

Automata-Based Abstraction Refinement for μ HORS Model Checking

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This Talk

Efficient model checking algorithm for μ HORS
(Recursively-typed Higher-Order Recursion Scheme)

[Kobayashi, Igarashi, ESOP13]

which has been applied to automated verification of

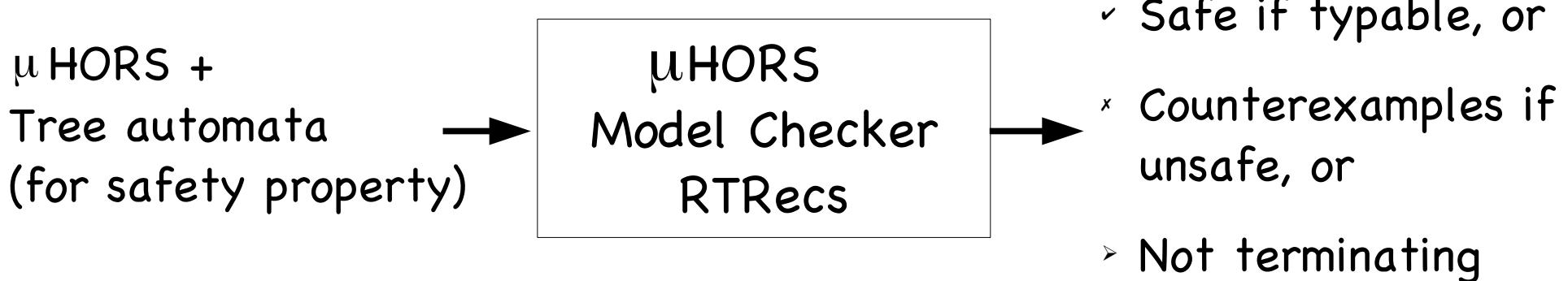
- functional OO (objected-oriented) and
- multi-threaded higher-order programs

Naoki Kobayashi, Xin Li. “Automata-based abstraction refinement for μ HORS model checking.” LICS15

Motivation: μ HORS Model Checking

[Kobayashi, Igarashi, ESOP13]

- μ HORS: a model that is Turing-complete
(\approx recursively-typed call-by-name λ -calculus)
- Sound procedure based on iterations of type inference, checking and refinement
- Relatively-complete w.r.t. certain condition of types

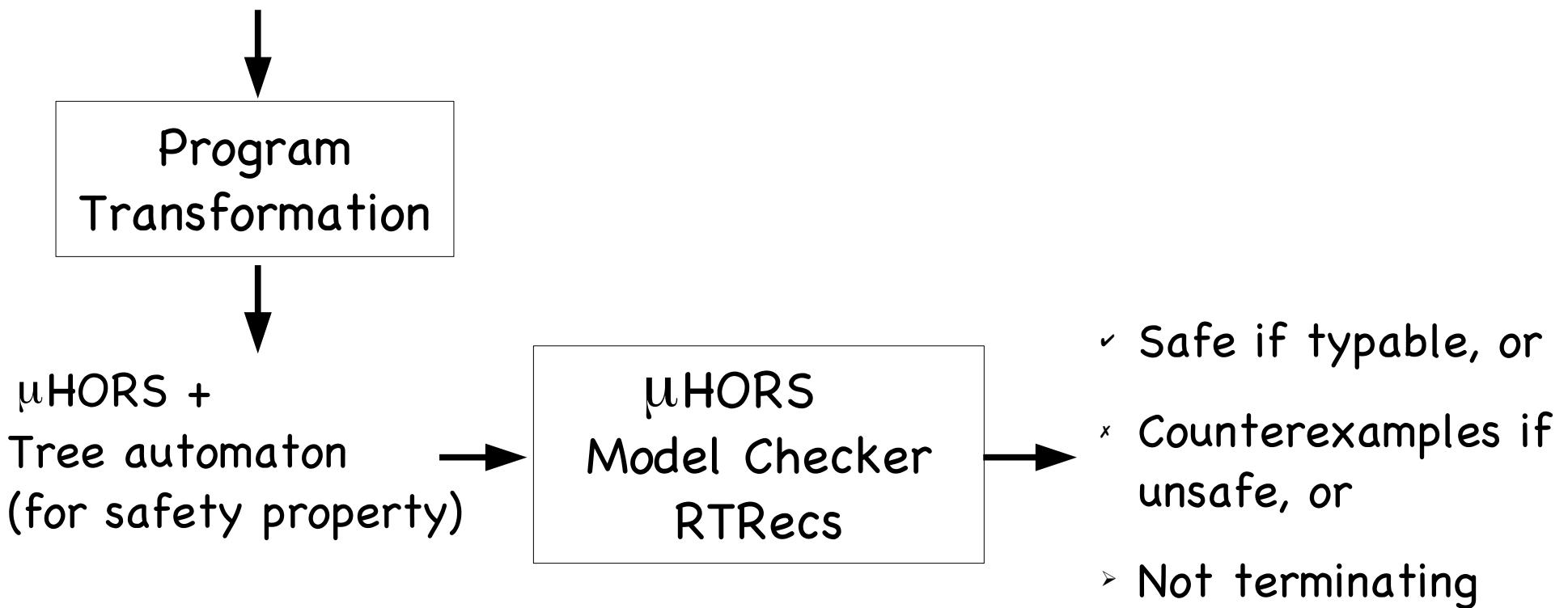


Motivation: μ HORS Model Checking

[Kobayashi, Igarashi, ESOP13]

- Applications to OO and multi-threaded programs

Featherweight Java or
Multi-threaded programs
+ Specification

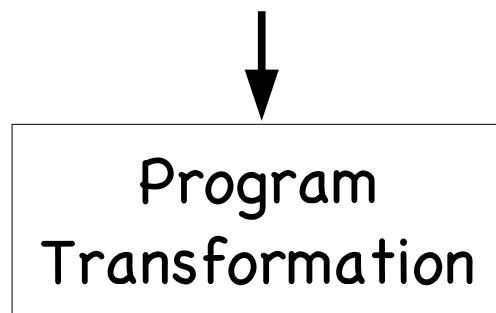


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[Kobayashi, Igarashi, ESOP13]

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CPS (continuation-passing style)
transformation as giving semantics
of the source program in λ -calculus

μ HORS +
Tree automaton
(for safety property)

μ HORS
Model Checker
RTRecs

- ✓ Safe if typable, or
- ✗ Counterexamples if unsafe, or
- Not terminating

Limitations of RTRecs

- Does not scale well as the size of the tree automaton states increases
- Counterexample finding by an exhaustive search of the state space is ineffective

Our Contributions

- A sound procedure for μ HORS that often scales better by experiments
- Relatively complete w.r.t. certain conditions of (a regular set of) term trees
- Evaluation by verification of OO and multi-threaded boolean programs with recursion

Outline

- Background
 - μ HORS model checking
 - Example: application to OO verification
- New model checking procedure for μ HORS
 - Overview and key ideas
 - Illustrate abstraction and refinement
 - Properties of the procedure
- Implementation and experiments
- Related work and conclusion

