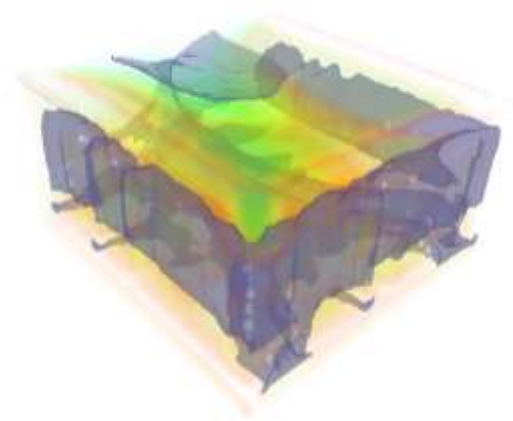
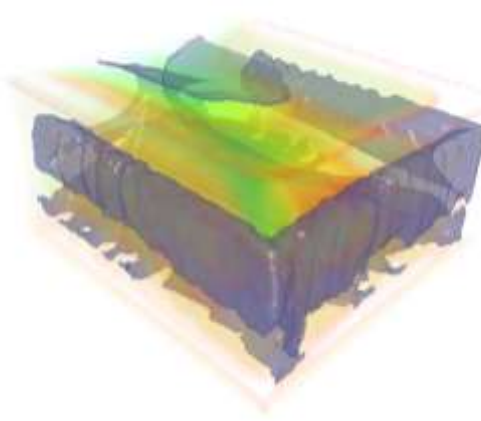
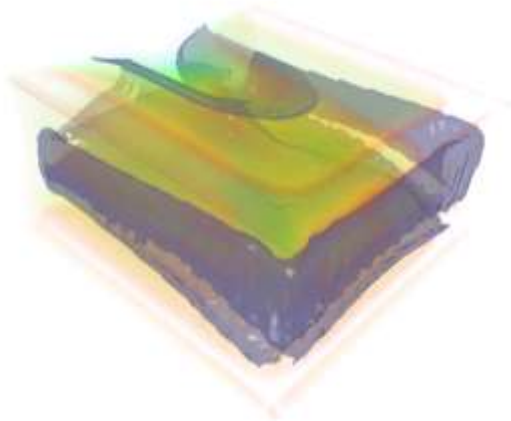
- Magnetic field and mass density around a simulated black hole which is generated by a collision of binary neutron star merger.



Data courtesy of Prof. Shibata, Dr. Kiuchi, Dr. Sekiguchi, Kyoto University

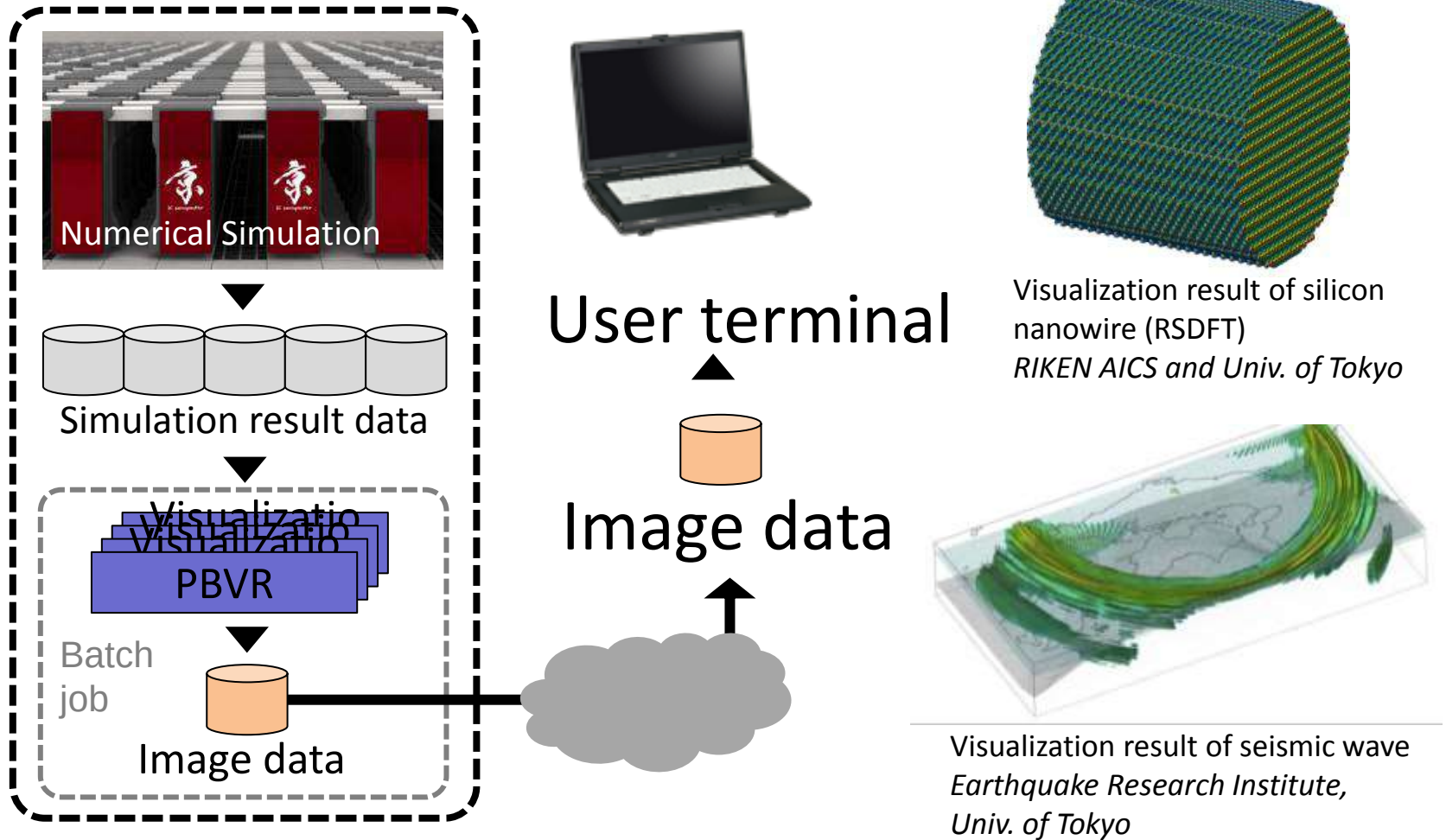
Visualization of fluid dynamics data

- Immiscible multi-phase fluid in a tank with vertical moving wall by MICS (Multiphase Incompressible flow solver with Collocated grid System)



Data courtesy of Prof. Ushijima, Mr. Fujioka, Kyoto University

Parallel PBR on K computer

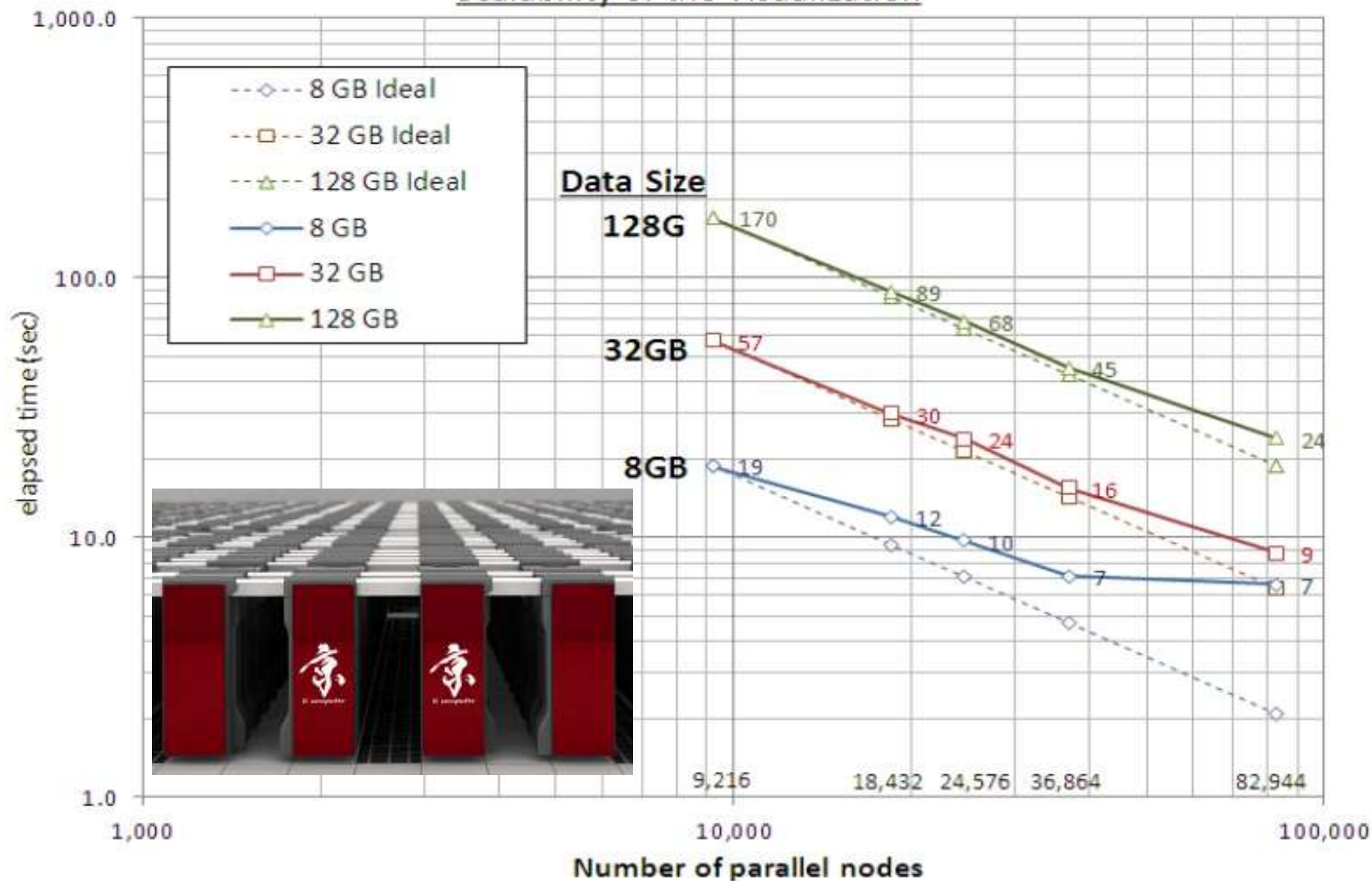


Ogasa et al., "Visualization technology for the K computer", Fujitsu Scientific & Technical Journal, Vol.48, No.3, 2012.

Visualization in K-computer system

Fujitsu Sci. Tech. Journal, Vol.38 No.4, 2012

Scalability of the Visualization

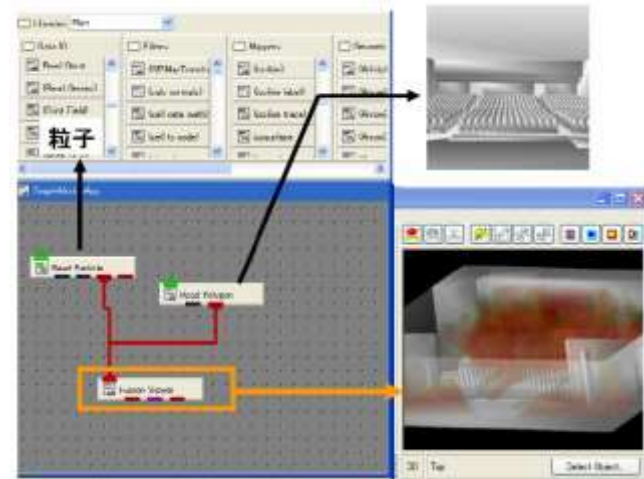


Technology transfer to AVS/Express

<http://www.avs.com/solutions/express/>



Since its first release in 1995, AVS/Express has been selected by thousands of corporations, solution providers, academic institutions and government agencies to provide powerful insight to nearly one million end-users in an array of industries.

