

Constant-Factor Approximation for ATSP with Two Edge Weights

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joint work with Ola Svensson and László A. Végh

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Traveling Salesman Problem

Given distances between n cities, find the shortest tour which visits them all.

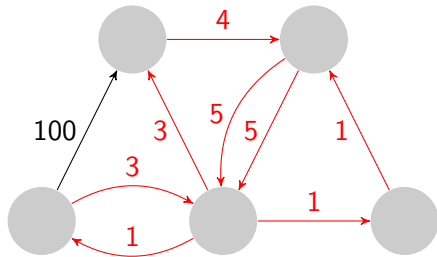
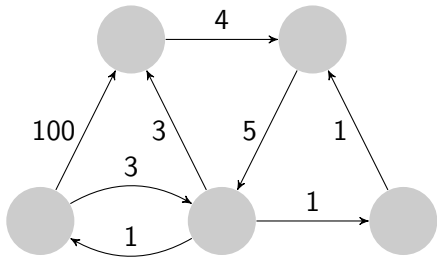
- ▶ Probably the best known NP-hard optimization problem
- ▶ Variants studied in mathematics as early as the 1800s
- ▶ Still huge gaps in understanding, especially of the asymmetric version

Definition of ATSP

Given: weighted directed graph $G = (V, E, w)$, $w : E \rightarrow \mathbb{R}_+$.

Find the cheapest multiset of edges $F \subseteq E$ such that the subgraph (V, F) is Eulerian and connected.

- ▶ Eulerian: for each vertex, indegree = outdegree.
- ▶ $w(F) = \sum_{e \in F} w(e)$: weight (cost) of tour.



Held-Karp relaxation

Write x_e for the number of times we traverse edge e and

$$\text{minimize} \quad \sum_{e \in E} w_e x_e$$

$$\begin{aligned} \text{subject to} \quad & x(\delta^+(v)) = x(\delta^-(v)) && \text{for all } v \in V, \\ & x(\delta^+(S)) \geq 1 && \text{for all } \emptyset \neq S \subsetneq V, \\ & x_e \geq 0 && \text{for all } e \in E \end{aligned}$$

where $\delta^+(v)$: outgoing edges of v , $\delta^-(v)$: incoming edges.

That is:

- ▶ x should be Eulerian,
- ▶ x should connect the entire graph.

Can be solved in polynomial time.

ATSP is NP-hard (even if G is unweighted, undirected etc.)

Main questions:

What is the best approximation ratio possible (in polynomial time)?

What is the integrality gap of the Held-Karp relaxation?

- ▶ Approximation algorithms:
 - ▶ $\mathcal{O}\left(\frac{\log n}{\log \log n}\right)$ -approximation algorithm [Asadpour et al. 2010]
 - ▶ lower bound: 75/74-approximation is NP-hard [Karpinski et al. 2013]
- ▶ Integrality gap:
 - ▶ upper bound: $\mathcal{O}(\text{poly } \log \log n)$ [Anari, Oveis Gharan 2014]
 - ▶ lower bound: 2 [Charikar et al. 2006]
 - ▶ (smaller gap between lower and upper bounds)
- ▶ Is there an $\mathcal{O}(1)$ -approximation algorithm?

Special cases

What if we assume something about G ?

Oveis Gharan, Saberi 2011

$\mathcal{O}(1)$ -approximation algorithm for ATSP on **bounded-genus graphs** (incl. planar graphs)

(because bounded-genus graphs have $\mathcal{O}(1)$ -*thin trees*)

For symmetric TSP, since 2010, improvements when G is **unweighted** (graph TSP). What about ATSP?

Svensson 2015

$\mathcal{O}(1)$ -approximation algorithm for ATSP on **unweighted** graphs

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- ▶ Implies $\mathcal{O}(w_{\max}/w_{\min})$ -approximation in general – but this ratio can be unbounded
- ▶ Next logical step?

This work: Svensson, T., Vegh 2016

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(also a constant bound on the integrality gap)

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Local-Connectivity ATSP

Svensson 2015

$\mathcal{O}(1)$ -approximation algorithm for ATSP on **unweighted** graphs

follows by:

- ▶ defining a new easier problem called Local-Connectivity ATSP
- ▶ reduction (technical core of paper):

For any class of graphs, if can approximate Local-Connectivity ATSP well, then can approximate ATSP well!

