

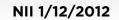
Yahoo! Research

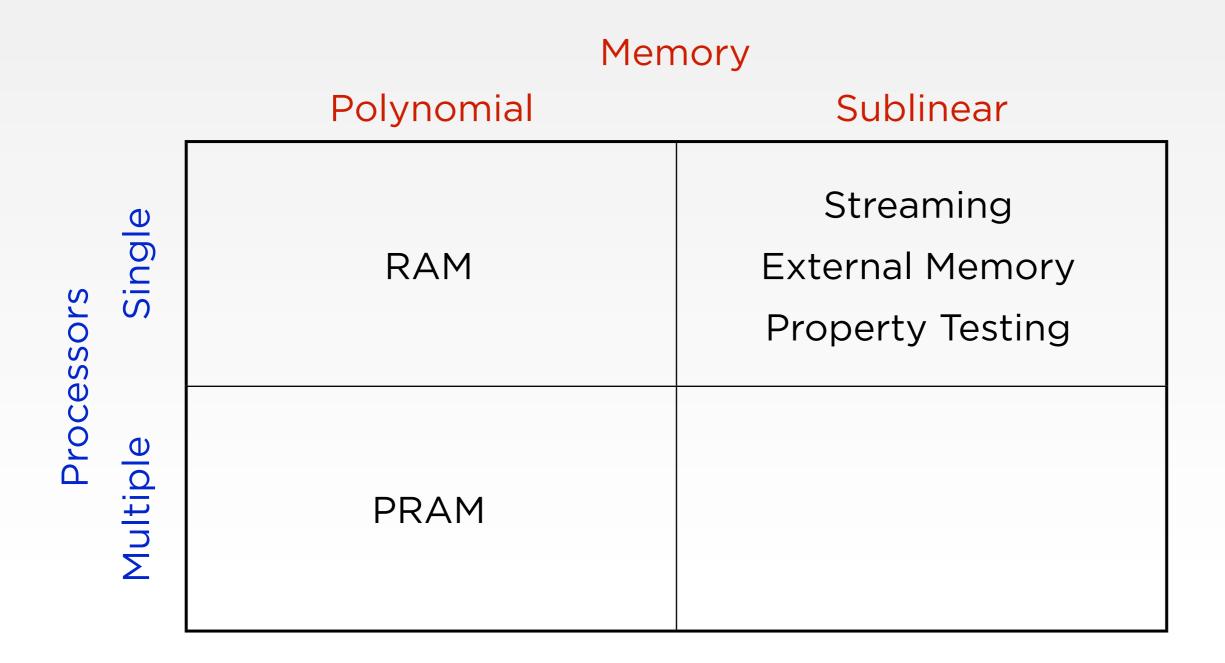
Based on work with: Bahman Bahmani, Howard Karloff, Ravi Kumar, Silvio Lattanzi, Ben Moseley, Siddharth Suri, Andrea Vattani