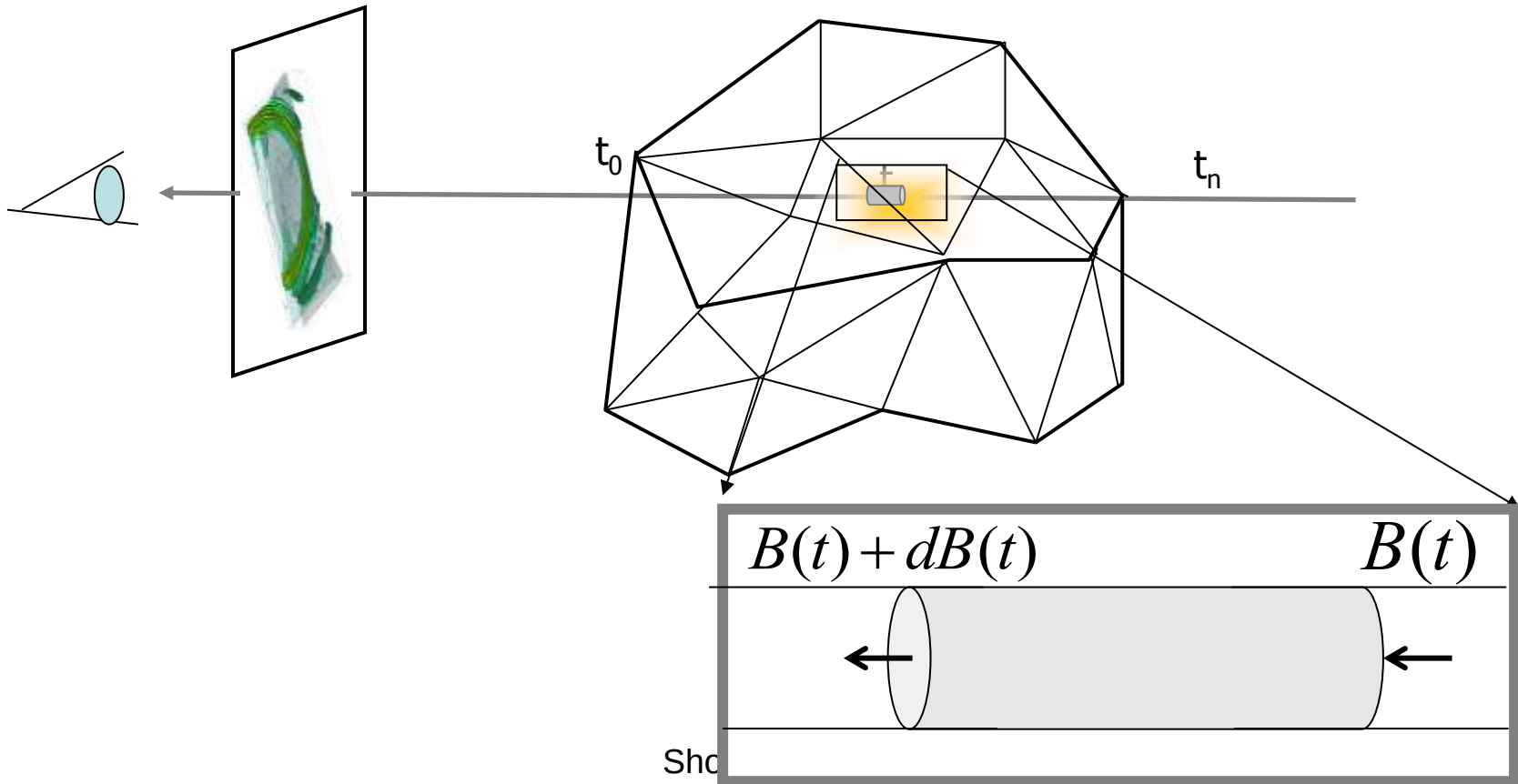


Particle-Based Rendering and its applications

RENDERING AND PARTICLES

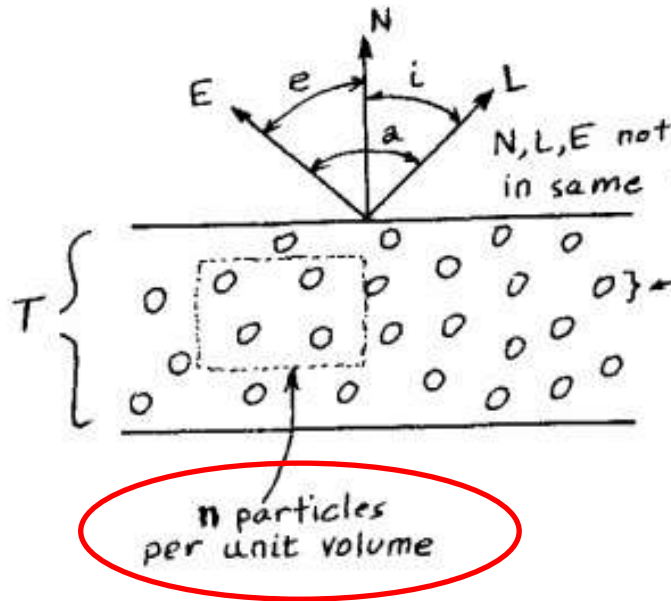
What is volume rendering?

- Technique used to display a 2D projection of a 3D discretely sampled data set.



Volume rendering and particles

- The number of particles follow the poisson process



All other particles are assumed to be of radius p also. For such a particle to be completely outside the cylinder its center must be outside this volume. Statistically, then, the attenuation of light traversing a cylinder of radius p and volume V is $P(0;V)$ = the probability of 0 particles in volume V . Now the expected number of particles in a given volume V is nV . If n is small this can be modelled as a Poisson process and

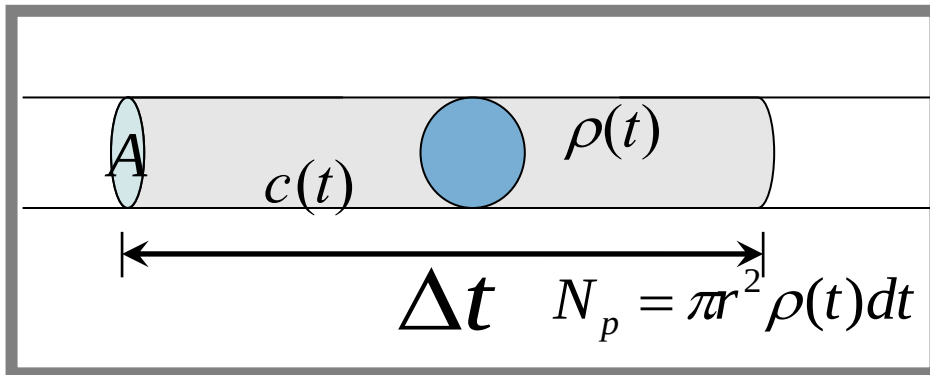
$$P(0;V) = \exp(-nV)$$

J. F. Blinn, "LIGHT REFLECTION FUNCTIONS FOR SIMULATION OF CLOUDS AND DUSTY SURFACES,"

Opacity definition

- Probability that there are more than one particles

$$P(N = k) = \frac{\exp(-N_p) N_p^k}{k!}$$



$$P(N = 0) = \exp(-N_p)$$

$$\alpha = 1 - \exp(-N_p)$$

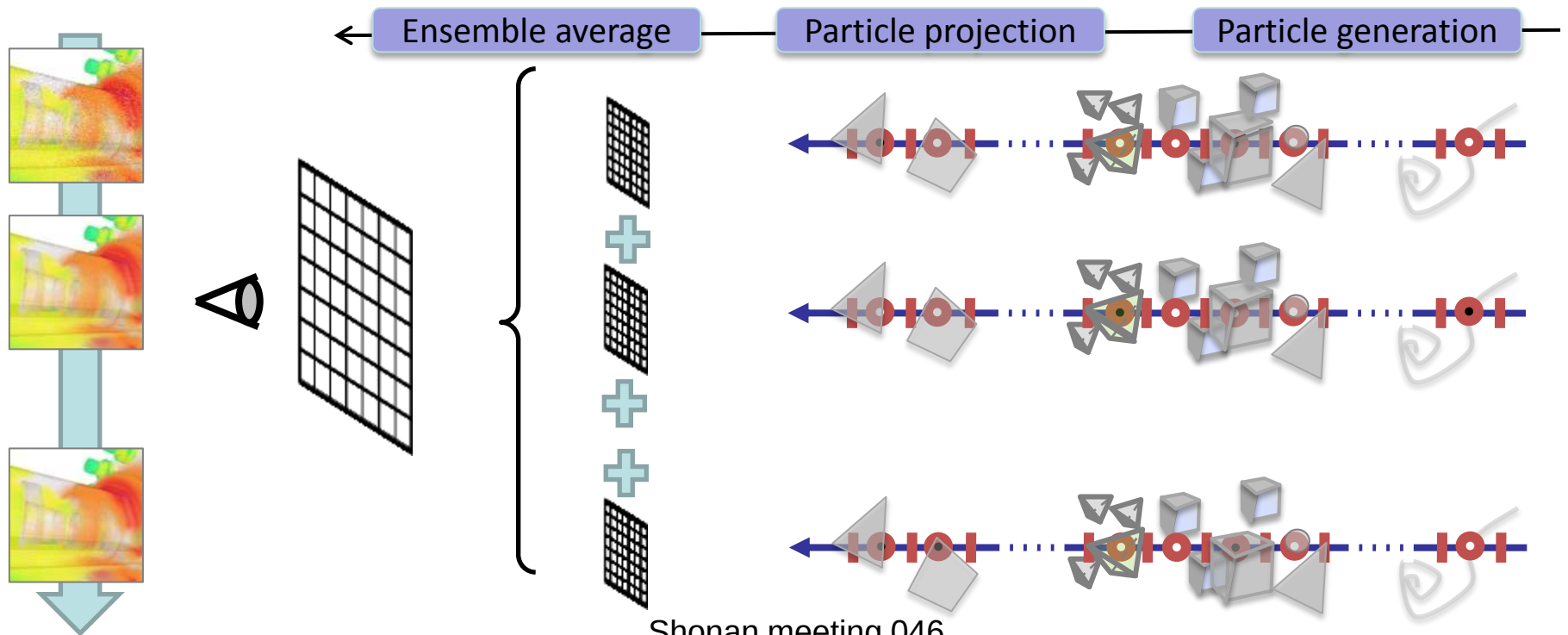
$$\rho = -\frac{\log(1 - \alpha)}{\pi r^2 \Delta t}$$

Particle-Based Rendering and its applications

PARTICLE-BASED RENDERING

Particle-based rendering (PBR)

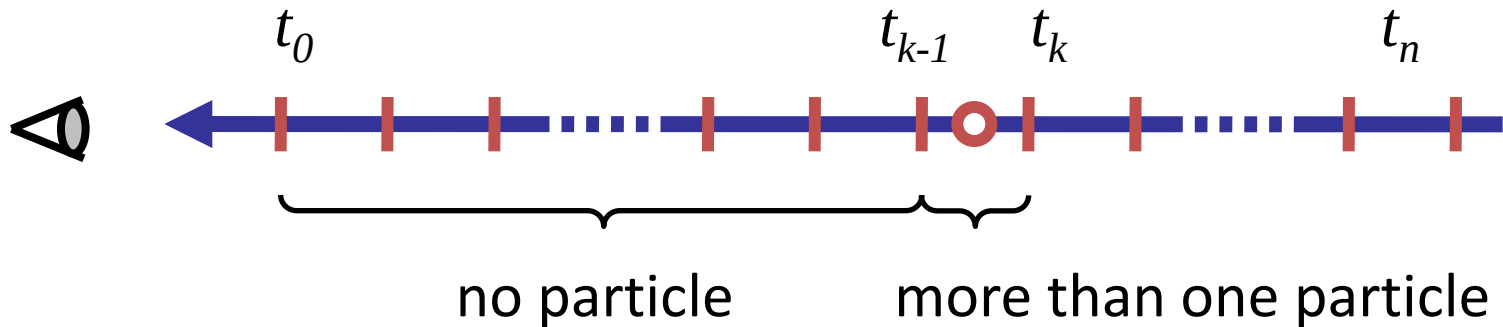
- Generate a set of **opaque** particles
- Project the particles onto an image plane
- Use an ensemble average

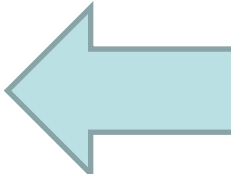


Relationship between conventional rendering and PBR

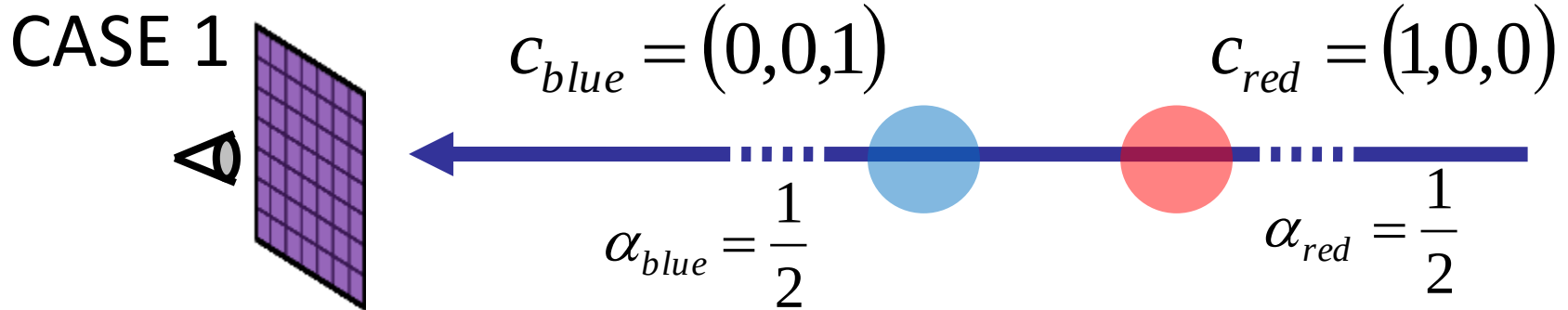
- Brightness = Expected value of particle colors

$$B = \sum_{i=1}^n c_i \times \underbrace{(\alpha_i \prod_{j=1}^{i-1} (1 - \alpha_j))}_{P_k} \quad B = \sum_{k=1}^n c_k P_k$$