- ▶ can indeed approximate Local-Connectivity ATSP well for unweighted graphs (easy part of paper)
- (note similarity with the thin tree approach)

For what other classes of graphs can we approximate Local-Connectivity ATSP well?

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More motivation

- ▶ A lot of work to prove the reduction
- ▶ Approximating Local-Connectivity ATSP on unweighted graphs is easy
- ▶ Now makes sense to put more work into the latter

Good sign: previously $\mathcal{O}(1)$ -approximation for unweighted ATSP was unknown – now it follows easily

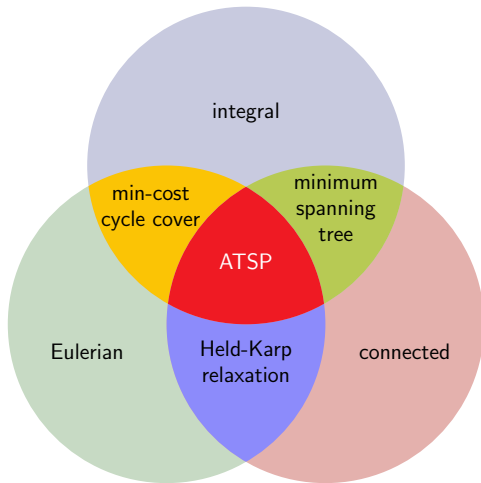
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Pick two

Want the cheapest $x : E \rightarrow \mathbb{R}_+$ which touches every vertex and is:



Everything in the diagram is easy, except for ATSP!

Repeated cycle cover algorithm [Frieze et al. 1982]

- ▶ Pick cheapest cycle cover (**polytime solvable**)
- ▶ “Contract”
- ▶ Repeat

Number of phases = approximation ratio = $\log n$
because **connectivity too weak**

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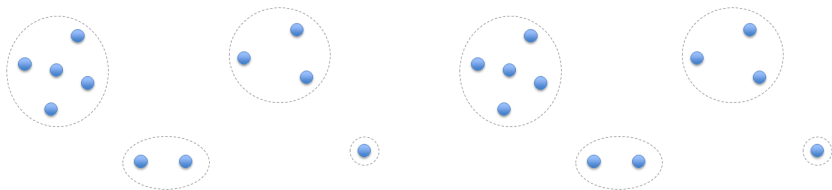


Find a subproblem which **yields stronger connectivity** than min-cost cycle cover but **weaker** than ATSP (and not polytime solvable)

Local-Connectivity ATSP

Given: weighted directed graph $G = (V, E, w)$, $w : E \rightarrow \mathbb{R}_+$,
and a partitioning $V = V_1 \cup \dots \cup V_k$.

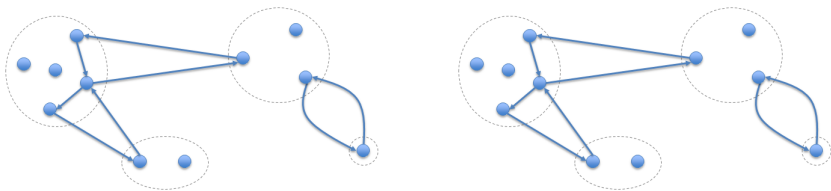
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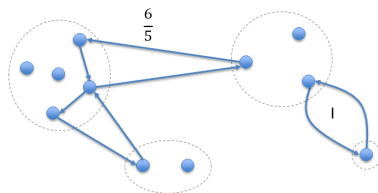
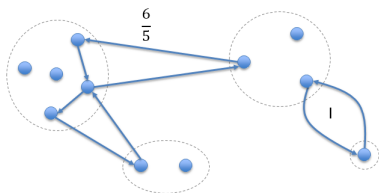


Local-Connectivity ATSP

Given: weighted directed graph $G = (V, E, w)$, $w : E \rightarrow \mathbb{R}_+$,
and a partitioning $V = V_1 \cup \dots \cup V_k$.

Find a **cheap** multiset of edges $F \subseteq E$ such that the subgraph (V, F) is Eulerian and **each cut** $(V_i, \overline{V_i})$ **is crossed**.

