

Threshold Influence Model for Allocating Advertising Budgets

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Topic: Budget Allocation for Marketing

- Modelling information diffusion
- Simple algorithm for optimization

TV



Newspaper



DM



Social ads



...

Media
sources

Q. How can we allocate budgets for effective advertisement?



Target customers

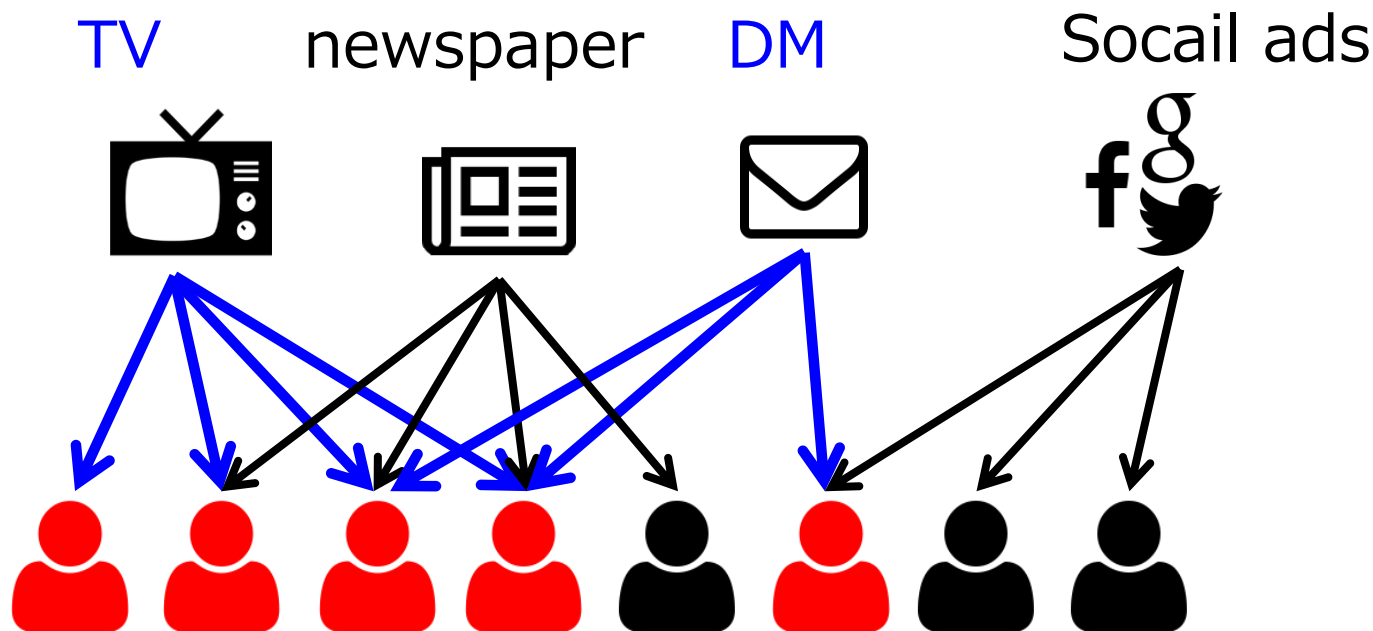
Simple Model: Maximum Coverage

- Maximize #customers watching ads

$$f(X) = \#\{ t : |N(t) \cap X| \geq 1 \}$$

$$\max. f(X)$$

$$\text{s.t. } |X| \leq k$$



TV and DM \rightarrow 5 people are covered

Two Influence Models[Alon et al.12]

$$\begin{array}{ll} \text{max.} & f(X) = \sum_{t \in T} \Pr[t] \\ \text{s.t.} & |X| \leq k \end{array}$$