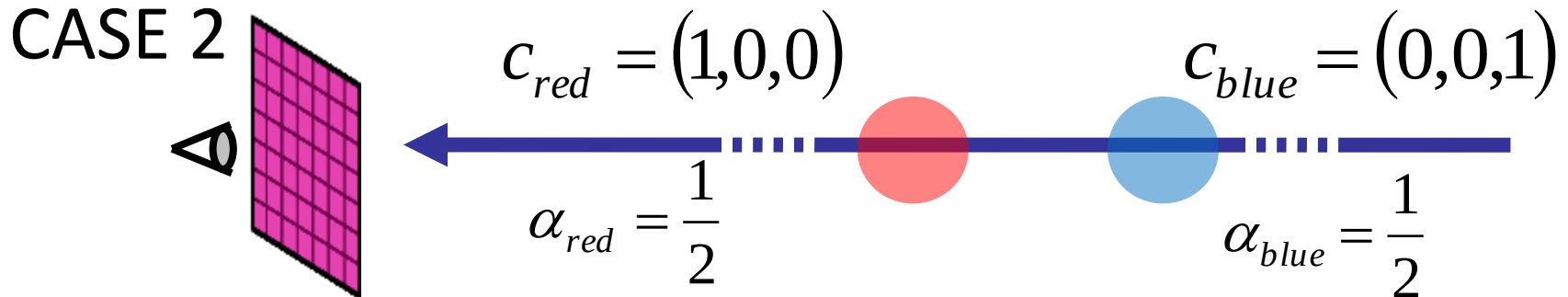


Probability of $B = c_k$  $P_k = \alpha_k \prod_{j=1}^{k-1} (1 - \alpha_j)$

Simple cases

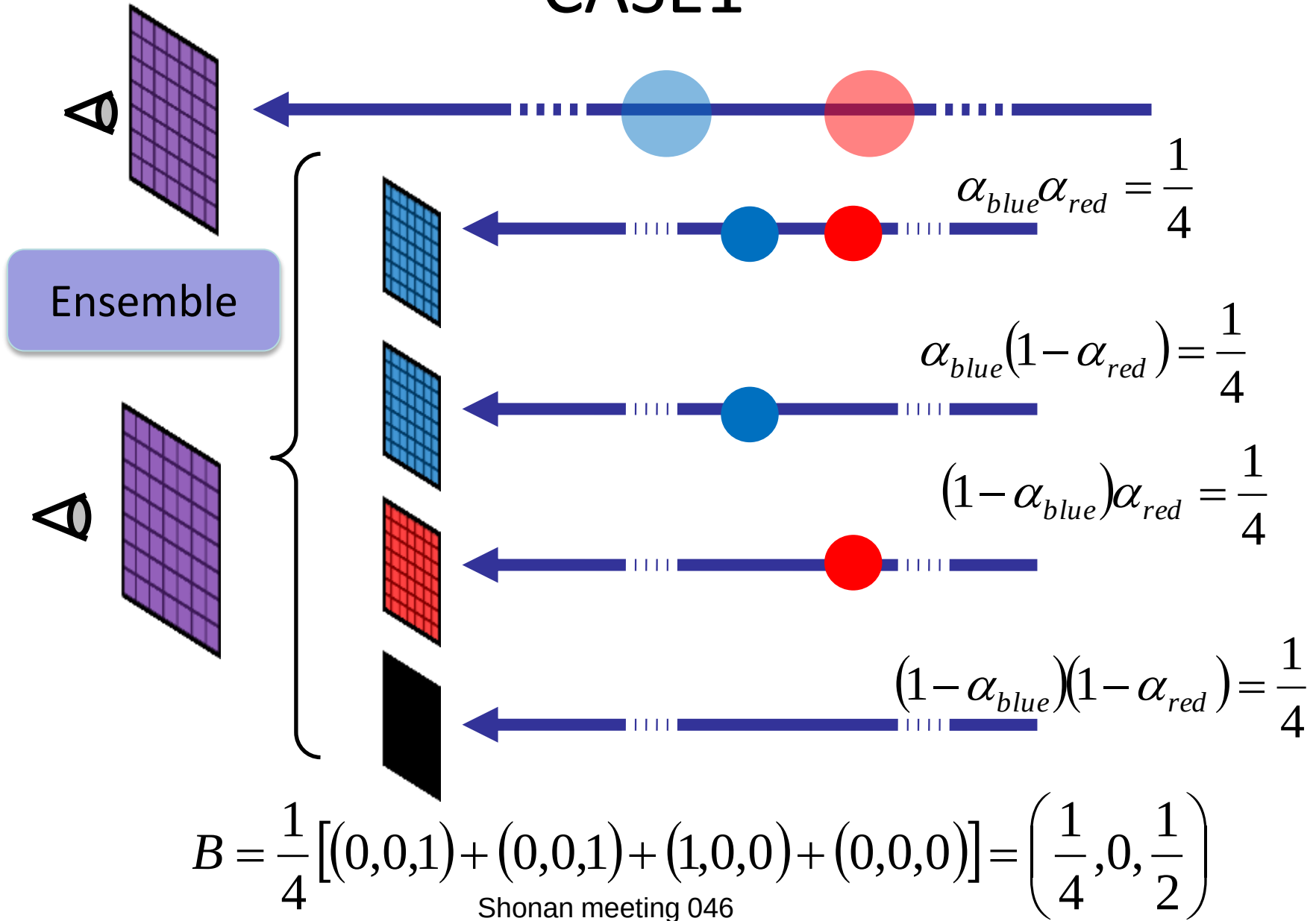


$$B = (1 - \alpha_{blue})\alpha_{red}c_{red} + \alpha_{blue}c_{blue} = \left(\frac{1}{4}, 0, \frac{1}{2}\right)$$

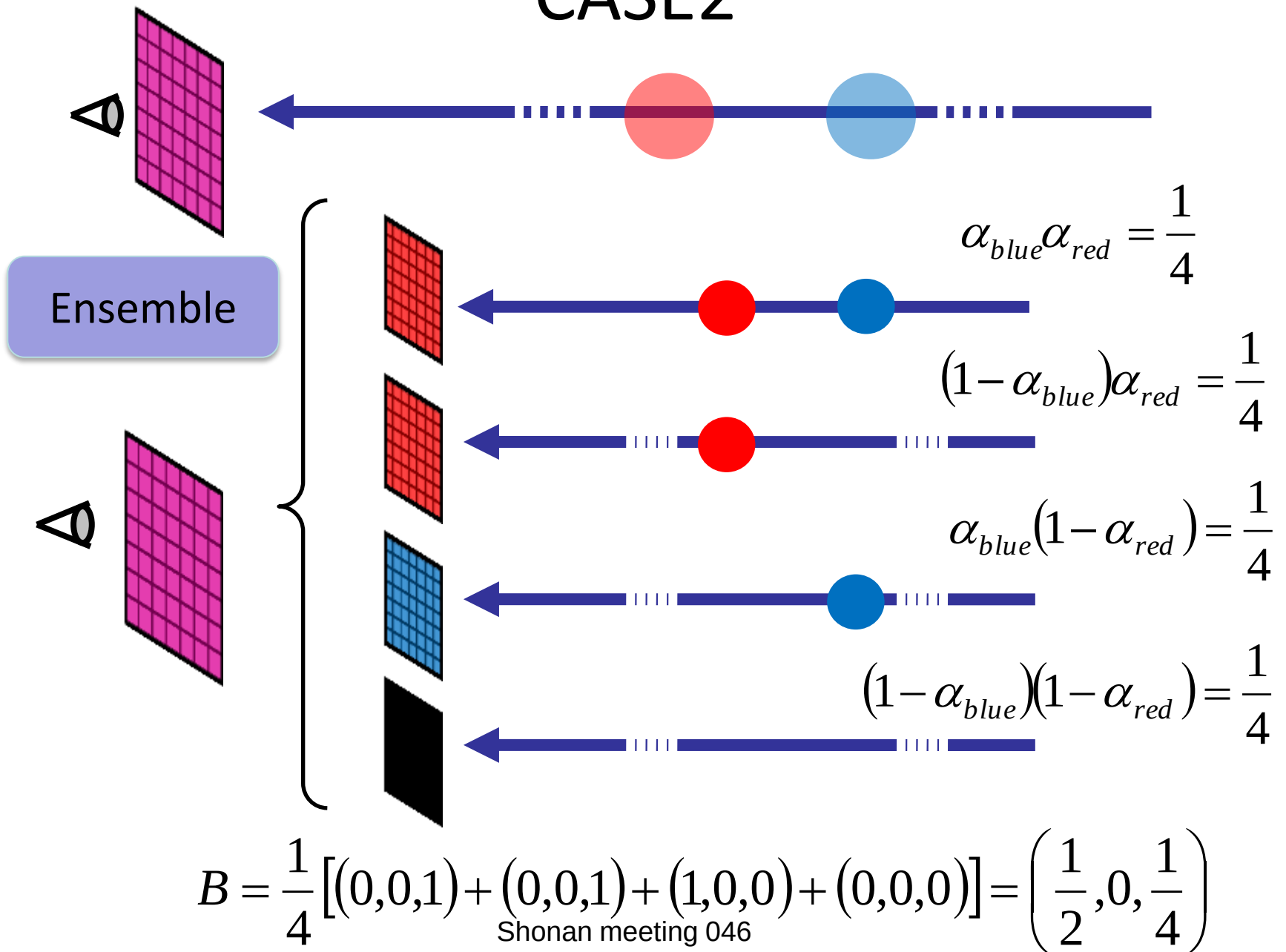


$$B = (1 - \alpha_{red})\alpha_{blue}c_{blue} + \alpha_{red}c_{red} = \left(\frac{1}{2}, 0, \frac{1}{4}\right)$$