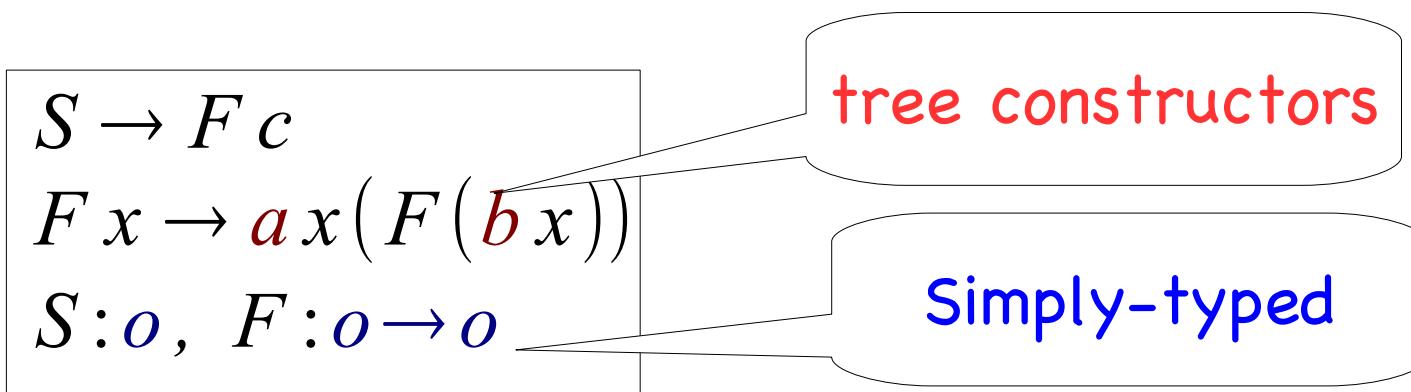
HORS: Higher-Order Recursion Scheme

Grammar for generating infinite trees

$$\begin{aligned} S &\rightarrow F\ c \\ F\ x &\rightarrow \textcolor{red}{a}\ x\left(F\left(\textcolor{red}{b}\ x\right)\right) \\ S:\textcolor{blue}{o},\ F:\textcolor{blue}{o} &\rightarrow o \end{aligned}$$

HORS: Higher-Order Recursion Scheme

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HORS: Higher-Order Recursion Scheme

Grammar for generating infinite trees

$$\begin{array}{l} S \rightarrow F c \\ F x \rightarrow a x (F(b x)) \\ S : o, \quad F : o \rightarrow o \end{array}$$

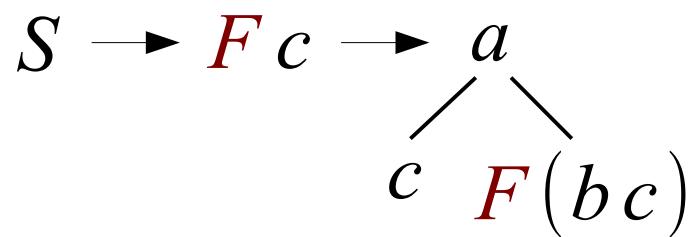
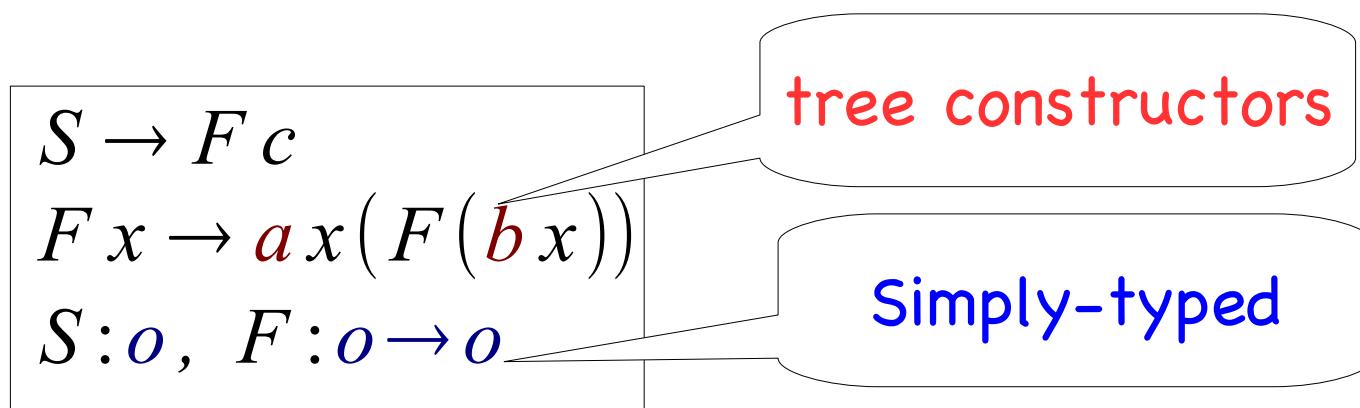
tree constructors