Expected #influenced customers

➤ Source-side model \subseteq max. monotone submodular fns

- Each **source** has a probability

$$\Pr[t \text{ is influenced }] = 1 - \prod_{s \in N(t) \cap X} (1 - p_s)$$

➤ Target-side model \approx max. thresholds coverage

- Each **target** has a probability

$$\Pr[t \text{ is influenced }] = 1 - (1 - p_t)^{|N(t) \cap X|}$$

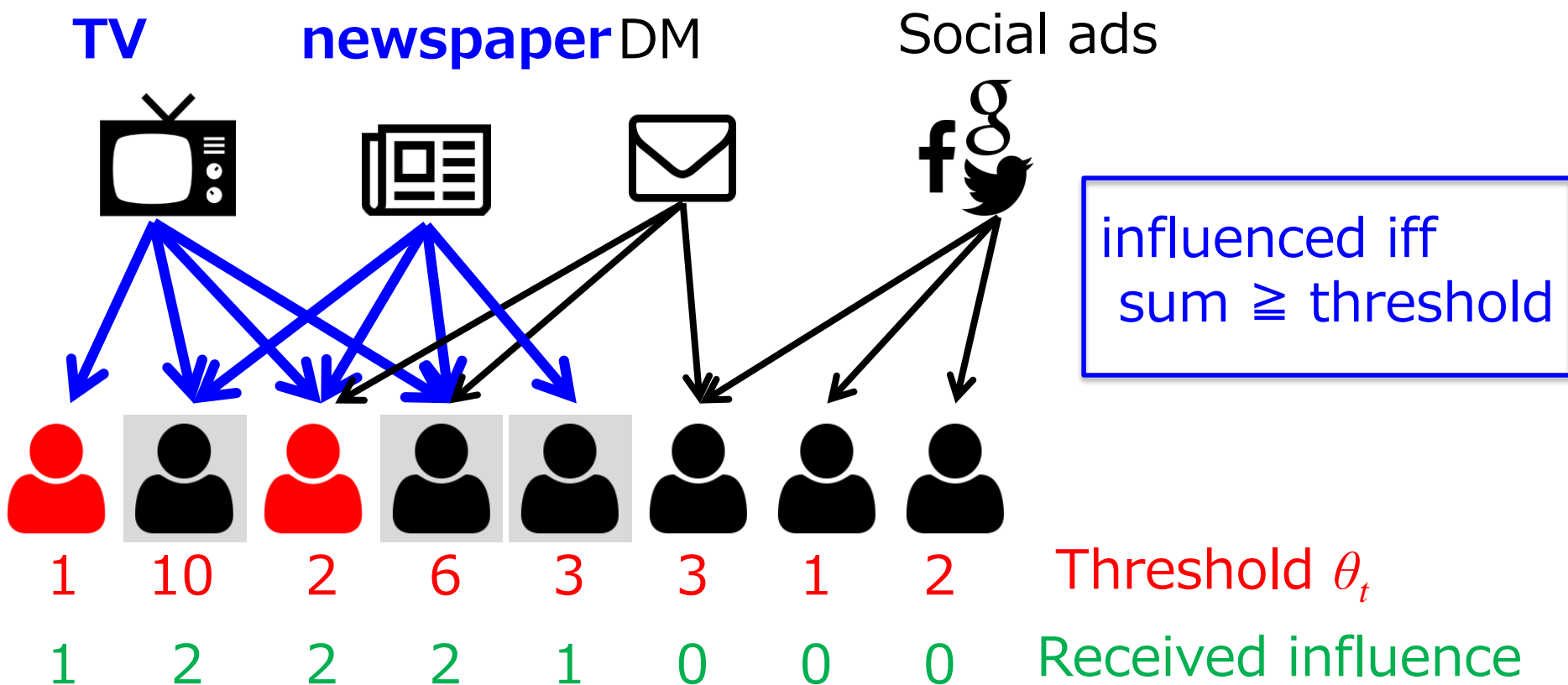
Maximum Thresholds Coverage

- Each customer has a **threshold**

$$f(X) = \#\{ t : |N(t) \cap X| \geq \theta_t \}$$

$$\max. f(X)$$

$$\text{s.t. } |X| \leq k$$



Maximum Thresholds Coverage

$$\begin{array}{ll} \max. & f(X) \\ \text{s.t.} & |X| \leq k \end{array}$$

#customers whose
received influence $\geq \theta_t$

➤ Observation

- Each threshold is 1 = maximum coverage
 - (1-1/e)-approximation
- Harder than the densest k -subgraph problem
 - f is not submodular or supermodular in general
 - If θ is randomly chosen, (1-1/e)-approximation