CASE1

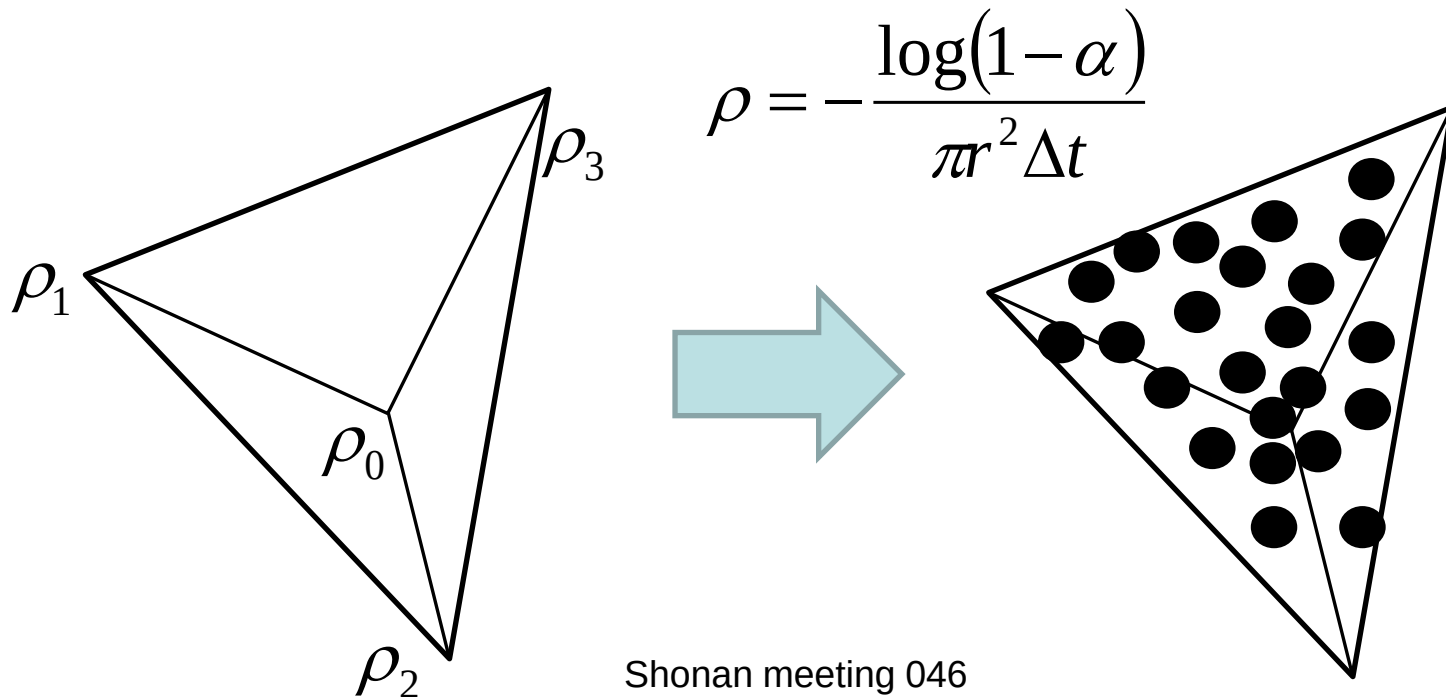


CASE2



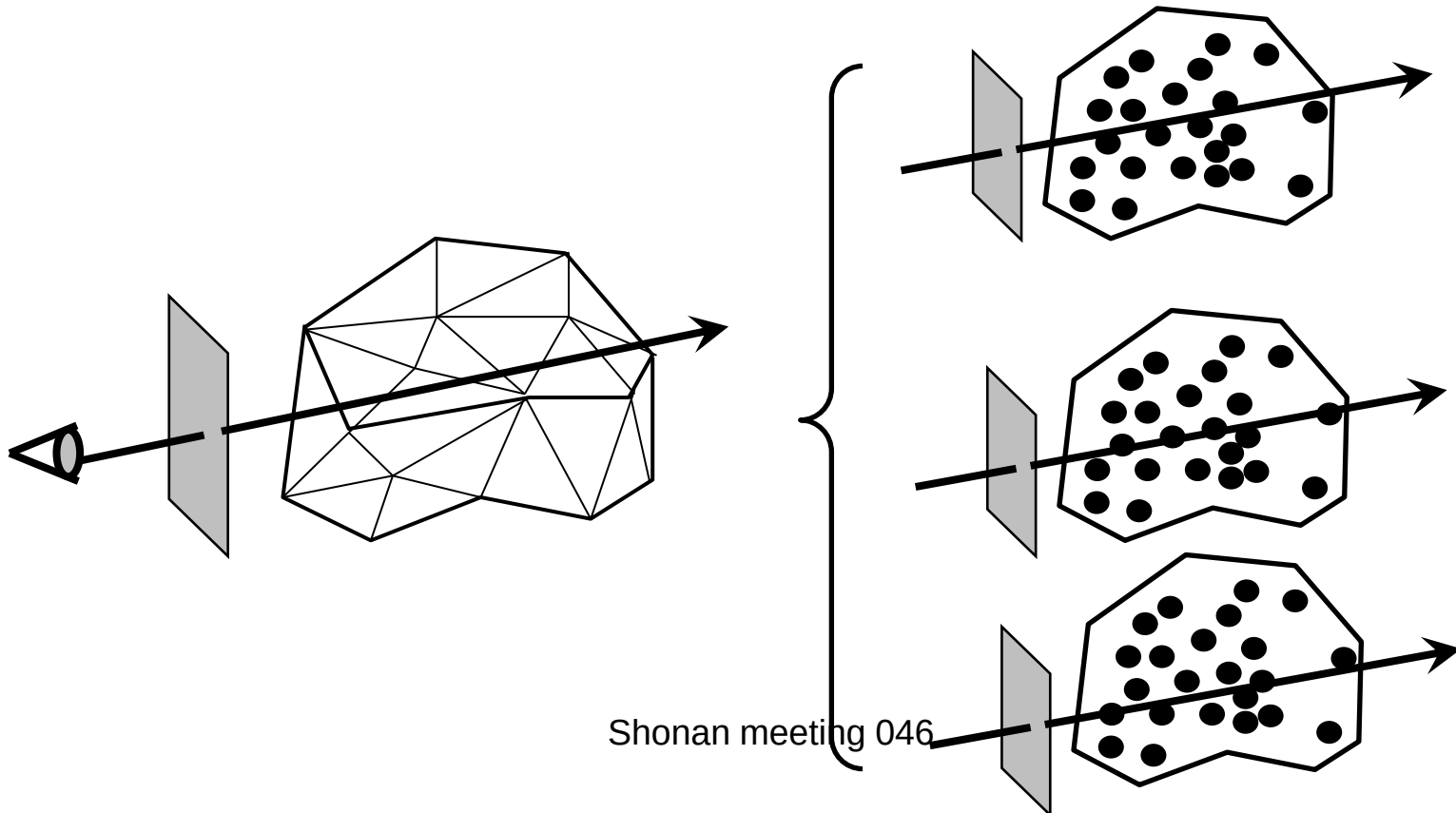
PBR in an object space (O-PBR)

- Generate a set of **opaque** particles in each cell
- Project the particles onto an image plane
- Use an ensemble average



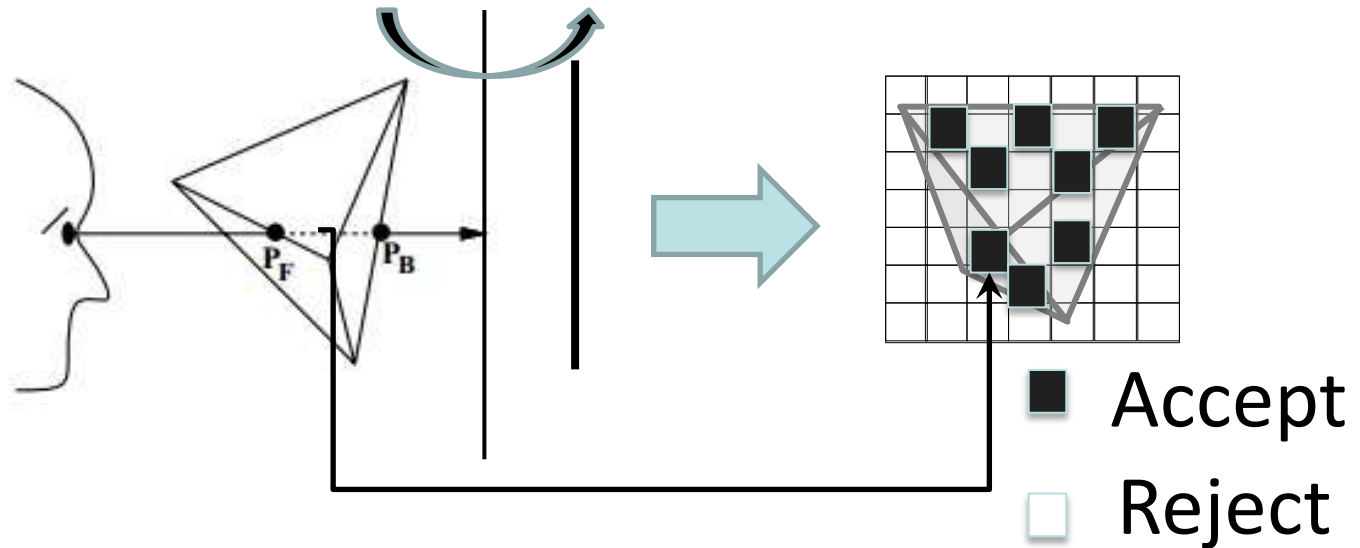
O-PBR procedure

- Generate a set of **opaque** particles in each cell
- Project the primitives onto an image plane
- Use an ensemble average



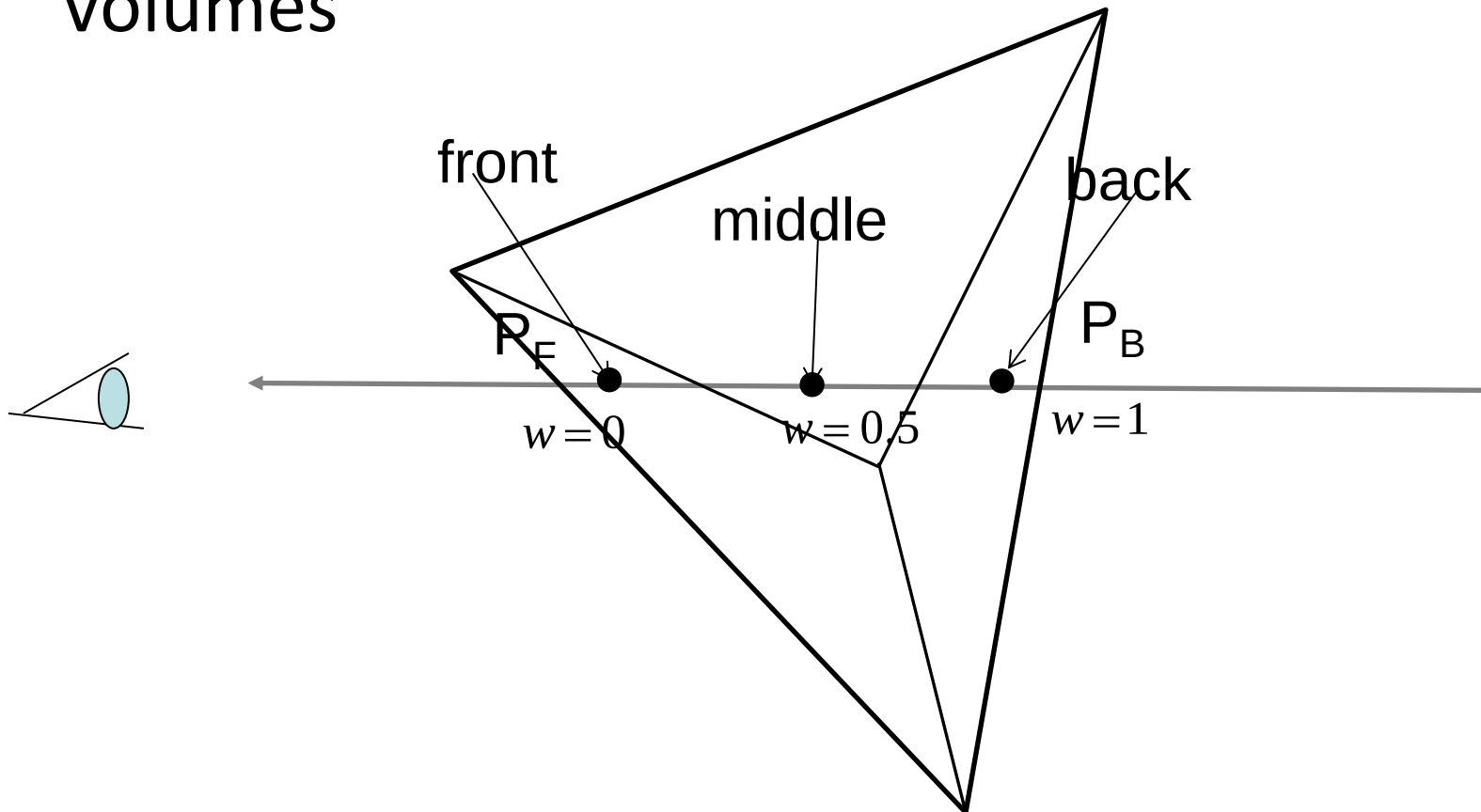
PBR in an image space (I-PBR)

- Generate a set of **opaque** particles in each footprint
 1. Evaluate an opacity at each fragment
 2. Accept the fragment if it > a random number
- Project the primitives onto an image plane
- Use an ensemble average



How to determine the depth ?