Algorithm is α -**light** if each component in (V, F) is **locally cheap**:
 $\frac{\# \text{ edges}}{\# \text{ vertices}} \leq \alpha$. (*oversimplified*)



Local-Connectivity ATSP

Framework:

$$G = (V, E, w) \quad \Leftarrow$$



$$\text{lb} : V \rightarrow \mathbb{R}_+ \text{ with} \\ \sum_{v \in V} \text{lb}(v) = \text{OPT}_{\text{LP}}$$

$$\text{partition } V = V_1 \cup \dots \cup V_k \quad \Leftarrow$$



solution F which is locally cheap
w.r.t. lb

Local-Connectivity ATSP

An α -light algorithm for Local-Connectivity ATSP has two phases:

- ▶ Given $G = (V, E, w)$, output $\text{lb} : V \rightarrow \mathbb{R}_+$ with $\sum_{v \in V} \text{lb}(v) = \text{OPT}_{\text{LP}}$.
 - ▶ lb stands for “lower bound”: a way to distribute the LP-lower-bound among vertices.
- ▶ Now, given also a partitioning $V = V_1 \cup \dots \cup V_k$, find multiset of edges $F \subseteq E$ such that:
 - ▶ subgraph (V, F) is Eulerian,
 - ▶ each V_i -cut is crossed: $|F \cap \delta^+(V_i)| \geq 1$ for $i = 1, \dots, k$,
 - ▶ F is cheap, even *locally*: for each connected component \tilde{G} of (V, F) we have $w(F \cap \tilde{G}) \leq \alpha \cdot \text{lb}(\tilde{G})$
(i.e. $\sum_{e \in F \cap E(\tilde{G})} w_e \leq \alpha \cdot \sum_{v \in V(\tilde{G})} \text{lb}(v)$).

Local-Connectivity ATSP

An α -light algorithm for Local-Connectivity ATSP has two phases:
Compared to an α -approximation for ATSP (w.r.t. HK relaxation):

- ▶ Given $G = (V, E, w)$, output $\text{lb} : V \rightarrow \mathbb{R}_+$ with $\sum_{v \in V} \text{lb}(v) = \text{OPT}_{\text{LP}}$. (Not present in ATSP.)
 - ▶ lb stands for “lower bound”: a way to distribute the LP-lower-bound among vertices.
- ▶ Now, given also a partitioning $V = V_1 \cup \dots \cup V_k$, (not given) find multiset of edges $F \subseteq E$ such that:
 - ▶ subgraph (V, F) is Eulerian,
 - ▶ each V_i -cut is crossed: $|F \cap \delta^+(V_i)| \geq 1$ for $i = 1, \dots, k$,
In ATSP, every cut is crossed: $|F \cap \delta^+(S)| \geq 1$ for $\emptyset \subsetneq S \subsetneq V$,
 - ▶ F is cheap, even *locally*: for each connected component \tilde{G} of (V, F) we have $w(F \cap \tilde{G}) \leq \alpha \cdot \text{lb}(\tilde{G})$
(i.e. $\sum_{e \in F \cap E(\tilde{G})} w_e \leq \alpha \cdot \sum_{v \in V(\tilde{G})} \text{lb}(v)$).
In ATSP, F is globally cheap: $w(F) \leq \alpha \cdot \text{lb}(V) \leq \alpha \cdot \text{OPT}_{\text{LP}}$.

To recap:

- ▶ the connectivity requirement is **relaxed**: rather than crossing all cuts, F only needs to cross each component of the partition $V = V_1 \cup \dots \cup V_k$,
- ▶ the cost requirement is **strengthened**: rather than being cheap as a whole, F needs to be cheap locally at each connected component (w.r.t. some lb function).

Local-Connectivity ATSP

For any class of graphs:

Fact

If there is an α -approximation for ATSP (w.r.t. HK relaxation), then there is an α -light algorithm for Local-Connectivity ATSP.

Proof.

Output any $lb : V \rightarrow \mathbb{R}_+$ such that $\sum_{v \in V} lb(v) = \text{OPT}_{\text{LP}}$.

Disregard the partitioning and just run the ATSP algorithm. If its output is globally cheap, it's also locally cheap (since there is only one connected component). \square

Theorem (Svensson)

If there is an α -light algorithm for Local-Connectivity ATSP, then:

- ▶ the integrality gap of the Held-Karp relaxation is at most 5α ,*
- ▶ there is a 9.001α -approximation algorithm for ATSP.*

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And:

Fact

There is a 3-light algorithm for Local-Connectivity ATSP on **unweighted** graphs.