→ **Today:** Different objective on the same model

This Talk: Problem with Different Objective

➤ Maximizing **cost-effectiveness**

- performance of budgets without constraint

$$\max \frac{f(X)}{|X|}$$

customers influenced
the cost spent

➤ NP-hard

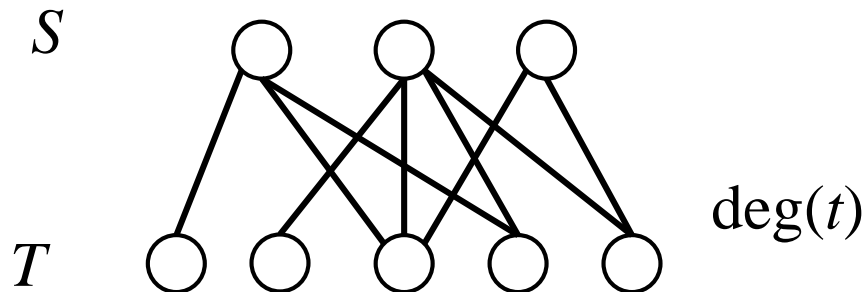
Result: Cost-Effectiveness Approximation

1) Decremental greedy algorithm

- Repeatedly remove one source w./ min. contribution
- Approx. factor = $\max \deg(t)$
- Works for a more general case
 - when influence is submodular
 - when sources/targets have weights

2) LP-based algorithm

- Approx. factor = $\max (\deg(t) - \theta_t + 1)$



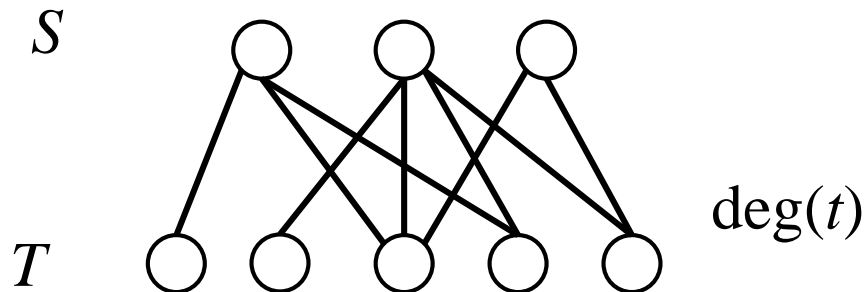
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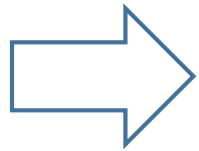


LP for Threshold Model

➤ Generalizing LP for densest subgraph [Charikar00]

($\theta_t = \deg(t) = 2$ for any t)

- Each source $s : x_s$
- Each target $t : y_t$



$$\max_{t \in T} \hat{a} y_t$$

sub to

Covering constraints

At least θ_t of neighboring x_s 's are 1
 $\Leftrightarrow y_t = 1$

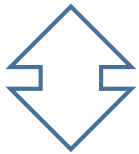
It is not good to have only

$$\sum_{s: \text{neighbor of } t} x_s \geq \theta_t y_t$$

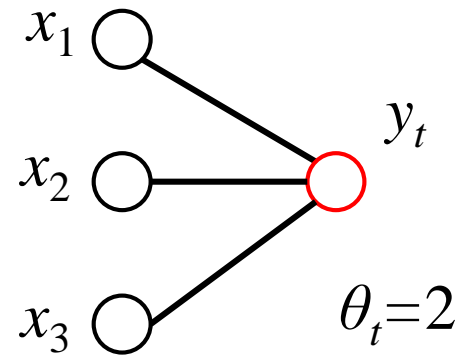
Constraint choosing 2 out of 3

- At least 2 of x_s 's are 1 $\Leftrightarrow y_t = 1$
 - \Leftrightarrow Sum of the 2 smallest ones is ≥ 1