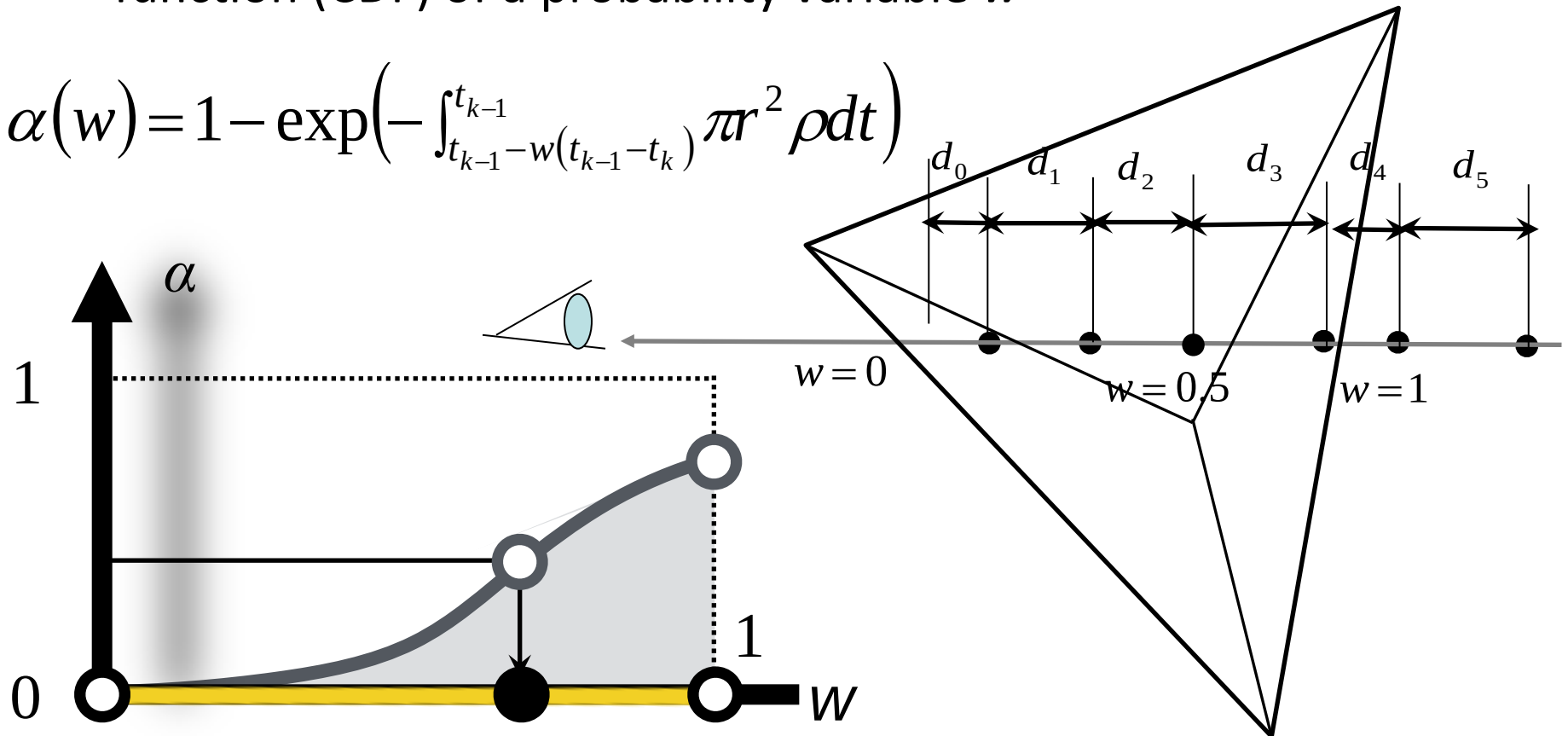
- Any location is OK for a single volume
- But, it may cause an artifact for multiple volumes



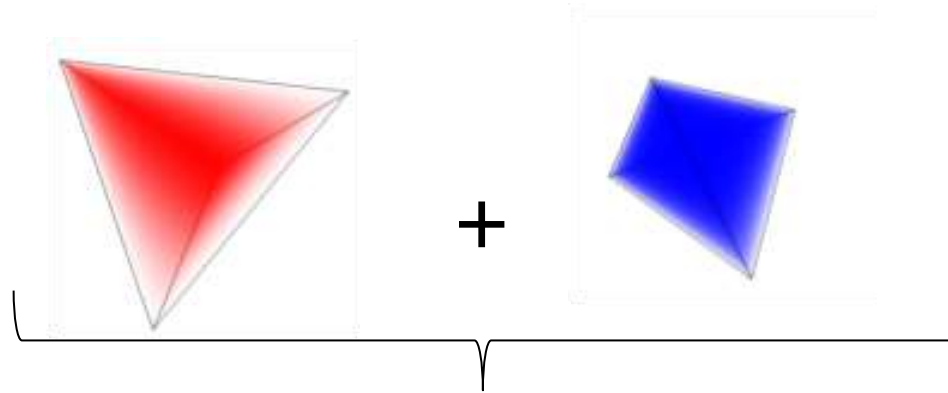
Use of exponential random numbers

- The distance between particles follow the exponential distribution if their number follows the poisson distribution
- The opacity $\alpha(w)$ is regarded as a cumulative distribution function (CDF) of a probability variable w

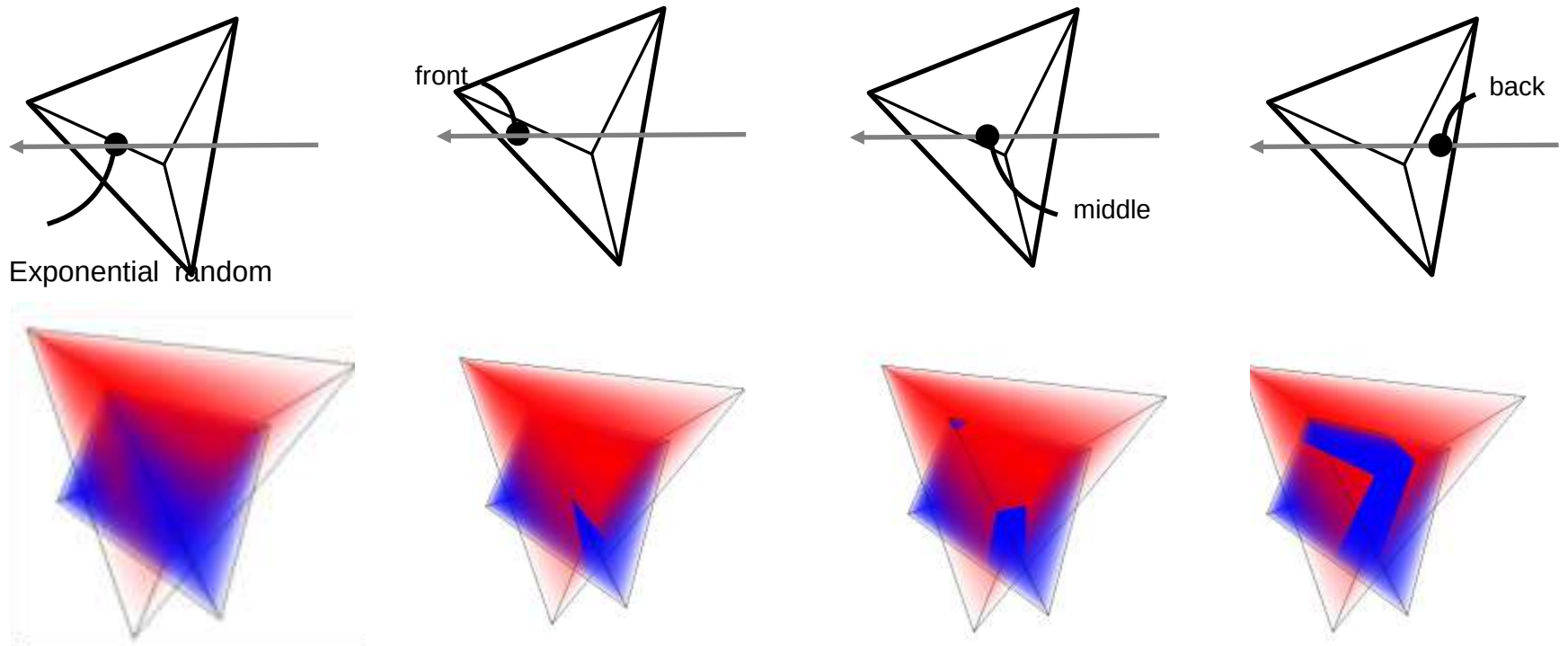
$$\alpha(w) = 1 - \exp\left(-\int_{t_{k-1}-w(t_{k-1}-t_k)}^{t_{k-1}} \pi r^2 \rho dt\right)$$



Fusion of two tetrahedra cells



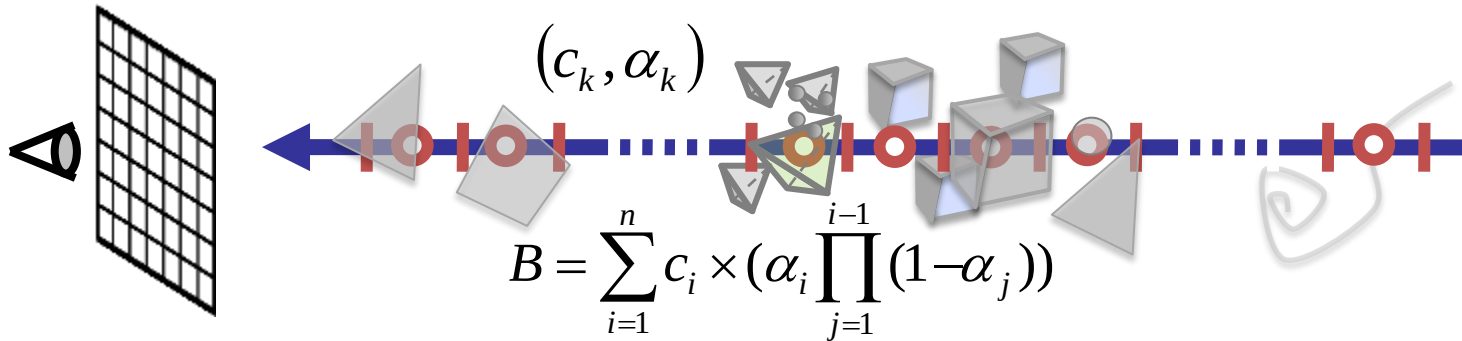
Demo



Particle-Based Rendering and its applications

SUMMARY

Particle-Based Rendering

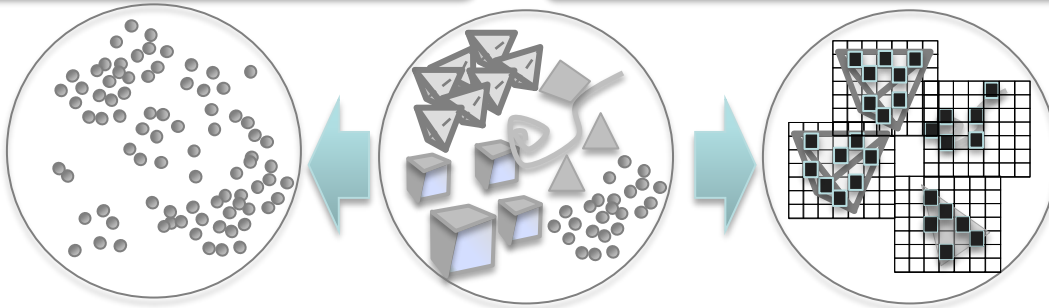


O-PBR

I-PBR

$$\alpha(s) = 1 - e^{-\pi r^2 \rho \Delta t}$$

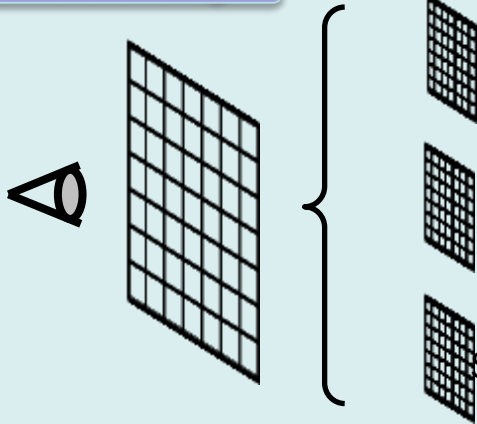
$$\rho(s) = -\frac{\log(1 - \alpha(s))}{\pi r^2 \Delta t}$$



