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$$\begin{pmatrix} M \\ V \end{pmatrix} \begin{pmatrix} V \\ V \end{pmatrix} = \begin{pmatrix} M \\ V \end{pmatrix}$$

$$\begin{pmatrix} M \\ V \\ V \end{pmatrix} = \begin{pmatrix} Mv \\ V \end{pmatrix} \longrightarrow \text{answer}$$

• Random linear projection M: $\mathbb{R}^n \to \mathbb{R}^k$ that preserves properties of any $v \in \mathbb{R}^n$ with high probability where $k \ll n$.

$$\begin{pmatrix} M \\ v \\ v \end{pmatrix} = \begin{pmatrix} Mv \\ v \end{pmatrix} \longrightarrow \text{answer}$$

 <u>Many Results</u>: Estimating norms, entropy, support size, quantiles, heavy hitters, fitting histograms and polynomials, ...

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- <u>Rich Theory</u>: Related to compressed sensing and sparse recovery, dimensionality reduction and metric embeddings, ...

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$$M \qquad \left) \left(\begin{array}{c} & & \\ & A_G \end{array} \right) = \left(\begin{array}{c} & MA_G \end{array} \right) \longrightarrow \text{answer} \\ & & \\ & & \\ & & \\ \end{array} \right) = \left(\begin{array}{c} & & \\ & MA_G \end{array} \right) \rightarrow \text{answer}$$

<u>Example</u>: Project O(n²)-dimensional adjacency matrix A_G to Õ(n) dimensions and still determine if graph is bipartite?

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- <u>Example</u>: Project O(n²)-dimensional adjacency matrix A_G to Õ(n) dimensions and still determine if graph is bipartite?
- No cheating! Assume M is finite precision etc.

• In semi-streaming, want to process graph defined by edges $e_1, ..., e_m$ with $\tilde{O}(n)$ memory and reading sequence in order.

In semi-streaming, want to process graph defined by edges
e₁, ..., e_m with Õ(n) memory and reading sequence in order.

[Muthukrishnan 05; Feigenbaum, Kannan, McGregor, Suri, Zhang 05]

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<u>Sketches</u>: To delete e from G: update MA_G→MA_G-MA_e=MA_{G-e}











a) Connectivityb) Applications



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• <u>Catch</u>: Sketch must be homomorphic for algorithm operations.

Algorithm (Spanning Forest):

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 2. Contract selected edges. Repeat until no edges.



Lemma: Takes O(log n) steps and selected edges include spanning forest.

For node i, let ai be vector indexed by node pairs. Non-zero entries: ai[i,j]=1 if j>i and ai[i,j]=-1 if j<i.</p>

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- Example:



 \oslash Lemma: For any subset of nodes S \subset V,

support
$$\left(\sum_{i\in S} \mathbf{a}_i\right) = E(S, V \setminus S)$$

Ingredient 3: lo-Sampling

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Solution Lemma: Exists random $C \in \mathbb{R}^{d \times m}$ with $d = O(\log^2 m)$ such that for any $a \in \mathbb{R}^m$ $Ca \longrightarrow e \in \text{support}(a)$ with probability 9/10.
[Cormode, Muthukrishnan, Rozenbaum 05; Jowhari, Saglam, Tardos 11]
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 $\sum_{j\in S} C_i \mathbf{a}_j = C_i \left(\sum_{j\in S} \mathbf{a}_j \right) \longrightarrow e \in \operatorname{support}(\sum_{j\in S} \mathbf{a}_j) = E(S, V \setminus S)$

- <u>Thm</u>: Can check connectivity with $O(n\log^3 n)$ -size sketch.
- Main Idea: a) Sketch! b) Run Algorithm in Sketch-Space



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• <u>Lemma</u>: Number of connected components doubles iff G is bipartite. Can sketch G' implicitly.

<u>Idea</u>: Given G, define graph G' where a node v becomes v₁ and v₂ and edge (u,v) becomes (u₁,v₂) and (u₂,v₁).



• <u>Lemma</u>: Number of connected components doubles iff G is bipartite. Can sketch G' implicitly.

Idea: Given G, define graph G' where a node v becomes v1 and v2 and edge (u,v) becomes (u1,v2) and (u2,v1).



- <u>Lemma</u>: Number of connected components doubles iff G is bipartite. Can sketch G' implicitly.
- <u>Thm</u>: Can check bipartiteness with O(nlog³ n)-size sketch.

• <u>Idea</u>: If n_i is the number of connected components if we ignore edges with weight greater than $(1+\epsilon)^i$, then:

$$w(MST) \leq \sum_{i} \epsilon (1+\epsilon)^{i} n_{i} \leq (1+\epsilon) w(MST)$$

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- <u>Thm</u>: Can (I+ε) approximate MST in one-pass dynamic semi-streaming model.
- <u>Thm</u>: Can find exact MST in dynamic semi-streaming model using O(log n/log log n) passes.

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- <u>Thm</u>: Can check k-connectivity with O(nklog³ n)-size sketch.
- <u>Extension</u>: There exists a $O(\epsilon^{-2}n\log^5 n)$ -size sketch with which we can approximate all cuts up to a factor $(1+\epsilon)$.



Original Graph



Sparsifier Graph

Algorithm (k-Connectivity):

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For i=2 to k:

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 Run Algorithm in Sketch Space:
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 Use M²A_G-M²A_{F1}=M²(A_G-A_{F1})=M²(A_{G-F1}) to find F₂

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Use M³A_G-M³A_{F1}-M³A_{F2}=M³(A_{G-F1-F2}) to find F₃

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etc.

- A graph is k-connected if every cut has size \geq k.
- <u>Thm</u>: Can check k-connectivity with O(nklog³ n)-size sketch.
- <u>Extension</u>: There exists a $O(\epsilon^{-2}n\log^4 n)$ -size sketch with which we can approximate all cuts up to a factor $(1+\epsilon)$.



Original Graph



Sparsifier Graph

Summary

- <u>Graph Sketches:</u> Initiates the study of linear projections that preserve structural properties of graphs. Application to dynamic-graph streams and are embarrassingly parallelizable.
- <u>Properties:</u> Connectivity, sparsifiers, spanners, bipartite, minimum spanning trees, small cliques, matchings, ...



ありがとう!