$$\boxed{\begin{pmatrix} 1 & 1 & 1 \end{pmatrix} \quad \begin{pmatrix} 1 & 1 & 0 \end{pmatrix} \quad \begin{pmatrix} 1 & 0 & 0 \end{pmatrix} \quad \begin{pmatrix} 0 & 0 & 0 \end{pmatrix}}$$



$$\begin{aligned} x_1 + x_2 &\geq 3 y_t \\ x_2 + x_3 &\geq 3 y_t \\ x_1 + x_3 &\geq 3 y_t \end{aligned}$$



Constraint choosing θ_t out of $d=\text{deg}(t)$

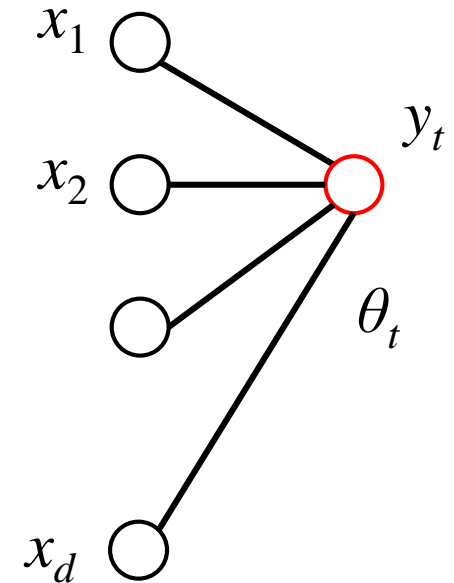
- ▶ At least θ_t of x_s 's are 1 $\Leftrightarrow y_t = 1$
 - \Leftrightarrow Sum of the p_t smallest ones is ≥ 1

$$(1 \quad \dots \quad \boxed{1} \quad 0 \quad \dots \quad 0)$$

$\underbrace{\hspace{1.5cm}}_{\theta_t}$
 $\underbrace{\hspace{1.5cm}}_{p_t = \text{deg}(t) - \theta_t + 1}$

$$\left\{ \begin{array}{l} x_1 + x_2 + \dots + x_{p_t} \geq y_t \\ x_2 + x_3 + \dots + x_{p_t+1} \geq y_t \\ \vdots \end{array} \right.$$

for any choice of p_t -size subsets



LP for Threshold Model

$$\max_{t \hat{=} T} \mathring{a} y_t$$

Exponential #consts

$$\mathring{a} x_s \stackrel{3}{=} y_t$$

$$\forall t \in T$$

$$\forall U \subseteq N(t), |U| = p_t$$

$$\mathring{a} x_s = 1$$

← Normalization

- Rem. This LP can be solved in poly-time
 - target t is valid if the sum of minimum p_t values $\geq y_t$