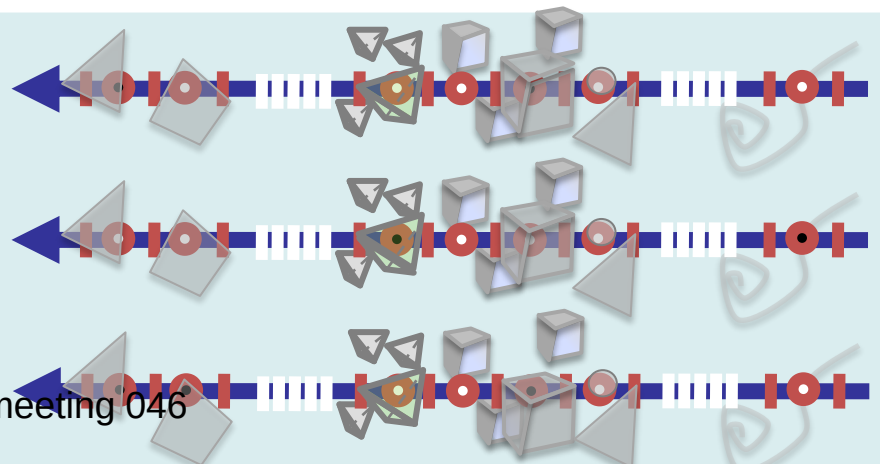
$$B = \sum_{k=1}^n c_k P_k$$

$$P_k = \alpha_k \prod_{j=1}^{k-1} (1 - \alpha_j)$$

Ensemble average



Shonan meeting 046



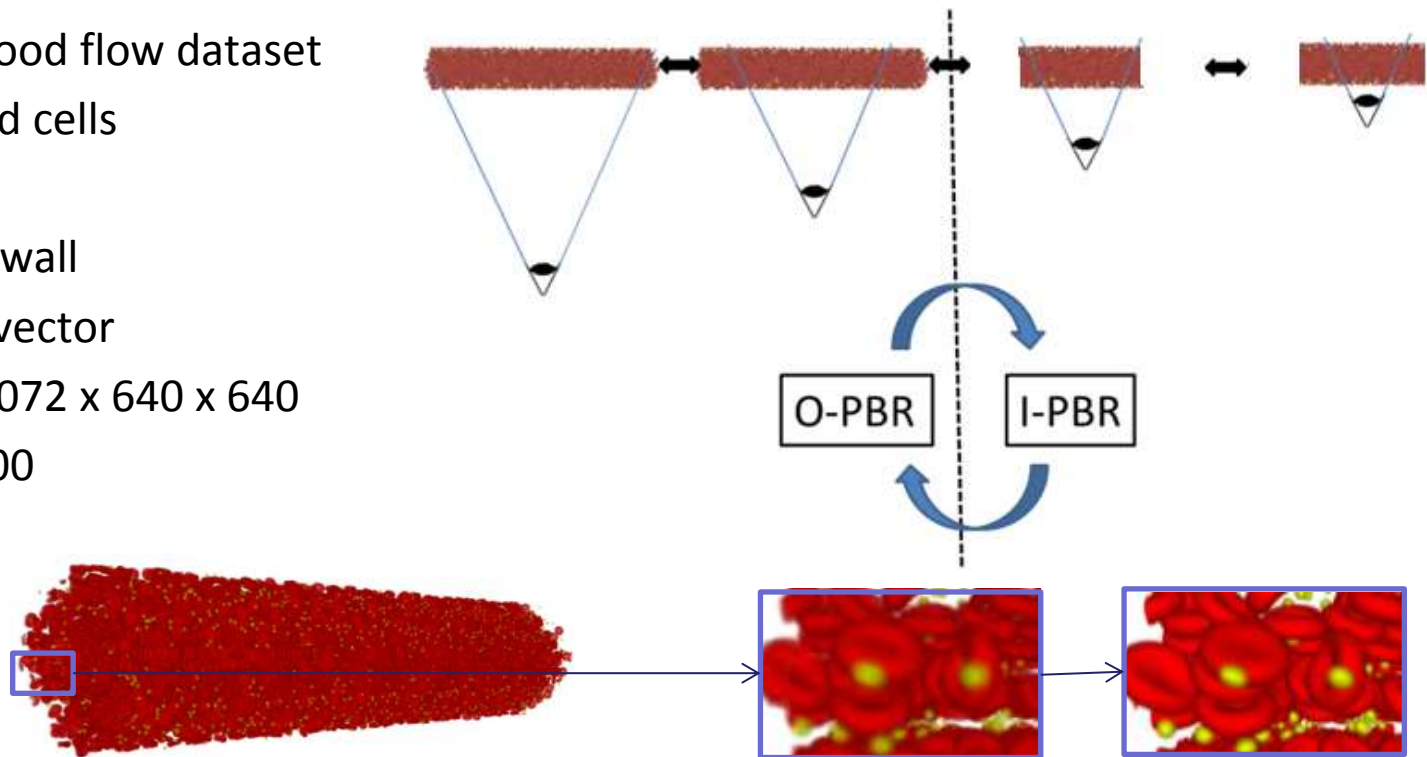
Comparison of O-PBR and I-PBR

- Parameters
 - N_c : Number of cells
 - N_p : Number of particles

Method	Particle generation	Rendering
O-PBR	$O(N_c)$ CPU	$O(N_p)$ GPU
I-PBR	$O(N_c)$ GPU	$O(N_c)$ GPU

Integration of O-PBR and I-PBR

- Large-scale blood flow dataset
 - Red blood cells
 - Platelets
 - Vascular wall
 - Velocity vector
- Resolution: 3,072 x 640 x 640
- Time steps: 100



D. Hara, N. Sakamoto, K. Koyamada, K. Sugiyama, "Adaptive visualization of large-scale blood flow using particle-based rendering," The 7th IEEE PacificVis Symposium Poster, 2014

Performance evaluation (1/2)

- Performance model (T : computing time [ms], M : GPU memory [byte])

- SPT (nc: # of cells, L_r : repetition level, L_s : subpixel level, wxh: image resolution)

$$T^{SPT} = L_r \left(5.67 \times 10^{-5} n_c + 4.51 \times 10^{-6} wh L_s^2 \right)$$

$$M^{SPT} = 20.6 n_c + 7.1 wh L_s^2$$

- PBVR (np: # of particles, L_r : repetition level, L_s : subpixel level, wxh: image resolution)

$$T^{PBVR} = L_r \left(9.96 \times 10^{-7} n_p + 1.47 \times 10^{-5} wh L_s^2 \right)$$

$$M^{PBVR} = 22.0 n_p + 6.86 wh L_s^2$$

- HAVS (nc: # of cells, K : k-buffer size, wxh: image resolution)

$$T^{HAVS} = 1.88 \times 10^{-6} n_c + 1.71 \times 10^{-6} wh + 0.275 K$$

$$M^{HAVS} = 37.65 n_c + 76.3 wh + 0.046 K$$

Performance evaluation (2/2)

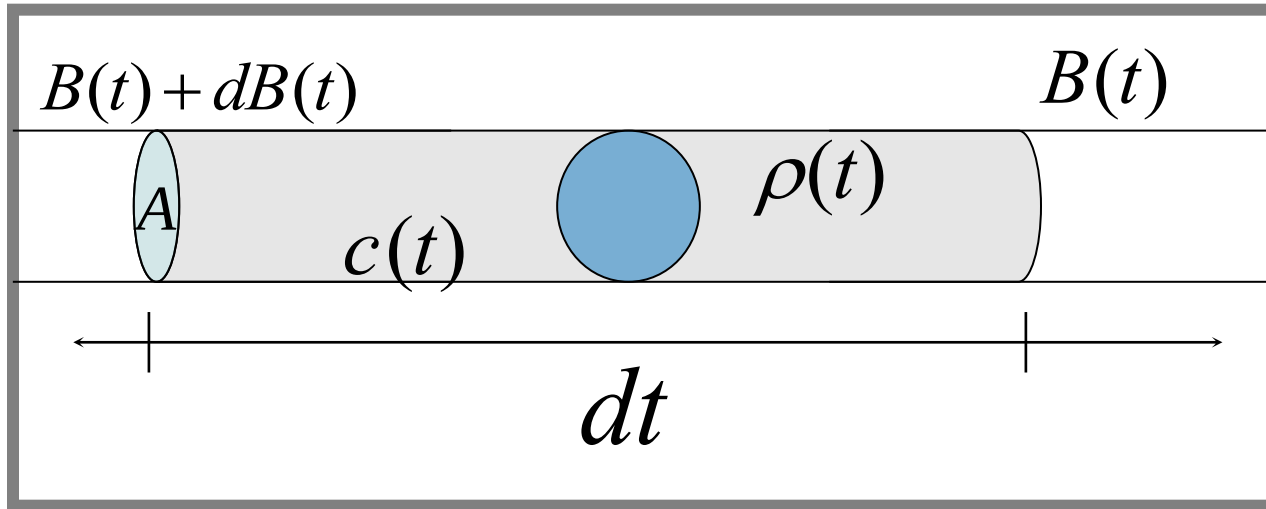
- Computational time
 - $HAVS < SPT, PBVR$
- GPU memory resources
 - $HAVS > SPT, PBVR$
- SPT vs. PBVR (512GB VRAM, 1024x1024)
 - if # of tets. $< 24.5M$ SPT
 - otherwise PBVR

Stochastic rendering for facilitating a high-precision modeling

VISUALIZATION

Optical model of volume rendering

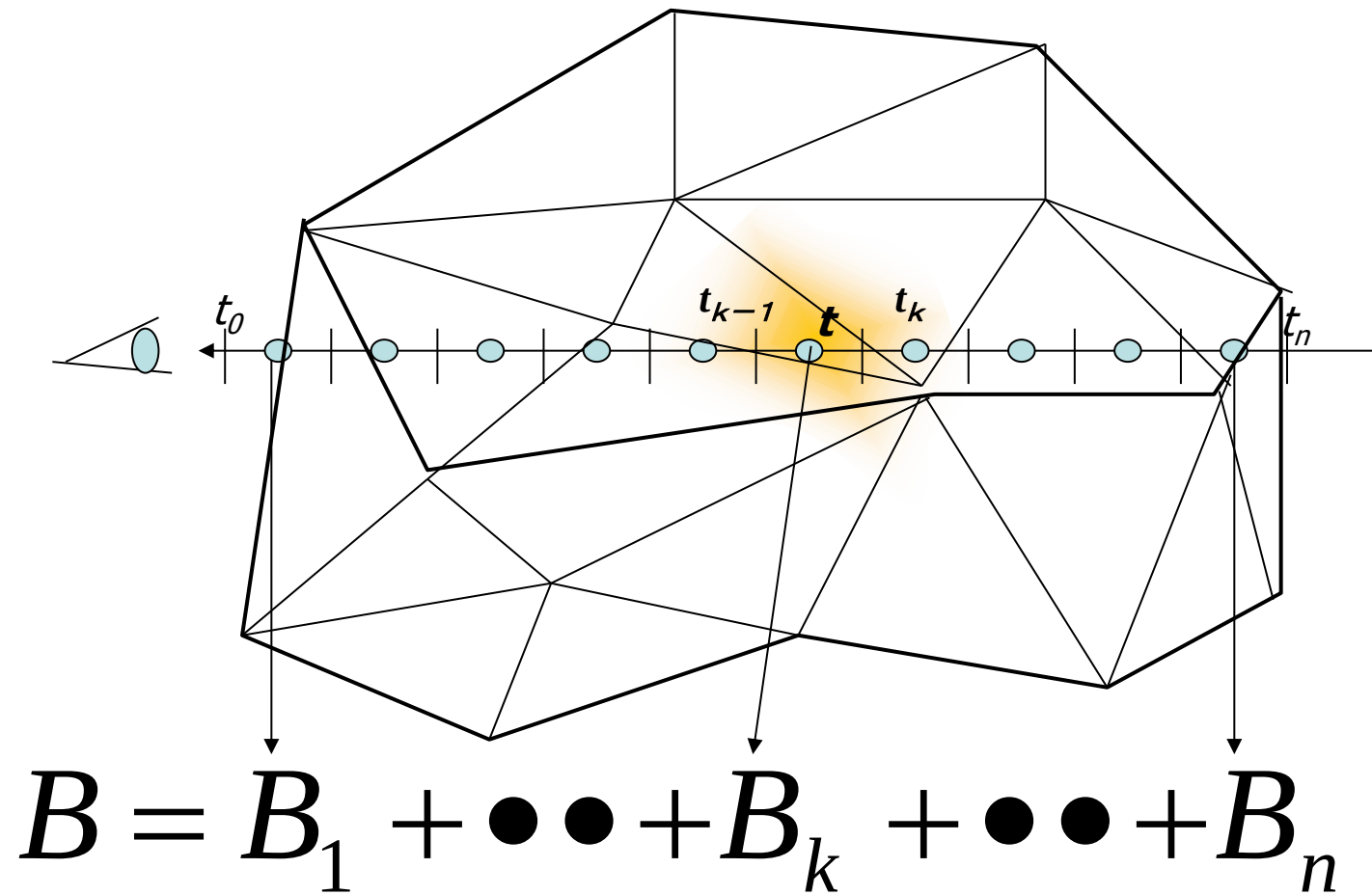
Sabella, 1988



$B(t)$: Brightness $\rho(t)$: particle density r : particle radius $c(t)$: luminosity

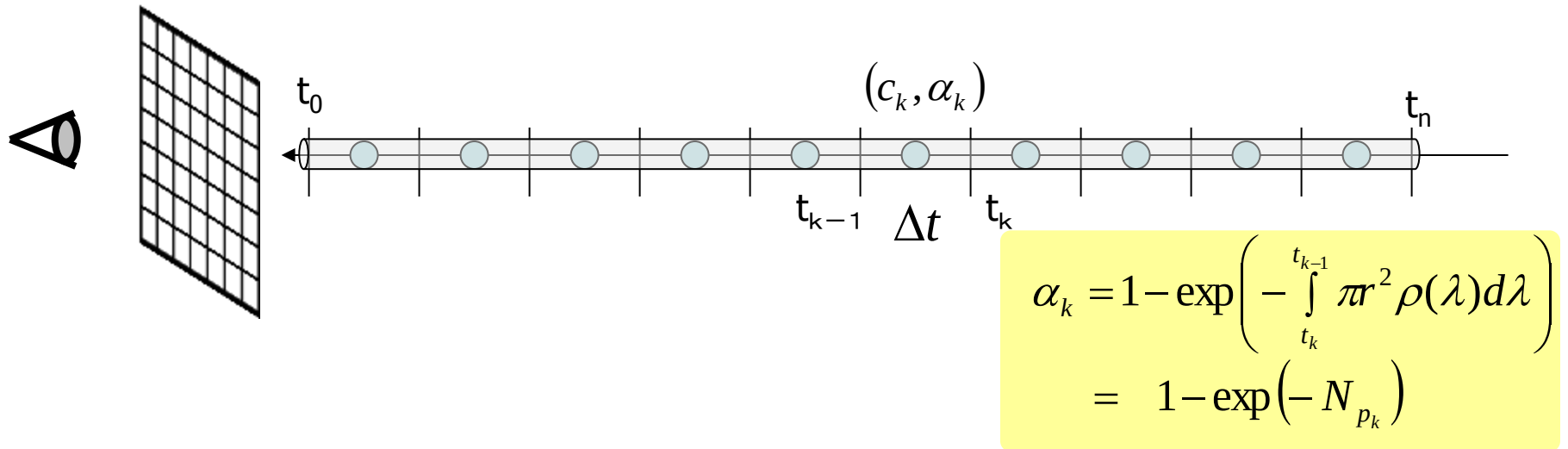
$$\begin{aligned} dB(t)A &= -\text{absorbed} + \text{emitted} \\ &= (-B(t) + c(t)) \times \pi r^2 \rho(t) A dt \\ \frac{dB(t)}{dt} &= (-B(t) + c(t)) \times \pi r^2 \rho(t) \end{aligned}$$