Simply-typed

$S \rightarrow F c$

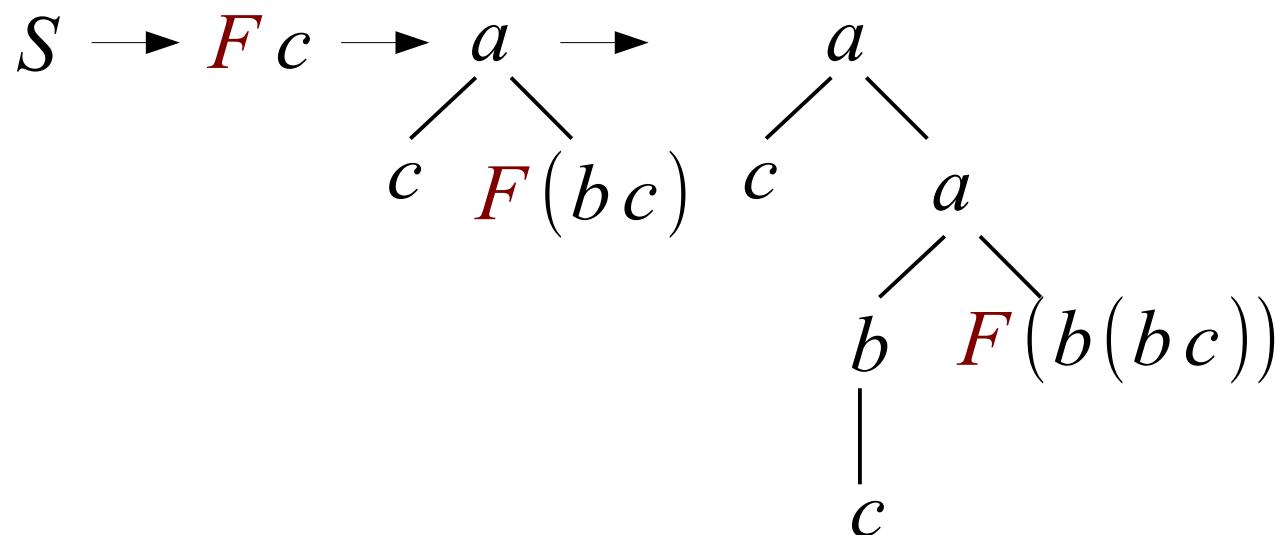
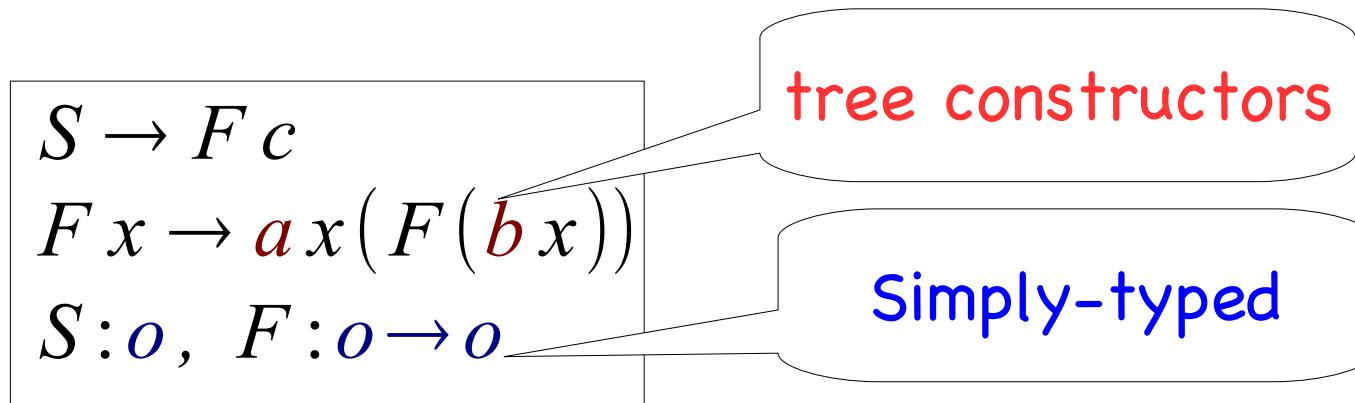
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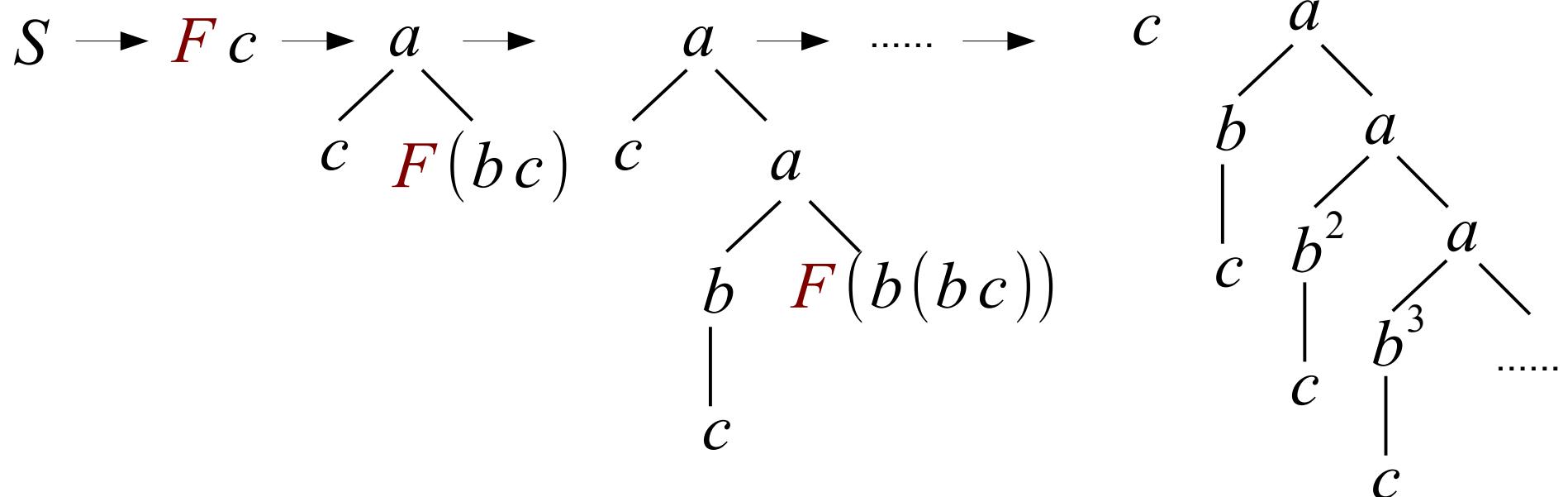
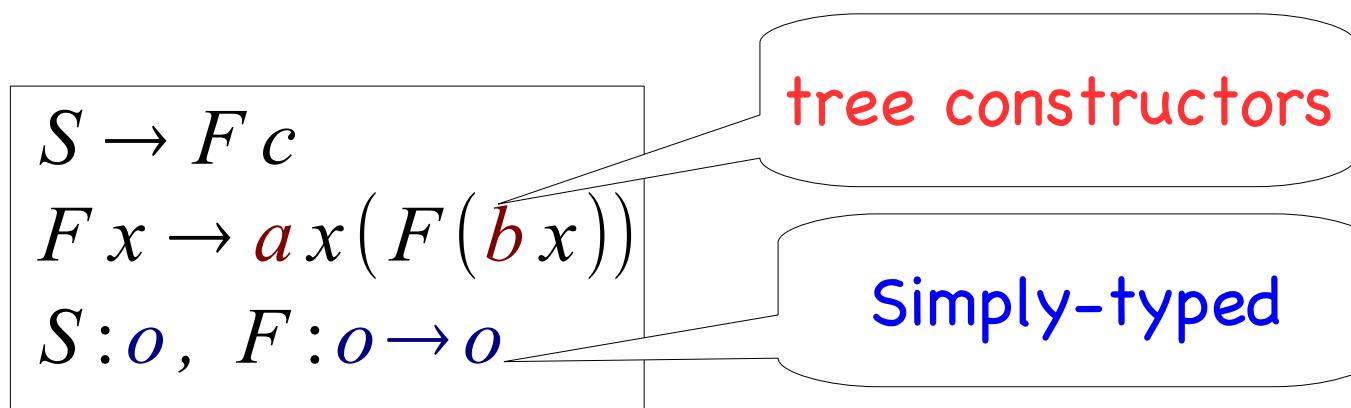