LP for Threshold Model

$$\max_{t \in T} \dot{a} y_t$$

Exponential #consts

$$\dot{a} x_s \leq y_t$$

$$\forall t \in T$$

$$\forall U \subseteq N(t), |U| = p_t$$

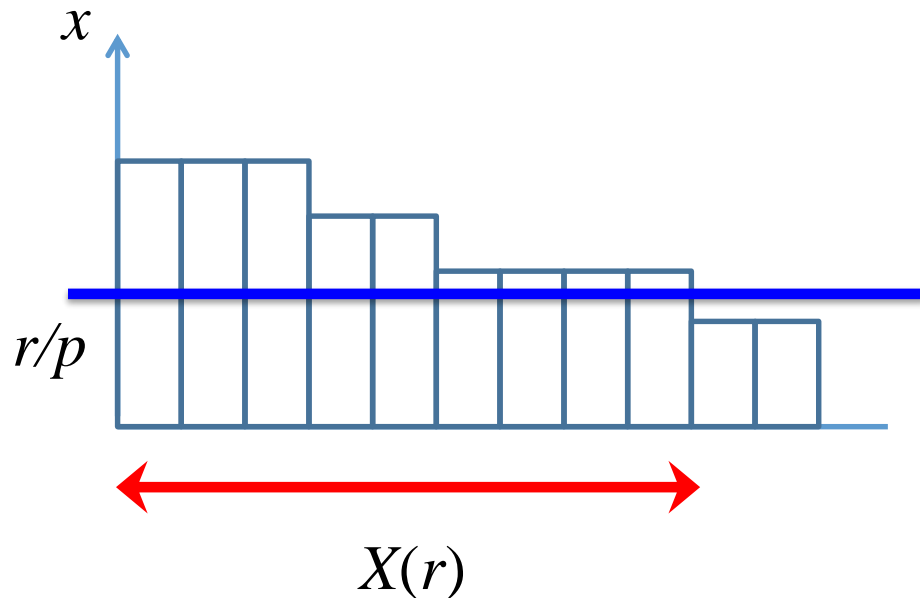
$$\dot{a} x_s = 1$$

← Normalization

[Thm]

LP-optimal value \geq optimal cost-effectiveness

- Find an LP-optimal solution x, y
- For a number r in $[0,1]$, define $X(r) = \{ s \mid x_s \geq r/p \}$
- Return the best $X(r)$ by changing r



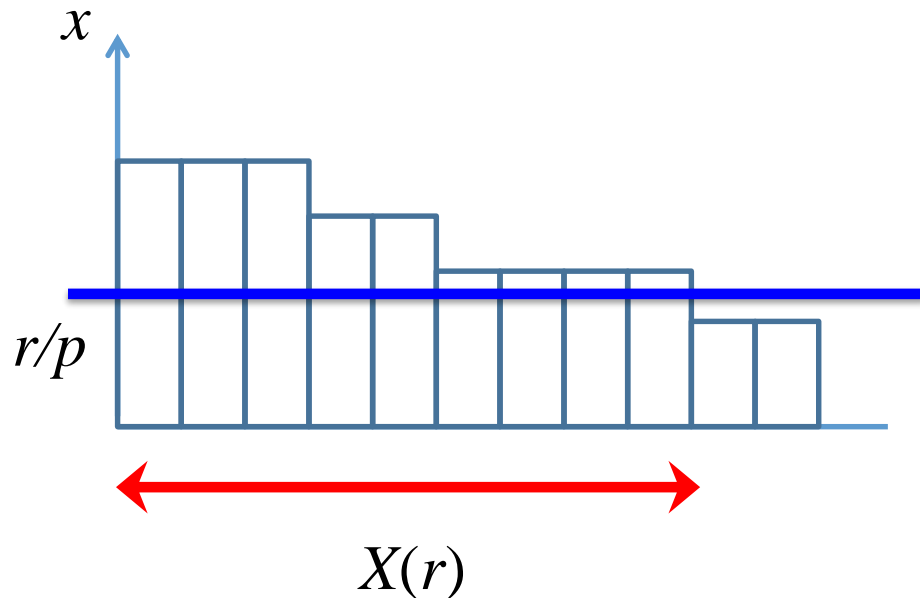
[Thm]

Rounded solution $X(r)$ is p -approximation

Rounding Algorithm

$$p = \max_{t \in T} p_t \quad 16$$

- Find an LP-optimal solution x, y
- For a number r in $[0,1]$, define $X(r) = \{ s \mid x_s \geq r/p \}$
- Return the best $X(r)$ by changing r