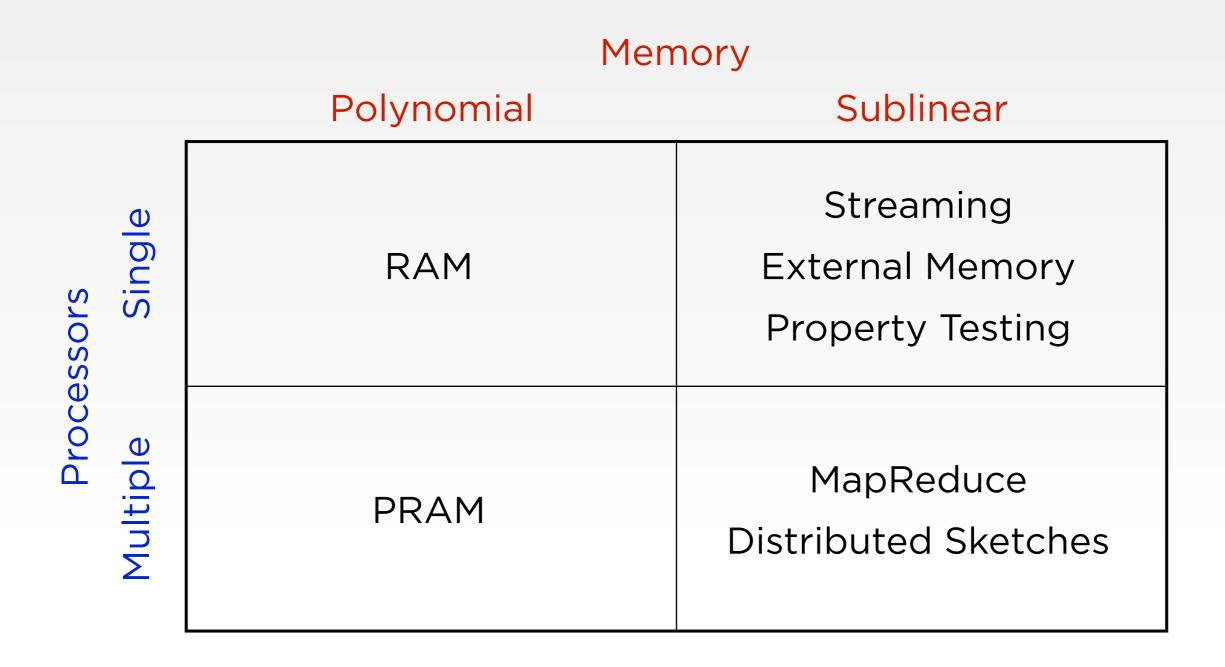
Dealing With Massive Data

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Memory	
Polynomial	Sublinear
RAM	Streaming External Memory Property Testing







Modeling MapReduce



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Sunday, February 19, 2012

Memory

- Typical datasets 100Gb+
- Cannot store the data in memory
- Insist on sublinear memory

Modeling MapReduce

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Machines

- Machines in a cluster do not share memory
- Shared clusters have 100-1000 machines
- Insist on sublinear number of machines

Modeling MapReduce

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Synchronization

- Computation proceeds in rounds
- Count the number of rounds

Not Modeling MapReduce

Lies, Damned Lies, Statistics

- And big-O notation
- And Competitive Analysis
- And...

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MapReduce Communication:

- Very important, makes a big difference

Not Modeling MapReduce

Lies, Damned Lies, Statistics

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MapReduce Communication:

- Very important, makes a big difference
- Many engineering improvements:
 - Dealing with Graphs: save graph structure locally between rounds
 - Move code to data (and not data to code)
 - Job scheduling (same rack / different racks, etc)

Algorithmics



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Algorithmics

Filtering:

- Reduce the problem size in parallel
- Solve the smaller instance sequentially

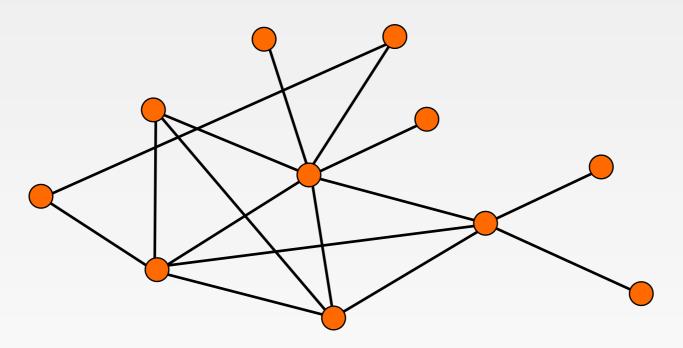
Algorithmics

Filtering:

- Reduce the problem size in parallel
- Solve the smaller instance sequentially

How to reduce input size?

- Connectivity: if (u,v) already connected, remove edge
- MST: remove heaviest edge on every cycle
- Matching: remove dead edges (see next talk)
- Clustering: remove nodes that are not in the coreset (see Ben's talk)
- Set Cover: remove dominated sets
- etc