So:

Theorem

*There is a 27-approximation algorithm for ATSP on **unweighted** graphs.*

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If:

Fact

There is a $\mathcal{O}(1)$ -light algorithm for Local-Connectivity ATSP on **some class of graphs**.

Then:

Theorem

*There is a $\mathcal{O}(1)$ -approximation algorithm for ATSP on **that class of graphs**.*

Local-Connectivity ATSP

For any class of graphs:

Theorem (Svensson)

If there is an α -light algorithm for Local-Connectivity ATSP, then:

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- ▶ *there is a 9.001α -approximation algorithm for ATSP.*

And:

Theorem (Svensson, T., Vegh [IPCO 2016])

There is a $\mathcal{O}(1)$ -light algorithm for Local-Connectivity ATSP on **graphs with two edge weights**.

So:

Theorem

*There is a $\mathcal{O}(1)$ -approximation algorithm for ATSP on **graphs with two edge weights**.*

How to solve Local-Connectivity ATSP?

As a warmup, we show:

Fact

There is a 3-light algorithm for Local-Connectivity ATSP on unweighted graphs.

Even simpler: assume the given partitioning is the **singleton partition** $V = \{v_1\} \cup \dots \cup \{v_n\}$.

How to solve Local-Connectivity ATSP?

Recap of L-C ATSP for unweighted G , singleton partition

Given $G = (V, E)$ (unweighted), want:

- ▶ $lb : V \rightarrow \mathbb{R}_+$ such that $\sum_{v \in V} lb(v) = \text{OPT}_{\text{LP}}$,
- ▶ $F \subseteq E$: Eulerian multiset of edges

such that

- ▶ each singleton cut is crossed: $|F \cap \delta^+(v)| \geq 1$ for all $v \in V$,
- ▶ locally at each connected component \tilde{G} of (V, F) , F is cheap: $|F \cap E(\tilde{G})| \leq 3 \cdot lb(\tilde{G})$.

We round the LP solution x^* .

Define lb so that each node “pays” for its outgoing edges:

$$lb(v) := x^*(\delta^+(v)) = \sum_{e \in \delta^+(v)} x_e^*$$

And pick an integral solution $z = \mathbb{1}_F$ to the circulation problem:

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Left to verify:

- ▶ locally at each connected component \tilde{G} of (V, F) , F is cheap:
 $|F \cap E(\tilde{G})| \leq 3 \cdot \text{lb}(\tilde{G})$.

True for any $\tilde{G} \subseteq V$:

$$|F \cap E(\tilde{G})| \leq \sum_{v \in \tilde{G}} z(\delta^+(v)) \leq \sum_{v \in \tilde{G}} \lceil x^*(\delta^+(v)) \rceil \leq \sum_{v \in \tilde{G}} 2x^*(\delta^+(v)) = 2\text{lb}(\tilde{G}).$$

Crucial: rounding up is fine because $x^*(\delta^+(v)) \geq 1$.

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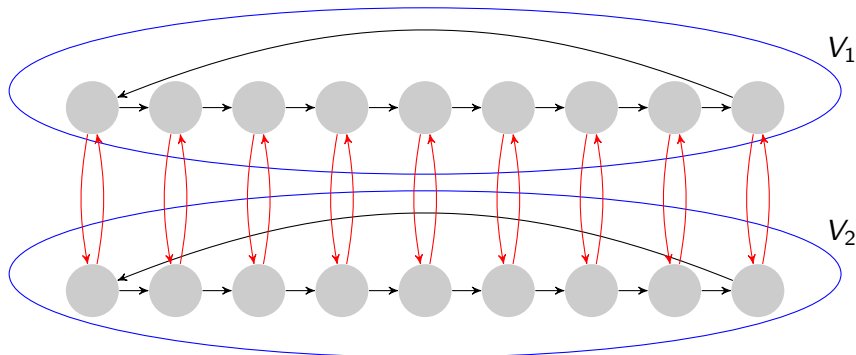
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How to solve Local-Connectivity ATSP

- ▶ Got 2-light algorithm
- ▶ Dealing with arbitrary partitions $V = V_1 \cup \dots \cup V_k$ makes it 3-light