Discretization



Brightness equation

- Sum of contributions from all the segments

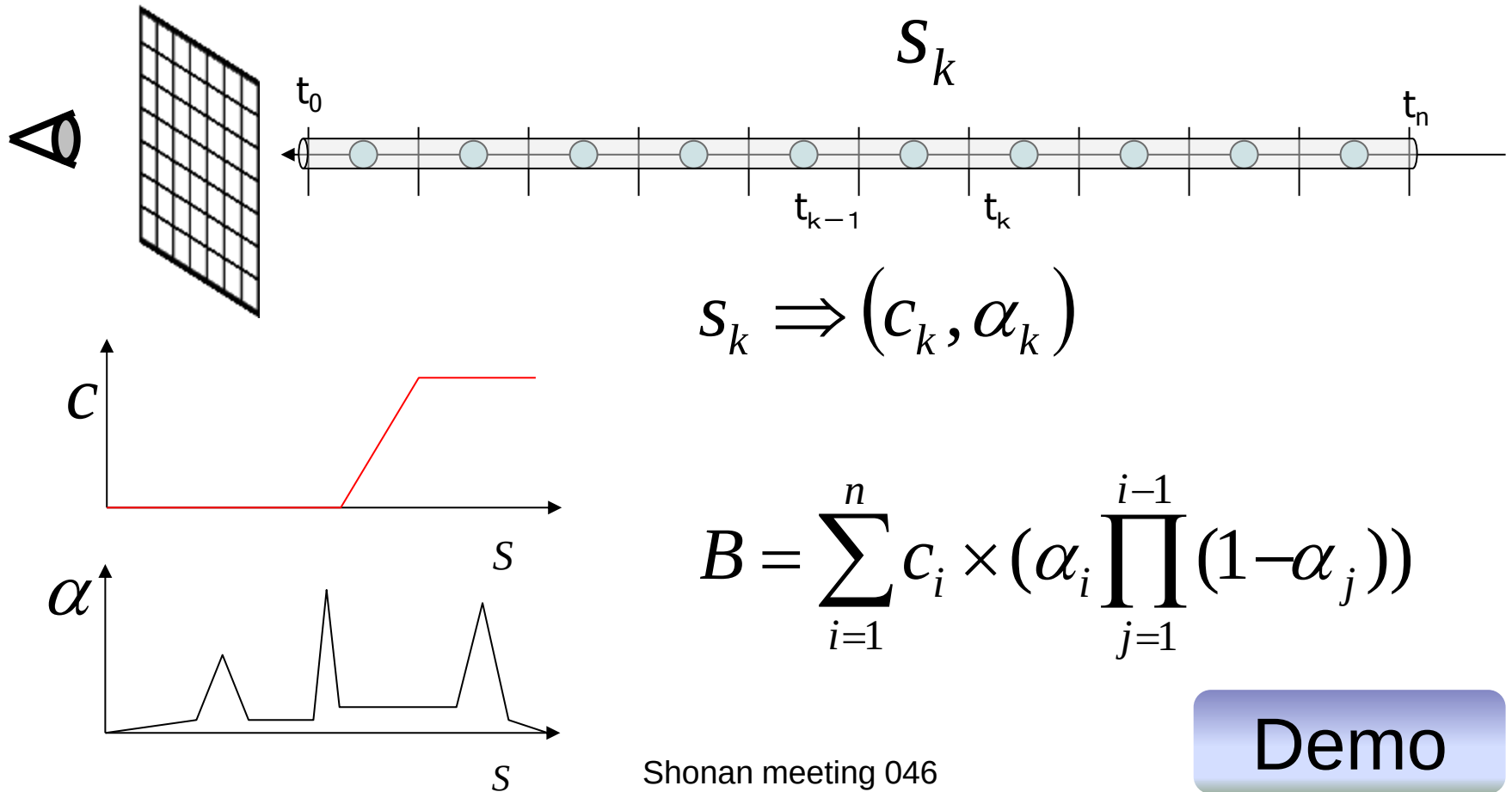


N_{p_k} : Number of particles in the k -th ray segment

$$B = \sum_{i=1}^n c_i \times \left(\alpha_i \prod_{j=1}^{i-1} (1 - \alpha_j) \right)$$

Transfer function

- Transform scalar value into color and opacity

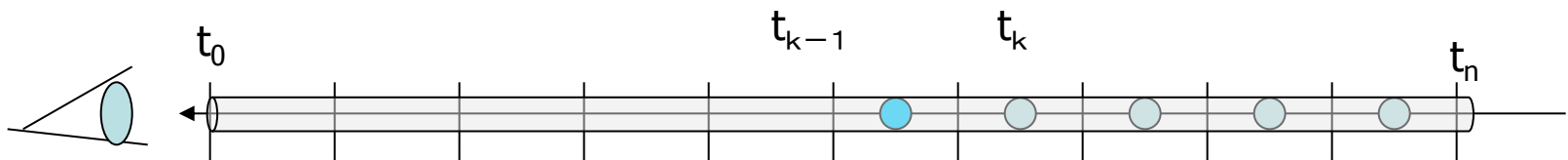


Back-to-front algorithm

- Derive a recurrence relation by adding a particle from back
- Blend intermediate brightness and particle color
- Assume that all the segments are sorted in the visibility order

$$B^{k-1} = \sum_{i=k}^n c_i \times (\alpha_i \prod_{j=k}^{i-1} (1 - \alpha_j))$$

$$B^k = \sum_{i=k+1}^n c_i \times (\alpha_i \prod_{j=k+1}^{i-1} (1 - \alpha_j))$$



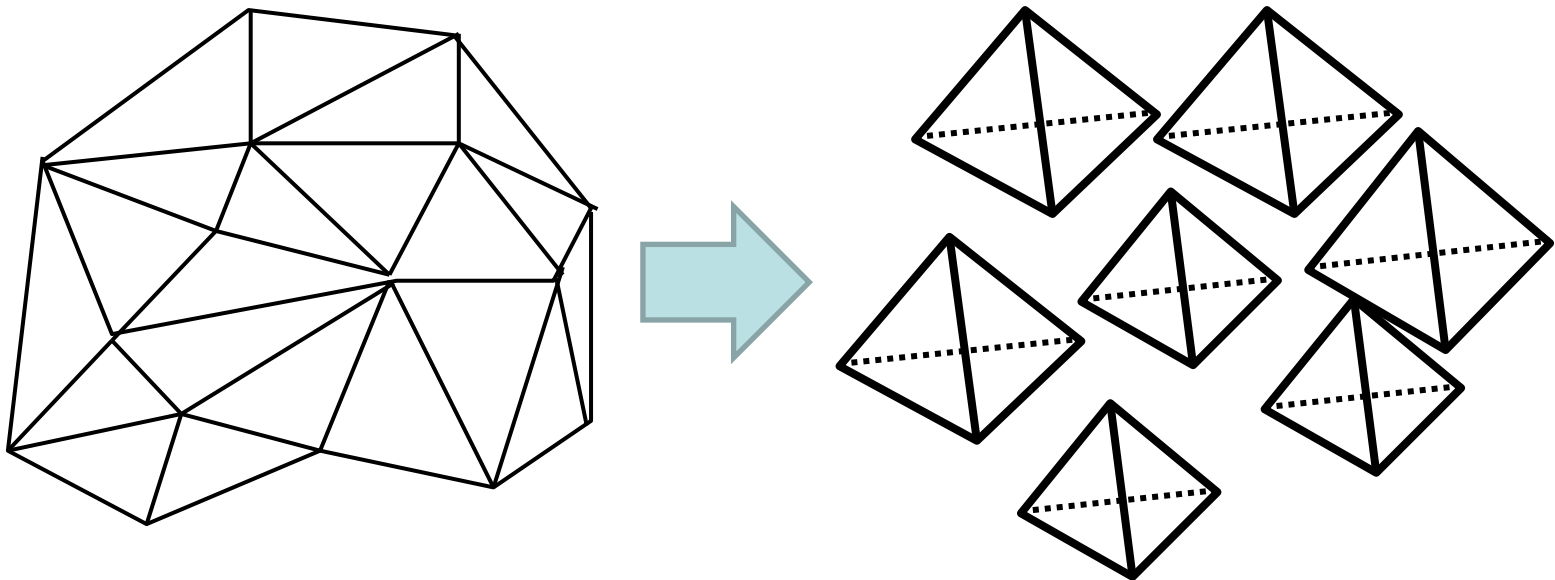
$$B^{k-1} = c_k \alpha_k + (1 - \alpha_k) B^k$$

Stochastic rendering for facilitating a high-precision modeling

VOLUME RENDERING FOR IRREGULAR GRIDS

Irregular grids

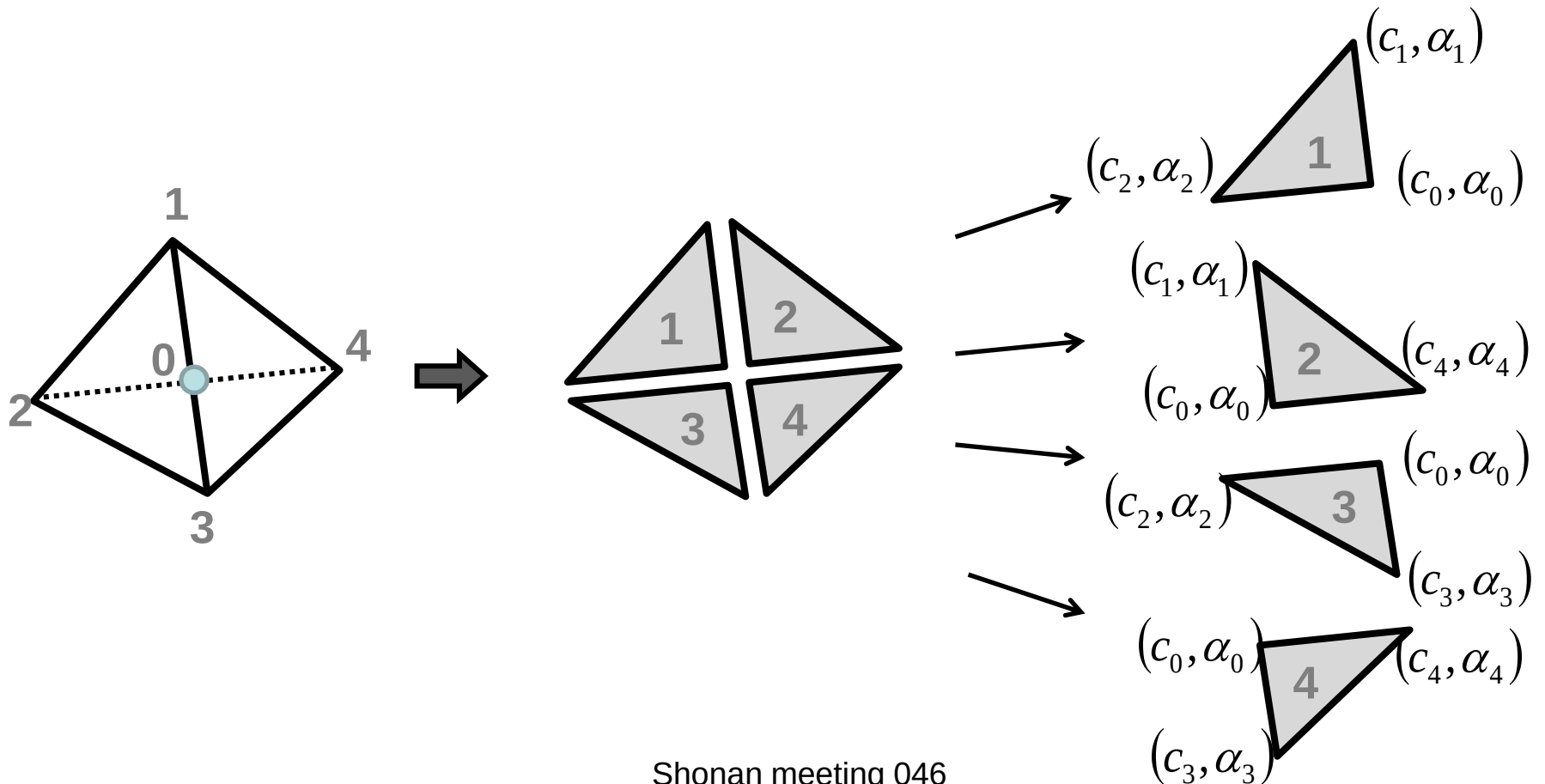
- Assume that irregular grids are composed of tetrahedral cells