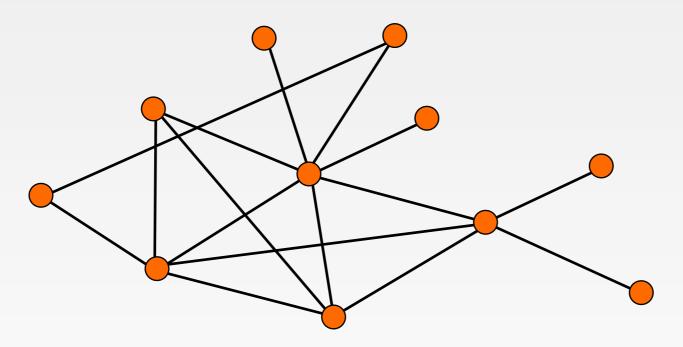
Problem: Given a graph G = (V, E), find $V' \subseteq V$ that maximizes:

$$\rho = \frac{|E(V')|}{|V'|}$$

NII 1/12/2012



Sunday, February 19, 2012



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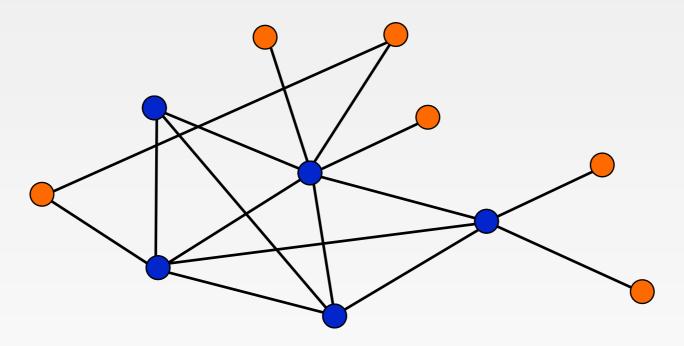
 $\rho = \frac{|E(V')|}{|V'|}$

Useful Primitive in Graph Analysis:

- Community Detection
- Graph Compression
- Link SPAM Mining
- Many other applications

NII 1/12/2012

Sergei Vassilvitskii



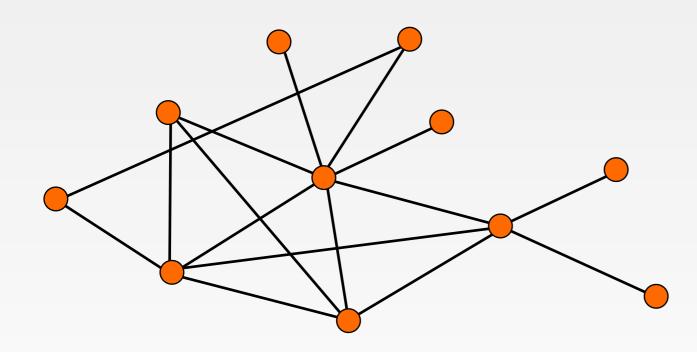
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Useful Primitive in Graph Analysis

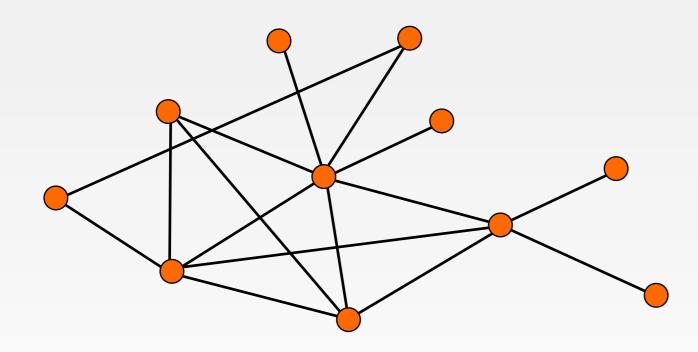
Can be solved exactly:

- LP Formulation
- Multiple Max flow computations



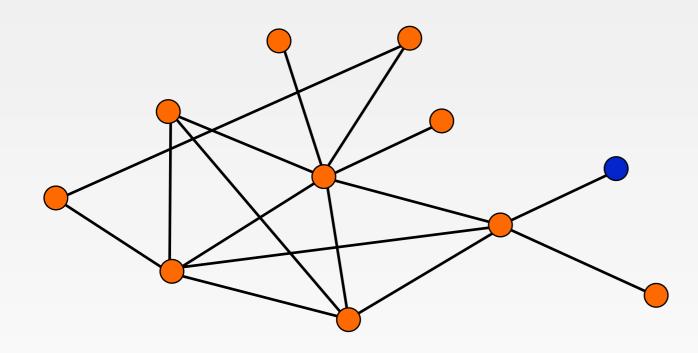
Simple Algorithm [Charikar '00]:

- Iteratively remove the lowest degree node and update vertex degrees
- Keep the densest intermediate subgraph



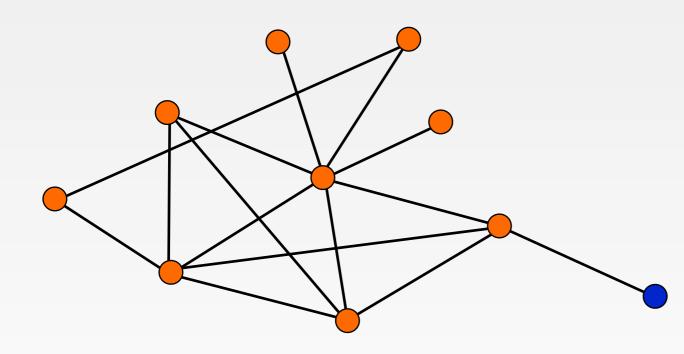
Best Density: 16/11 Current Density: 16/11

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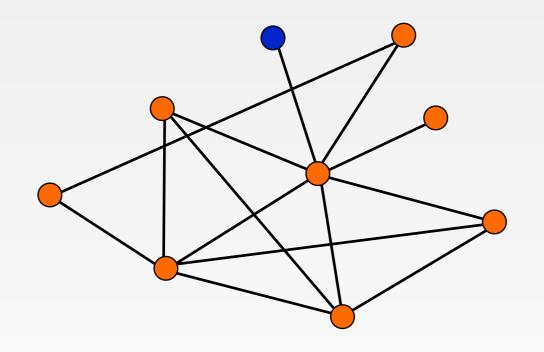
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Best Density: 15/10 Current Density: 15/10

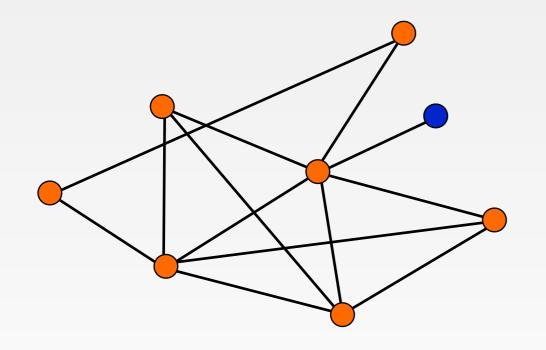
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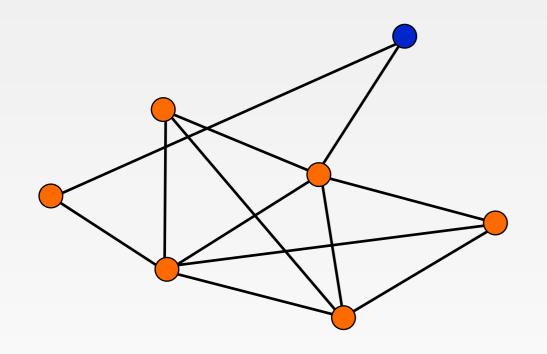
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Best Density: 13/8 Current Density: 13/8

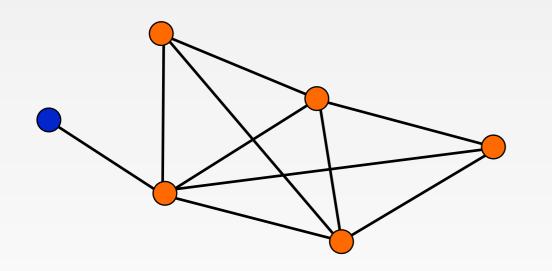
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Best Density: 12/7 Current Density: 12/7

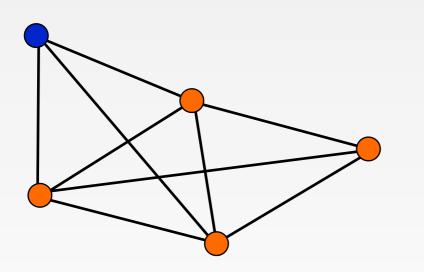
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Best Density: 12/7 Current Density: 10/6