Two edge weights

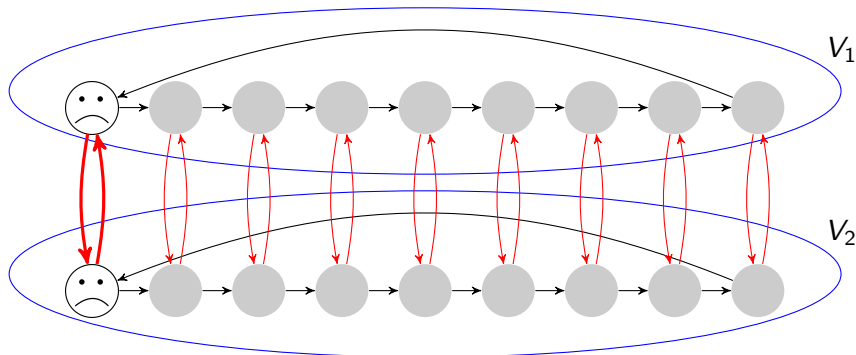
- ▶ Why not just do the same?



- ▶ Black edges are cheap and have $x_e^* = 1 - \frac{1}{k}$
- ▶ Red edges are expensive and have $x_e^* = \frac{1}{k}$
- ▶ In x^* , each vertex pays only for $\frac{1}{k}$ expensive flow:
the **thick red solution** can't be paid locally

Two edge weights

- ▶ Why not just do the same?



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Two edge weights

Problem: rounding **red** x^* -flow from ε to 1 is too expensive

Solution: group small chunks of **red** x^* -flow together and then round them

- ▶ we use a **flow theorem** to find a small set T of **terminals**
- ▶ we reroute **red** x^* -flow to these terminals so that any path that uses an expensive edge must then go a terminal
- ▶ we put higher lb on terminals so the **red** x^* -flow can be paid for there

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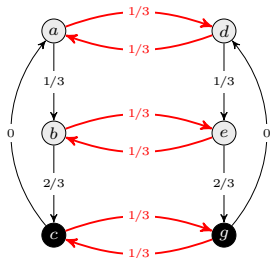
The flow theorem

Let E_1 : expensive edges.

Theorem

There is a set of terminals $T \subseteq V$ and a flow f from the tails of expensive edges to T which:

- ▶ $f \leq x^*$
- ▶ f saturates all expensive edges and has value $x^*(E_1)$
- ▶ T is small: $|T| \leq 8x^*(E_1)$



The picture shows f .

Red edges are expensive.

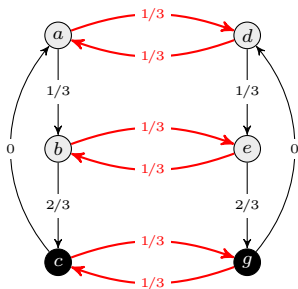
x^* is $1/3$ for expensive edges
and $2/3$ for cheap (black) edges.

Terminals T are black.

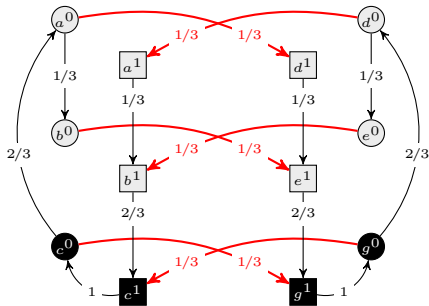
Splitting the graph

We use f and T to split G and x^* :

G and f



G_{sp} and x_{sp}^*



- ▶ copies v^1 carry the f -flow, copies v^0 carry the rest ($x^* - f$)
- ▶ now any cycle with an **expensive edge** must visit a terminal

And pick an integral solution $z = \mathbb{1}_F$ to the circulation problem:

$$1 \leq z(\delta^+(v)) \leq \lceil 2x_{sp}^*(\delta^+(v)) \rceil$$

Splitting the graph

- ▶ This mostly does the trick for the singleton partitioning.
- ▶ More work needed in the general case.

- ▶ What wider classes of graphs admit an $\mathcal{O}(1)$ -approximation?
 - ▶ Even the case of three edge weights is unsolved
- ▶ Beat $\mathcal{O}(\log n / \log \log n)$ for general case
 - ▶ Can we match the known integrality gap upper bound $\mathcal{O}(\text{poly } \log \log n)$?

Thank you for your attention!