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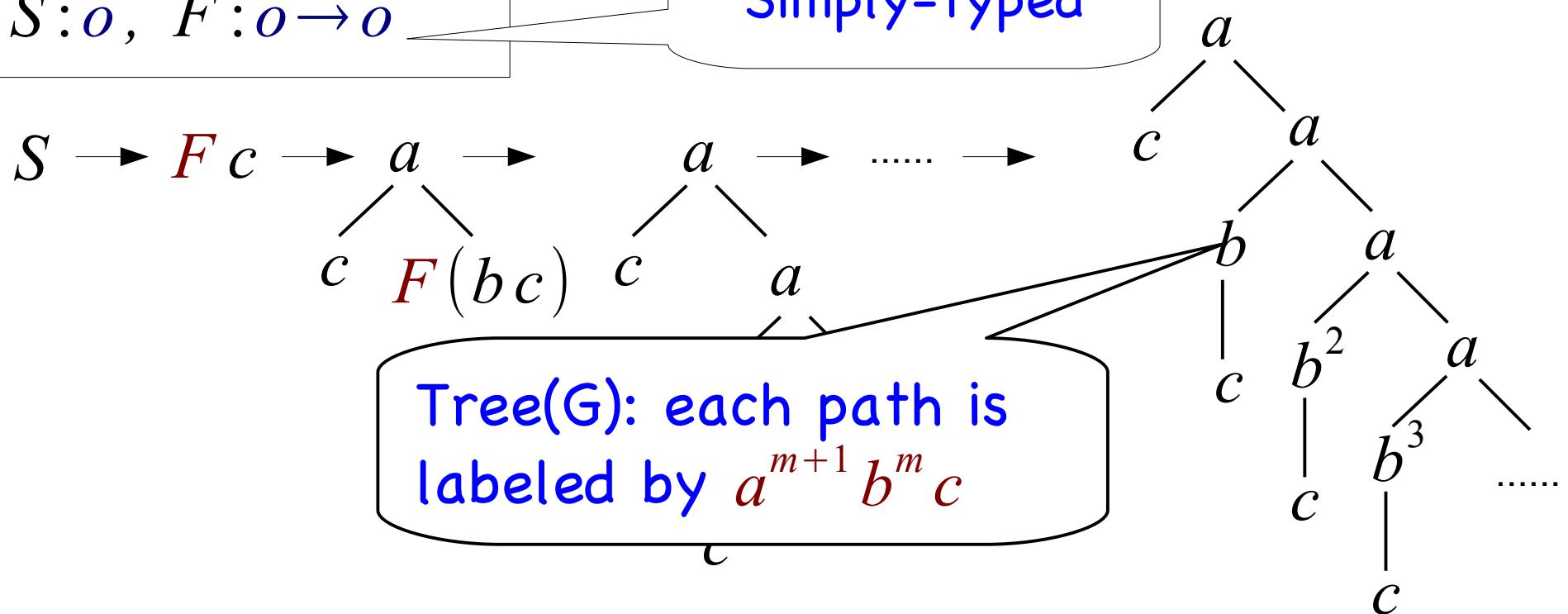
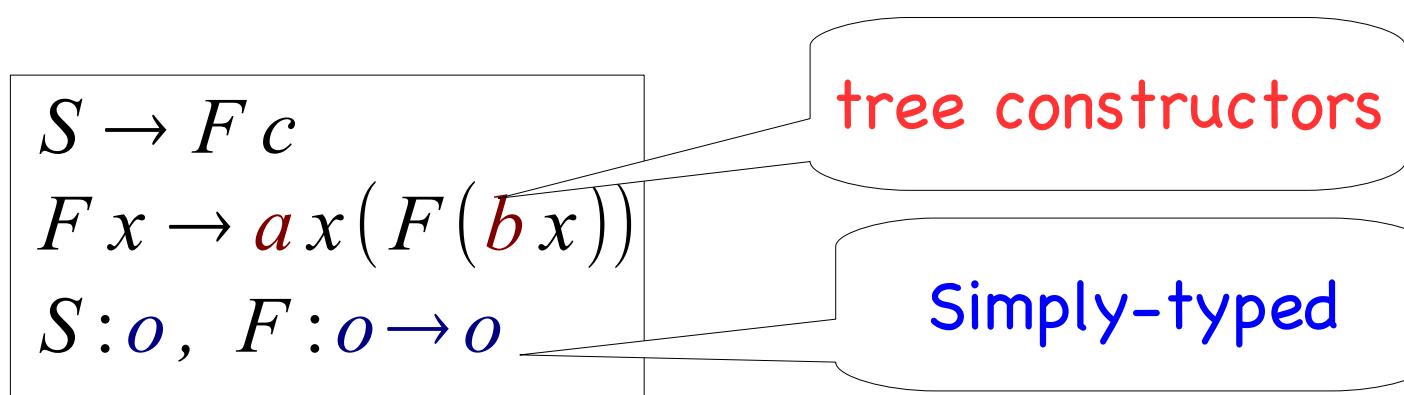
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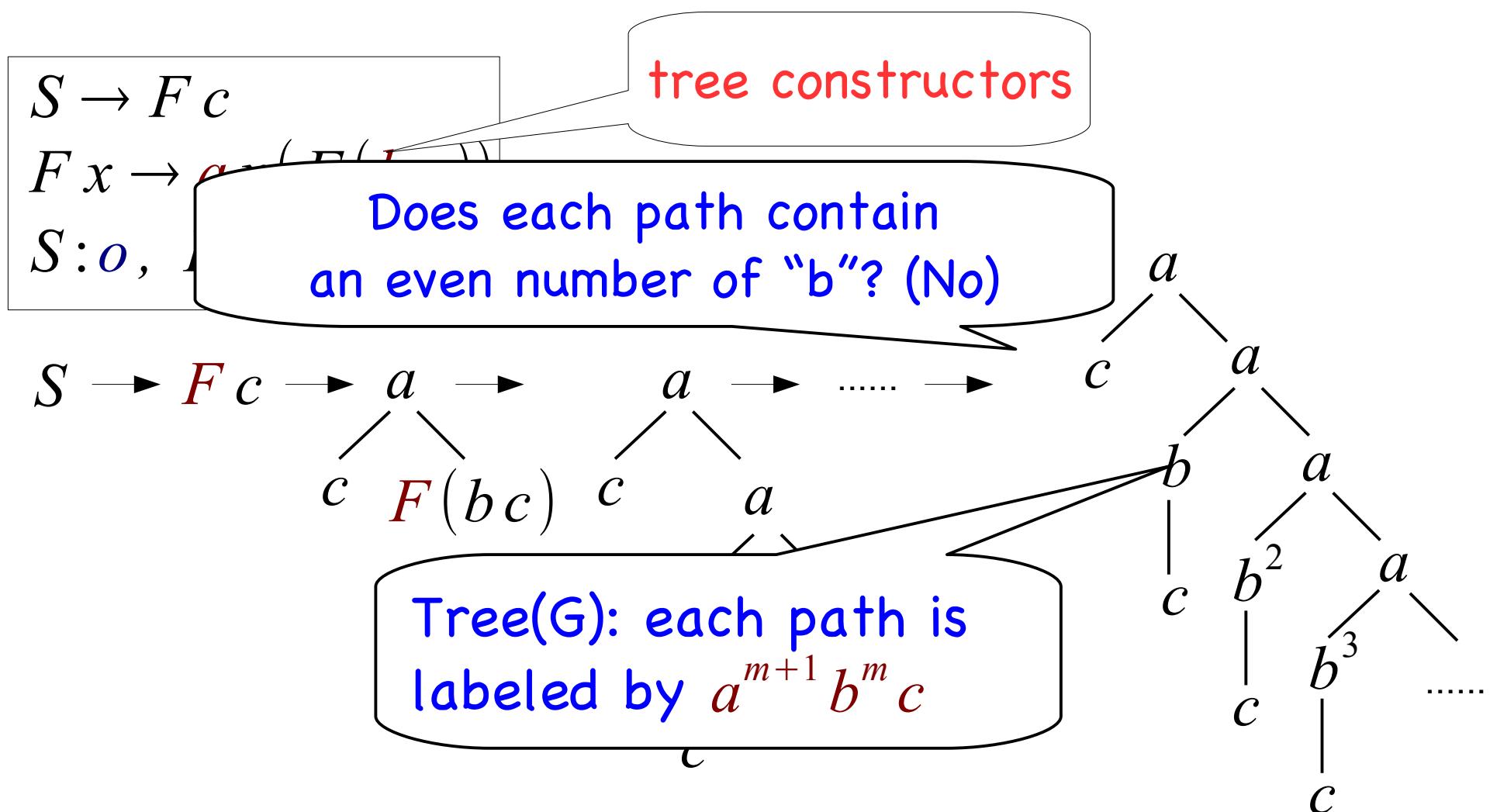
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μ HORS = HORS + Recursive Types