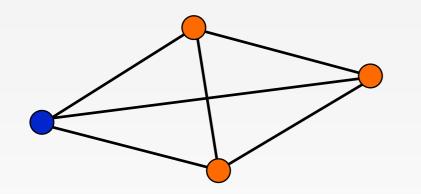
- Iteratively remove the lowest degree node and update vertex degrees
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Best Density: 9/5 Current Density: 9/5



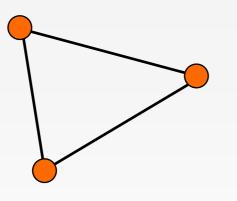
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Best Density: 9/5 Current Density: 6/4



- Iteratively remove the lowest degree node and update vertex degrees
- Keep the densest intermediate subgraph

Best Density: 9/5 Current Density: 3/3



- Iteratively remove the lowest degree node and update vertex degrees
- Keep the densest intermediate subgraph

Finding Dense Subgraphs (Analysis)

Approximation Ratio:

- Guaranteed to return a 2-approximation

Proof:

- Let $V^* \subseteq V$ be the optimal solution, and $\lambda^* = \frac{|E[V^*]|}{|V^*|}$ the optimal density.
- Consider the first time a vertex from V^* is removed.
- Every vertex in V^* has degree at least λ^* .
 - Otherwise can improve optimum density
- Therefore the density of that subgraph is at least:

$$\frac{\lambda^* |V^*|}{2|V^*|} = \lambda^*/2$$

Finding Dense Subgraphs (Analysis)

Approximation Ratio:

- Guaranteed to return a 2-approximation

Running Time:

- RAM:
 - Maintain a heap on vertex degrees
 - Update keys upon removing every edge
 - Straightforward implementation in $O(m \log n)$
- Streaming:
 - Seemingly need one pass per vertex to adapt this algorithm
 - Can show that need $\Omega(n/\log n)$ memory if using $O(\log n)$ passes
- MapReduce?
 - Open question in Chierichetti, Kumar and Tompkins WWW '10.

Sequential Algorithm:

- Remove the node with the smallest degree

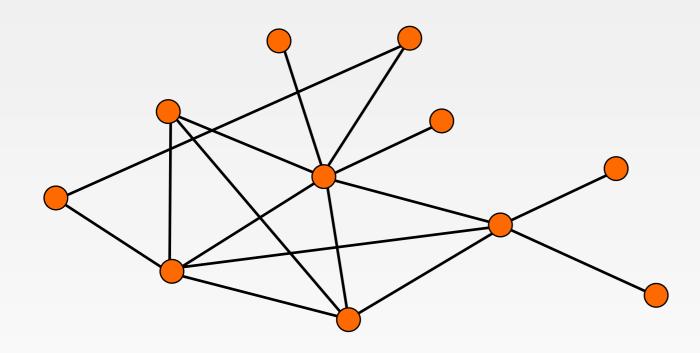
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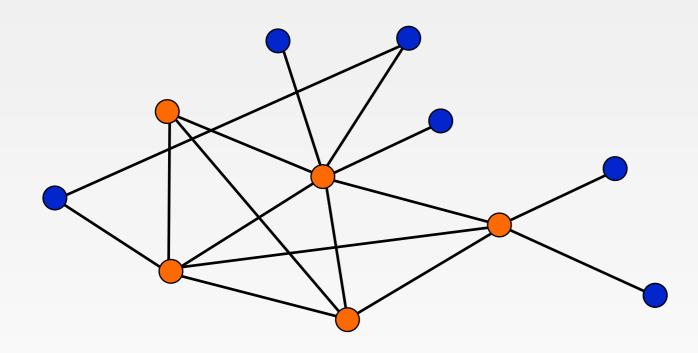
Parallel Version:

- Remove all nodes with less degree less than $(1 + \epsilon)$ average degree
- Of course this also includes the smallest degree node
- Every Step:
 - Round 1: Count remaining edges, vertices, compute vertex degrees
 - Distributed counting
 - Round 2: Remove vertices with degree below threshold
 - Distributed checking