Projected tetrahedra

1990, Shirley and Tuchman

- Split a triangle into 3 or 4 triangles on an image plane



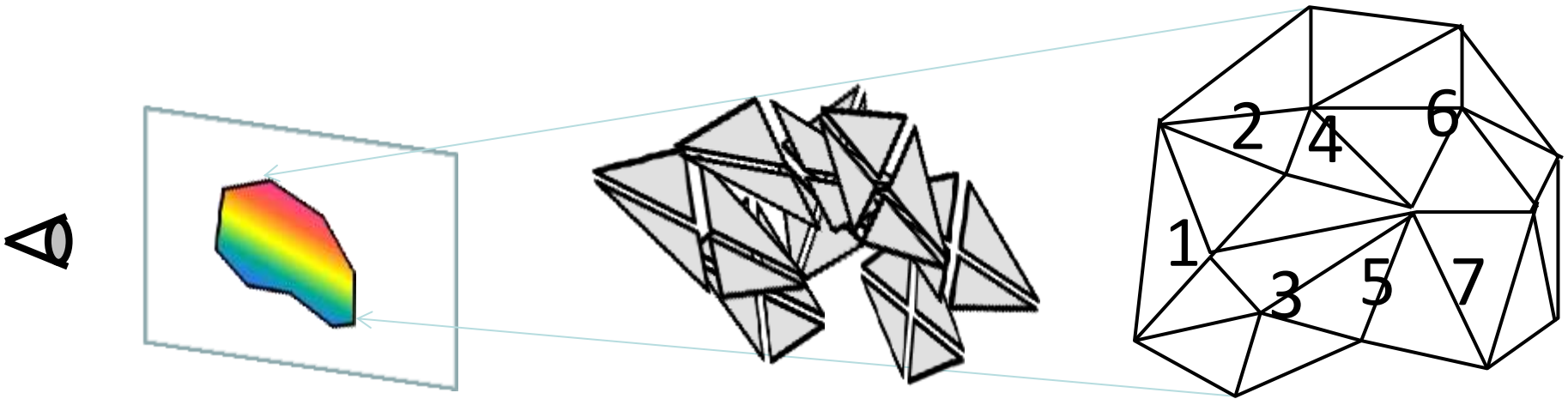
Shonan meeting 046

[P.Shirley, et. al., 1990]

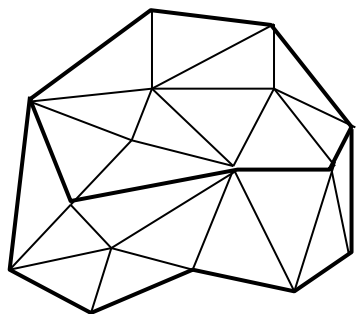
Projected tetrahedra

1990, Shirley and Tuchman

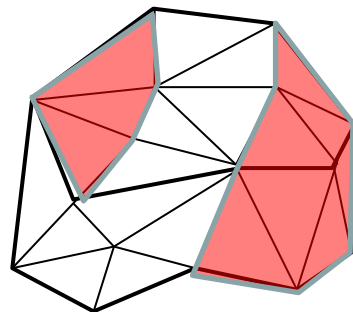
- Sort tetrahedral grid cells
- Project cells in the visibility order
- Subdivide the cells into 3 or 4 semi-transparent triangles
- Superimpose triangles in back-to-front order



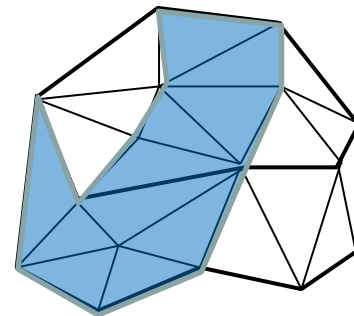
Sorting can be impossible



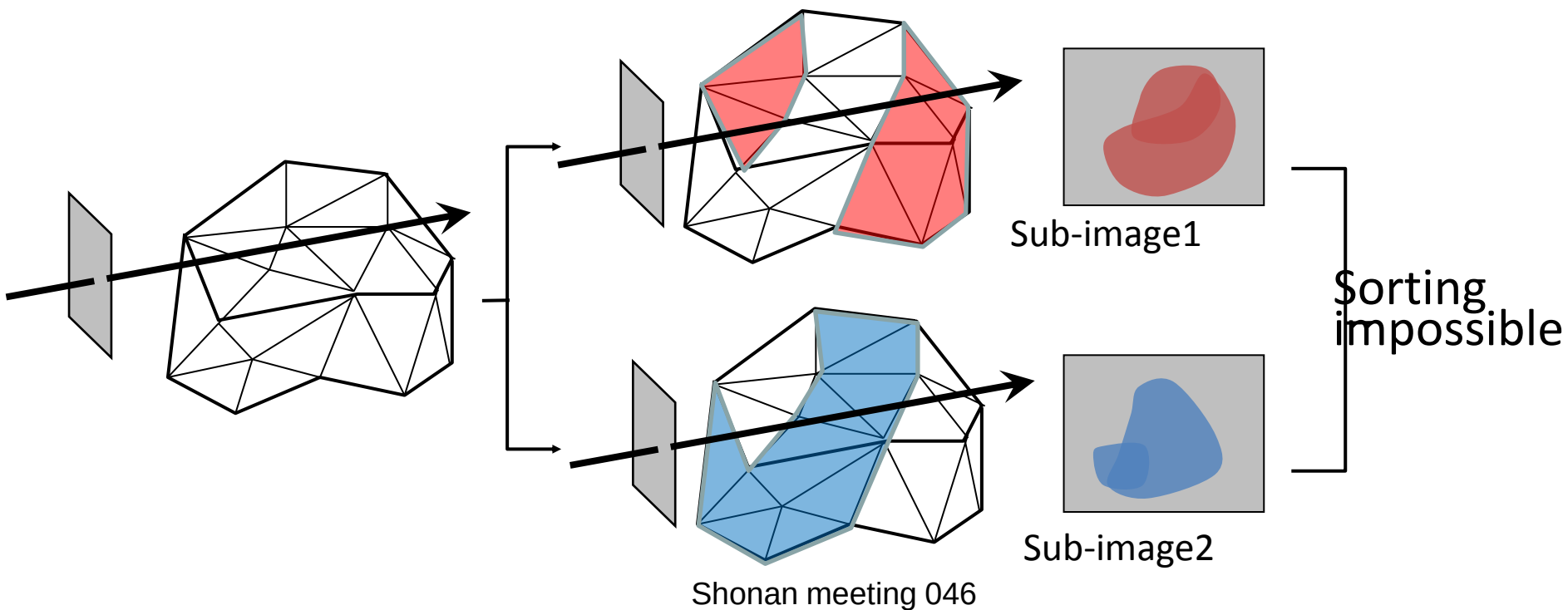
Whole region



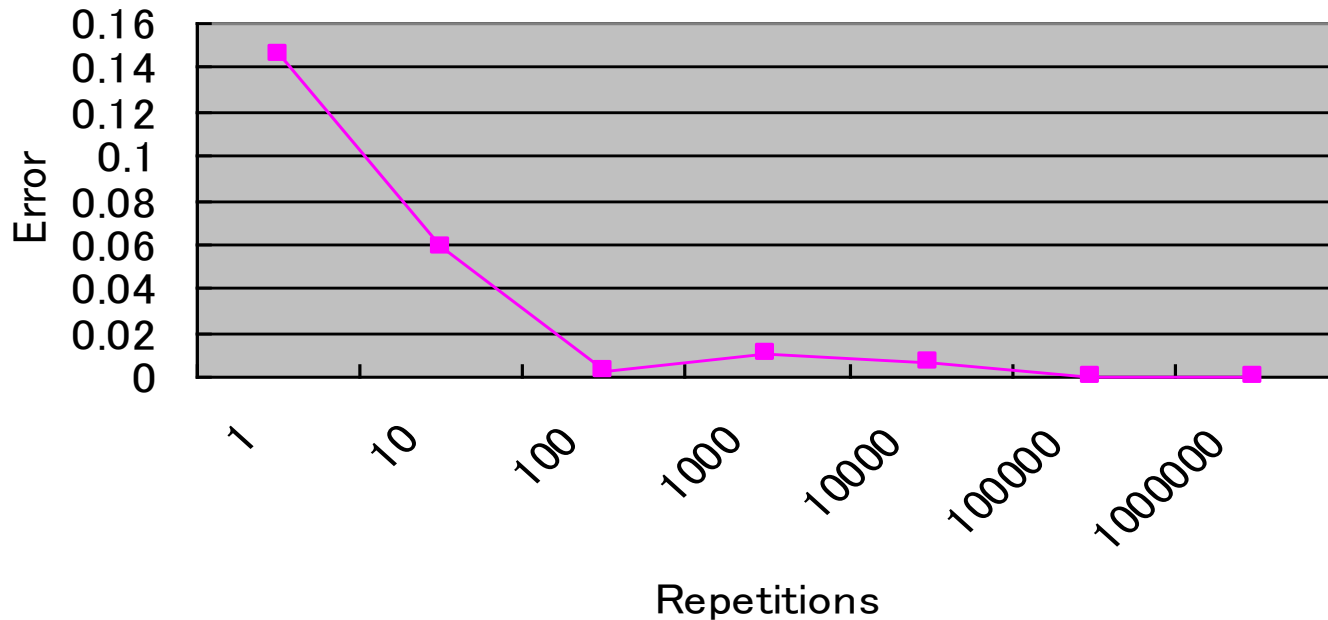
region1



region2



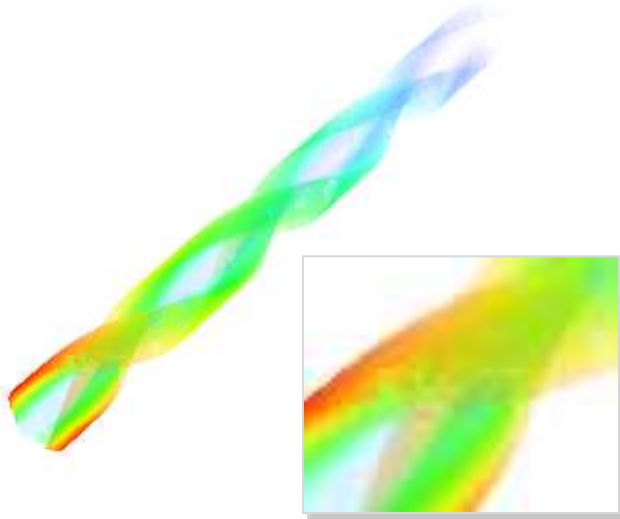
Accuracy of Sort-free rendering



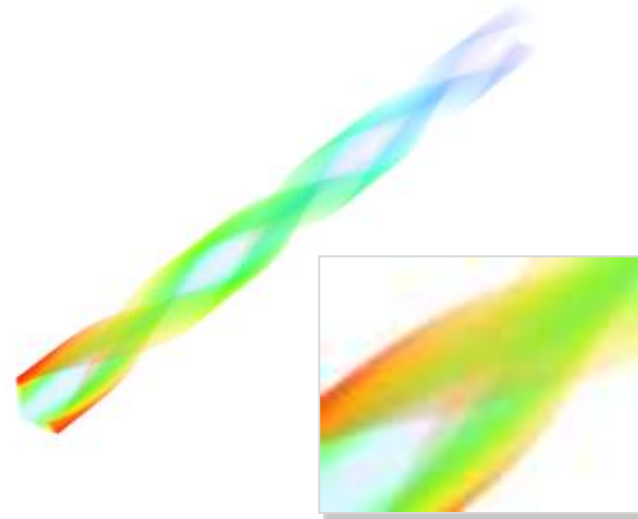
- The error is defined as the absolute difference between the true and approximated brightness values.
- The true brightness value is calculated by generating random numbers as opacities and luminosities in all of the ray-segments

Comparison with HAVS

- Drill data, 9.9M tets



HAVS (with sorting)



Ours(without sorting)