[Kobayashi, Igarashi, ESOP13]

Recursive types

$$\tau ::= \alpha \mid \tau_1 \rightarrow \dots \rightarrow \tau_n \rightarrow o \mid \mu \alpha. \tau$$

$$S \rightarrow F F b$$

$$F f g \rightarrow a(g(g c))(\textcolor{red}{f} f(B g))$$

$$B h x \rightarrow b(h x)$$

$$S : o, B : (o \rightarrow o) \rightarrow o \rightarrow o$$

$$F : \mu \alpha. \alpha \rightarrow (o \rightarrow o) \rightarrow o$$

μ HORS = HORS + Recursive Types

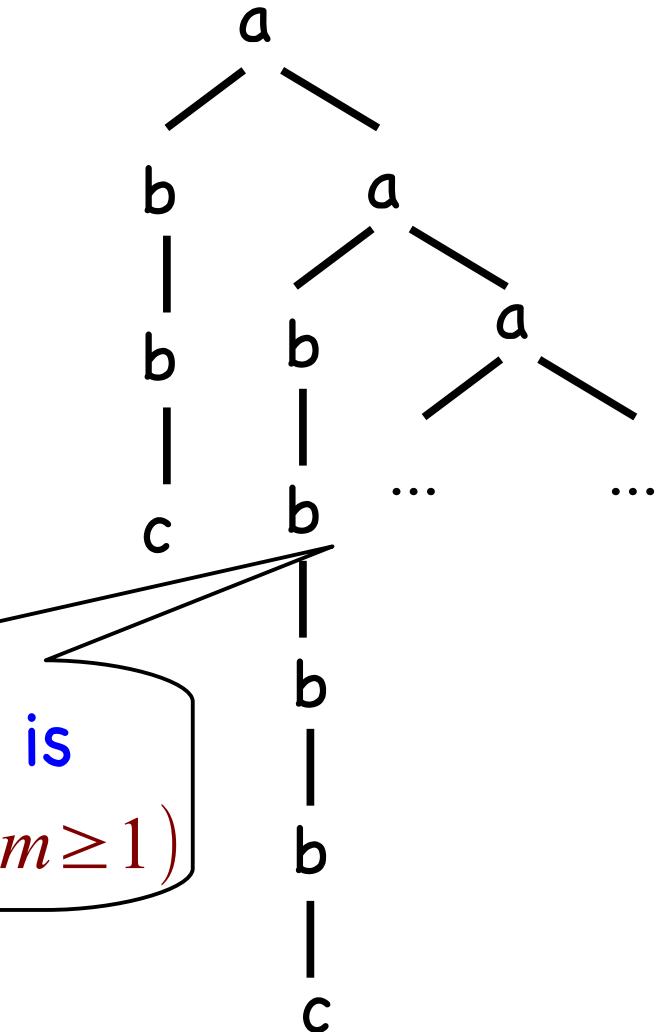
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Tree(G): each path is
labeled by $a^m b^{2m} c$ ($m \geq 1$)



μ HORS = HORS + Recursive Types

[Kobayashi, Igarashi, ESOP13]

Recursive types

$$\tau ::= \alpha \mid \tau_1 \rightarrow \dots \rightarrow \tau_n \rightarrow o \mid \mu \alpha. \tau$$

Does each path contain
an even number of "b"? (yes)

$$S \rightarrow F F$$

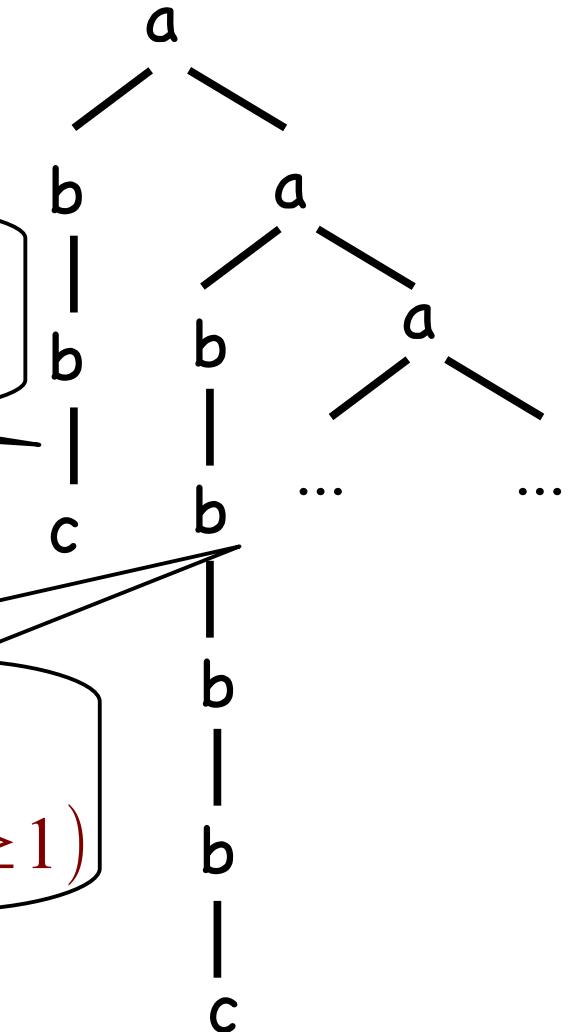
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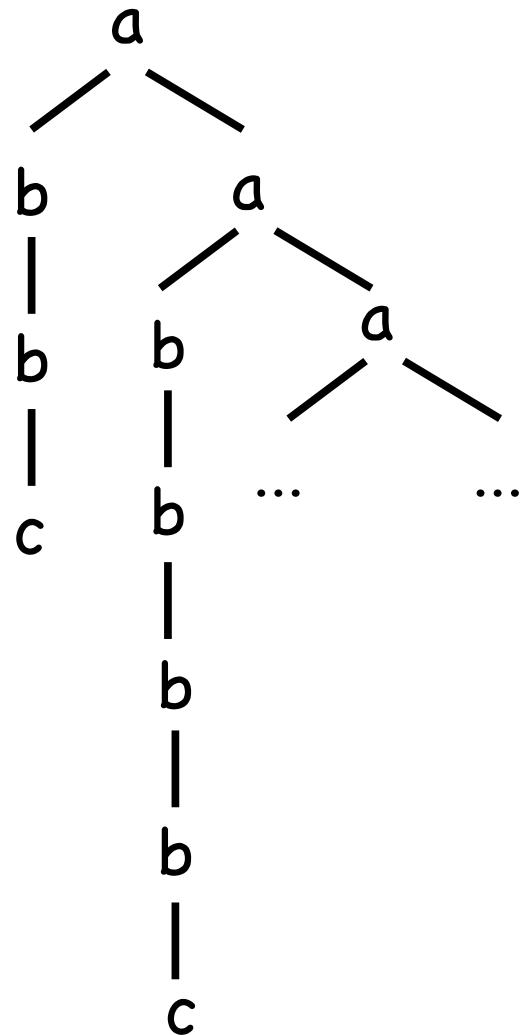
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Trivial Tree Automata [Klaus A., LMCS07]