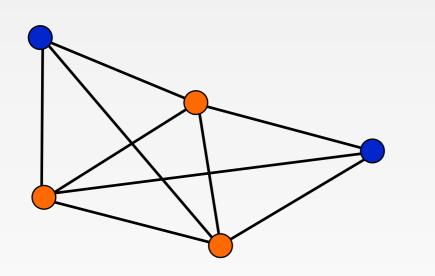
Best Density: 16/11 Current Density: 16/11 Average Degree: 32/11

- Iteratively remove nodes with degree below average and update vertex degrees
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Best Density: 16/11 Current Density: 16/11 Average Degree: 32/11

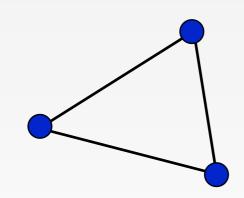
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Best Density: 9/5 Current Density: 9/5 Average Degree: 18/5

- Iteratively remove nodes with degree below average and update vertex degrees
- Keep the densest intermediate subgraph

Best Density: 9/5 Current Density: 3/3 Average Degree: 6/3



- Iteratively remove nodes with degree below average and update vertex degrees
- Keep the densest intermediate subgraph

Algorithm:

- Each round remove all vertices with degree less than $(1 + \epsilon) *$ average.

How many vertices do we remove?

- One cannot have too many vertices above average (This is not Lake Wobegon)
- Easy [Markov inequality] : at most a $\frac{1}{1+\epsilon}$ fraction of vertices remains in every round.
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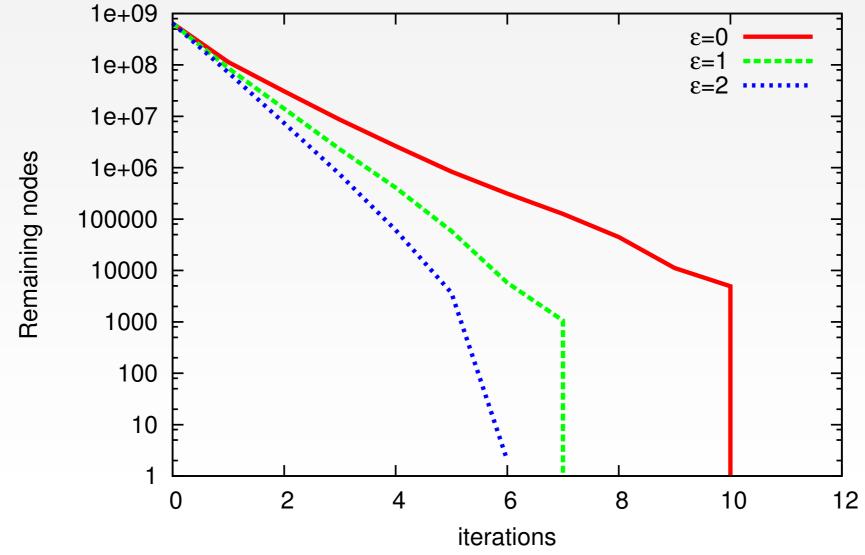
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Approximation Ratio:

- Achieves a $(2+\epsilon)$ approximation in the worst case
 - Only look at the degree of the nodes removed as compared to average. in

How well does it work?

IM Network graph: 650M nodes, 6.1B edges



IM: Remaining graph vs iterations

- Quickly reduce the size of the graph.
- Approximation ratio between 1.06 and 1.4 at $\epsilon = 1$

Improving Sequential Algorithms

Densest Subgraph

- Original algorithm: O(m) heap updates:
 - Update vertex degrees every time an edge is removed.
- New algorithm O(n) heap updates:
 - Number of vertices decreases geometrically every round

Improving Sequential Algorithms

Low Memory Algorithms:

- Recall MapReduce requirement of sublinear memory
- Can run the parallel algorithm sequentially
 - Work efficient algorithms imply identical running time

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In practice:

- Low memory algorithms are more efficient
- Take better advantage of caching hierarchy (L1, L2, OS)
- Empirically have observed faster running times running MapReduce algorithms sequentially

Wrapping Up

Conclusion:

- MapReduce combines parallelism with sublinear memory
- Filtering:
 - Reduce input size in parallel
 - Until data is small enough to be processed sequentially
- Unlike PRAMs, insisting on non-shared memory leads to very good cache performance when simulating sequentially.



Thank You

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