Covering at least

$$Y(r) = \{ t \mid y_t \geq r \}$$

Sum of the p_t smallest ones $\geq r$

\Leftrightarrow The θ_t th smallest ones $\geq r/p$

$\Leftrightarrow \theta_t$ of x_s 's are in $X(r)$

[lemma]

$$\exists r \quad \frac{|Y(r)|}{|X(r)|} \geq \frac{LPOPT}{p}$$

Proof Idea of Lemma

➤ If every r satisfies $|Y(r)| < \frac{LP}{p} |X(r)|$

$$\int_0^1 |Y(r)| dr < \frac{LP}{p} \int_0^1 |X(r)| dr$$

$$\max_{t \in T} \dot{a} y_t$$

$$\dot{a} x_s \leq y_t$$

$$\dot{a} x_s = 1$$

[lemma]

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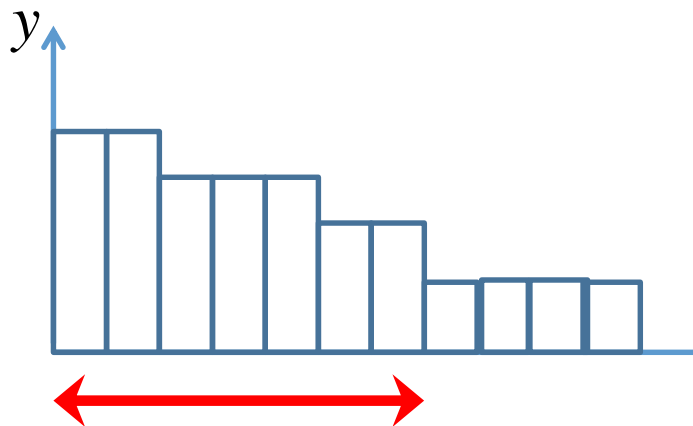
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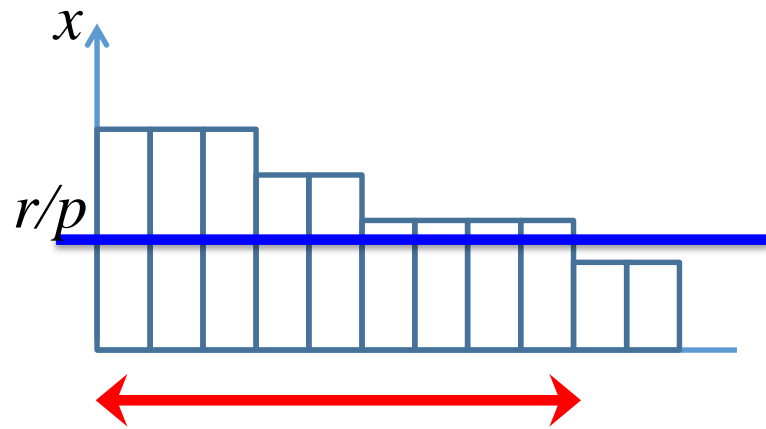
$$\int_0^1 |Y(r)| dr < \frac{LP}{p} \int_0^1 |X(r)| dr$$

$$\sum_t y_t = LP$$

$$\leq \sum_s px_s = p \rightarrow \text{contradiction}$$



$$Y(r) = \{ t \mid y_t \geq r \}$$



$$X(r)$$

$$\max_{t \in T} \dot{a} y_t$$

$$\dot{a} x_s \stackrel{3}{\geq} y_t$$

$$\dot{a} x_s = 1$$

$$s \in S$$

Summary

$$\max \frac{f(X)}{|X|}$$

➤ $\max(\deg(t) - \theta_t + 1)$ -approximation

• Q. Better approximation?

- P when $\theta_t = 1$ for any t (maximum coverage)
 - when f is submodular, opt is a singleton
- P when $\theta_t = \deg(t)$ for any t (densest subhypergraph)
 - f is supermodular

Q. Fractional optimization for other problems?

- Densest k -subgraph vs Densest subgraph

Q. Approx. for size-constrained problem?

- LP for densest k -subhypergraph gives $\deg(s)$ -approximation [Arulselman14]

$$\begin{array}{l} \max. \quad f(X) \\ \text{s.t.} \quad |X| \leq k \end{array}$$

Thank you for your attention