(top-down deterministic, all states are final)



$A:$

$$\delta(q_0, a) = q_0 q_0$$

$$\delta(q_1, a) = q_1 q_1$$

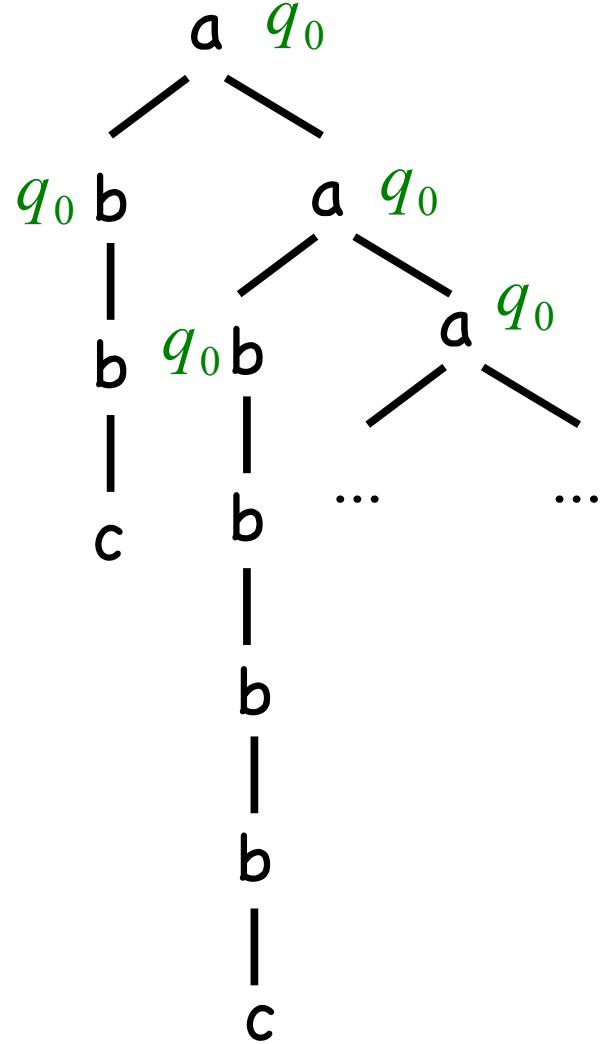
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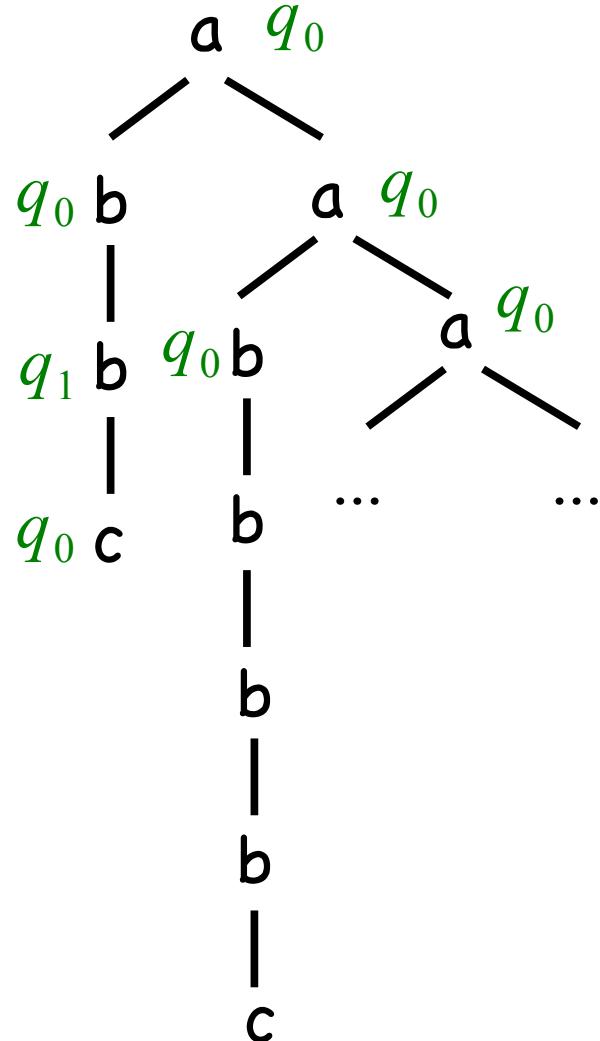
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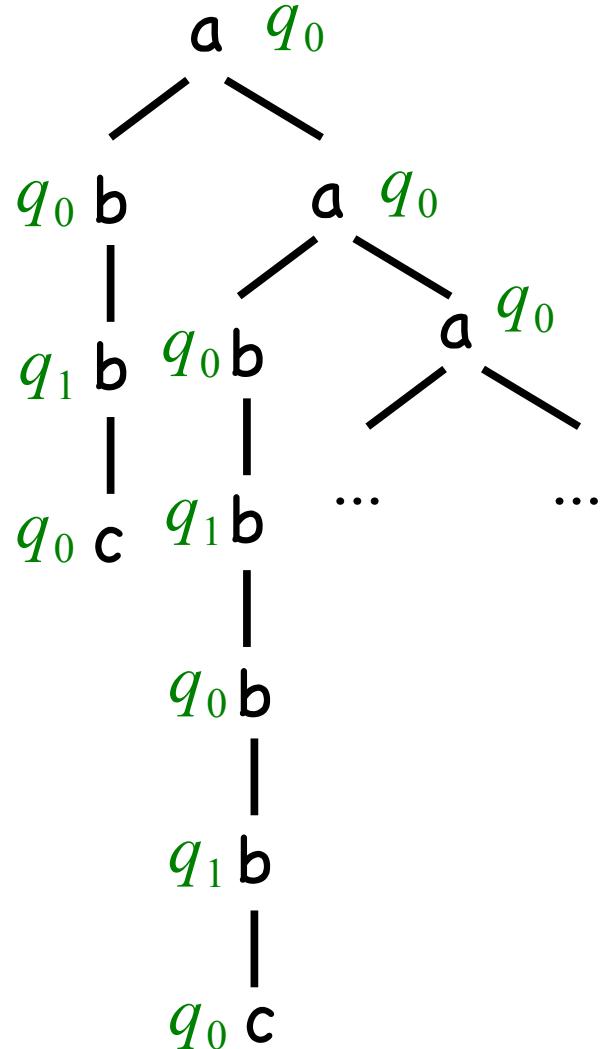
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A accepts Tree(G)

HORS Model Checking

Given G : HORS

A : Alternating parity tree automaton
(formula of modal μ -calculus or MSO logic)

Does A accept $\text{Tree}(G)$?

Theorem [Ong, LICS06]

HORS model checking is $k\text{-EXPTIME}$ -complete
for order- k recursion scheme

μ HORS Model Checking

Given G : μ HORS

A : trivial tree automaton

(for describing safety properties)

Does A accept $\text{Tree}(G)$?

Theorem [K., Igarashi, ESOP13] [Tsukada, K., FoSSaCS10]

μ HORS model checking is **undecidable**

(Sound and incomplete procedure is concerned)

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Example: Application to OO Verification

```
Class FileRd {  
    FileRd(File f) {...}  
    read() {...}  
    close() {...}  
    fun() {  
        if * then close()  
        else { read(); fun(); }  
    }  
  
    new FileRd("test.ml").fun();
```

Will files be properly closed?

(Example borrowed/modified from Kobayashi's talk@ESOP13)

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G:

FileRd $k \rightarrow k$ (Read Close Fun).
Read this $k \rightarrow r k$.
Close this $k \rightarrow c k$.
Fun this $k \rightarrow br (2@this\ this\ k)$
 $(1@this\ this\ (Fun\ this\ k))$.
 $S \rightarrow \text{FileRd} (\lambda x. 3@x\ x\ end)$.

A:

Each path of $\text{Tree}(G)$ ends with "c"

Will files be properly closed?

Does A accept $\text{Tree}(G)$?

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An object is as a tuple of methods

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The implicit parameter "this" in OO
A shorthand for (Read Close Fun)

Will files be properly closed?

Example: Application to OO Verification

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Will files be properly closed?

$i@x$: the i -th projection of x

Example: Application to OO Verification

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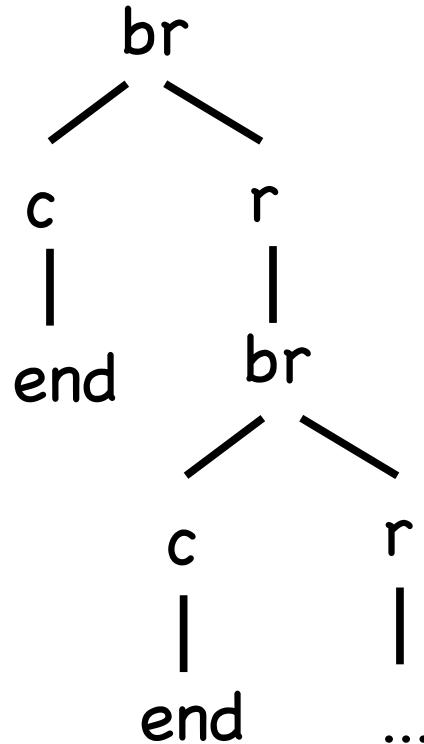
Will files be properly closed?

CPS transformation to
model event sequences

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Each path of Tree(G) ends with "c"

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Does A accept Tree(G) ? (yes)

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Configuration Graph [K., JACM13]

(a product of the reduction of G and A)

$$\boxed{\begin{array}{ll} G: & \\ S \rightarrow F F b & Bhx \rightarrow b(hx) \\ F f g \rightarrow a(g(gc))(ff(Bg)) & \\ A: & \\ \delta(q_0, a) = q_0 q_0 & \delta(q_0, b) = q_1 \\ \delta(q_1, a) = q_1 q_1 & \delta(q_1, b) = q_0 \\ & \delta(q_0, c) = \epsilon \end{array}}$$

Configuration Graph [K., JACM13]

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(S, q_0)
↓
 $[S]$
 (FFb, q_0)

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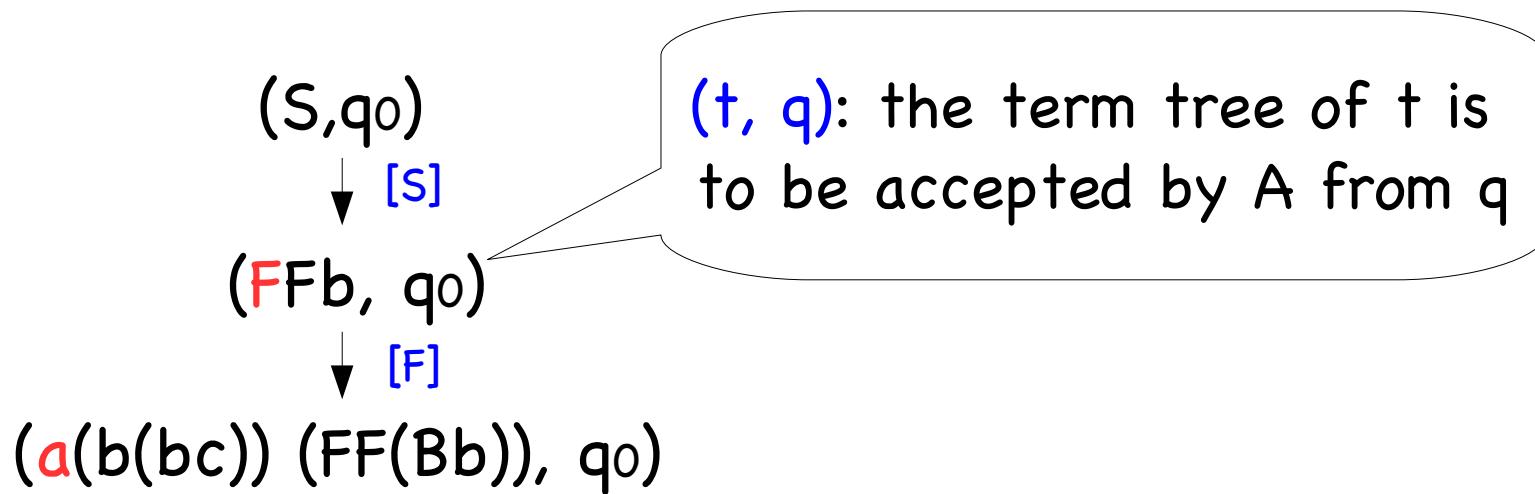
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↓
 $[S]$
 (FFb, q_0)

(t, q) : the term tree of t is
to be accepted by A from q

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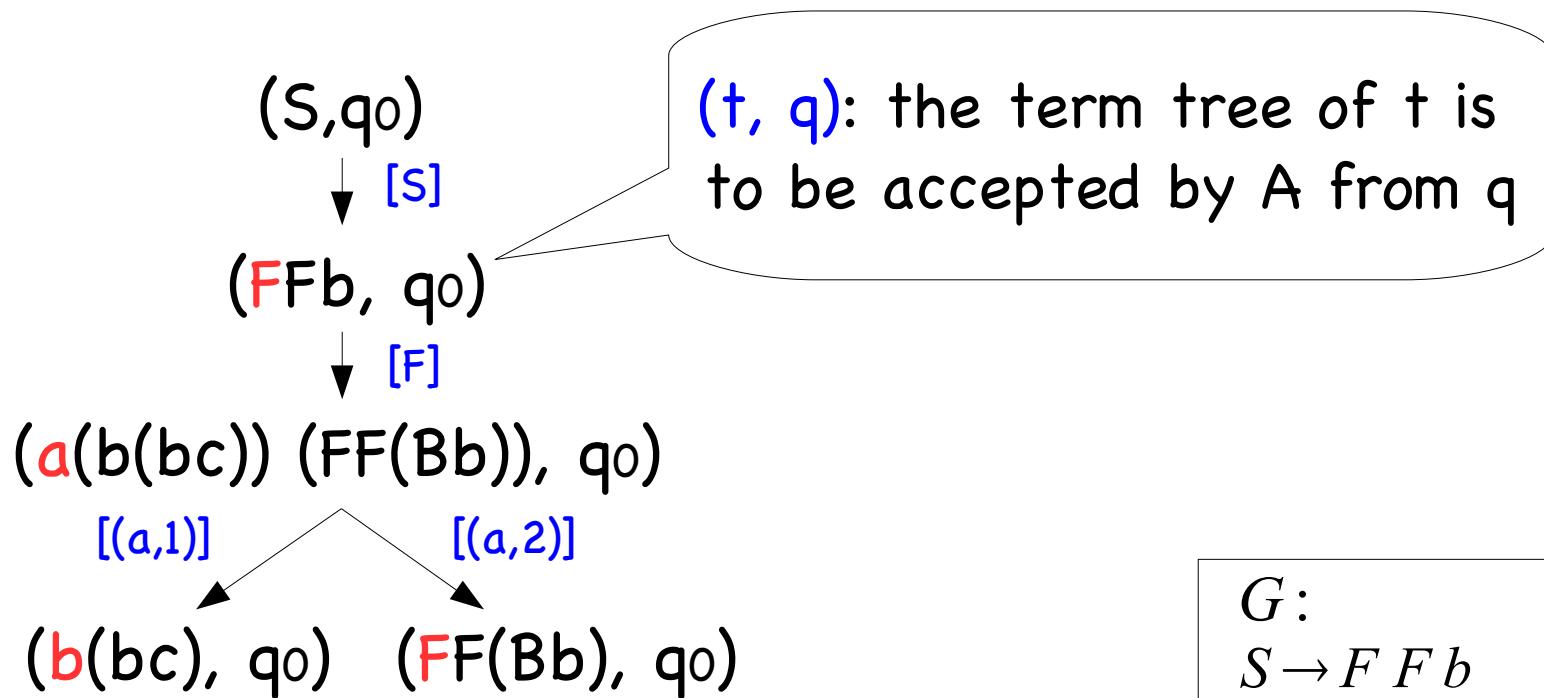
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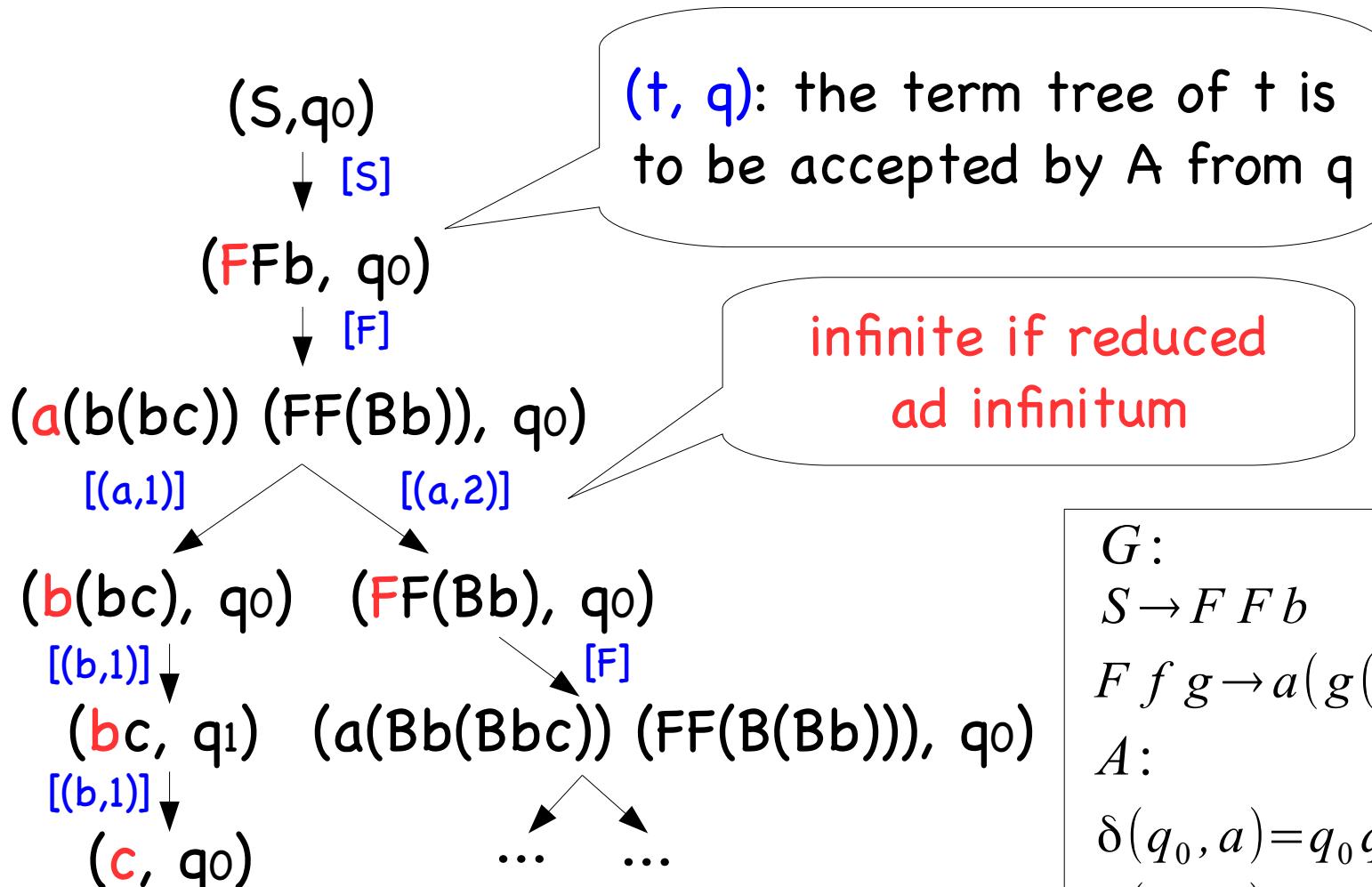
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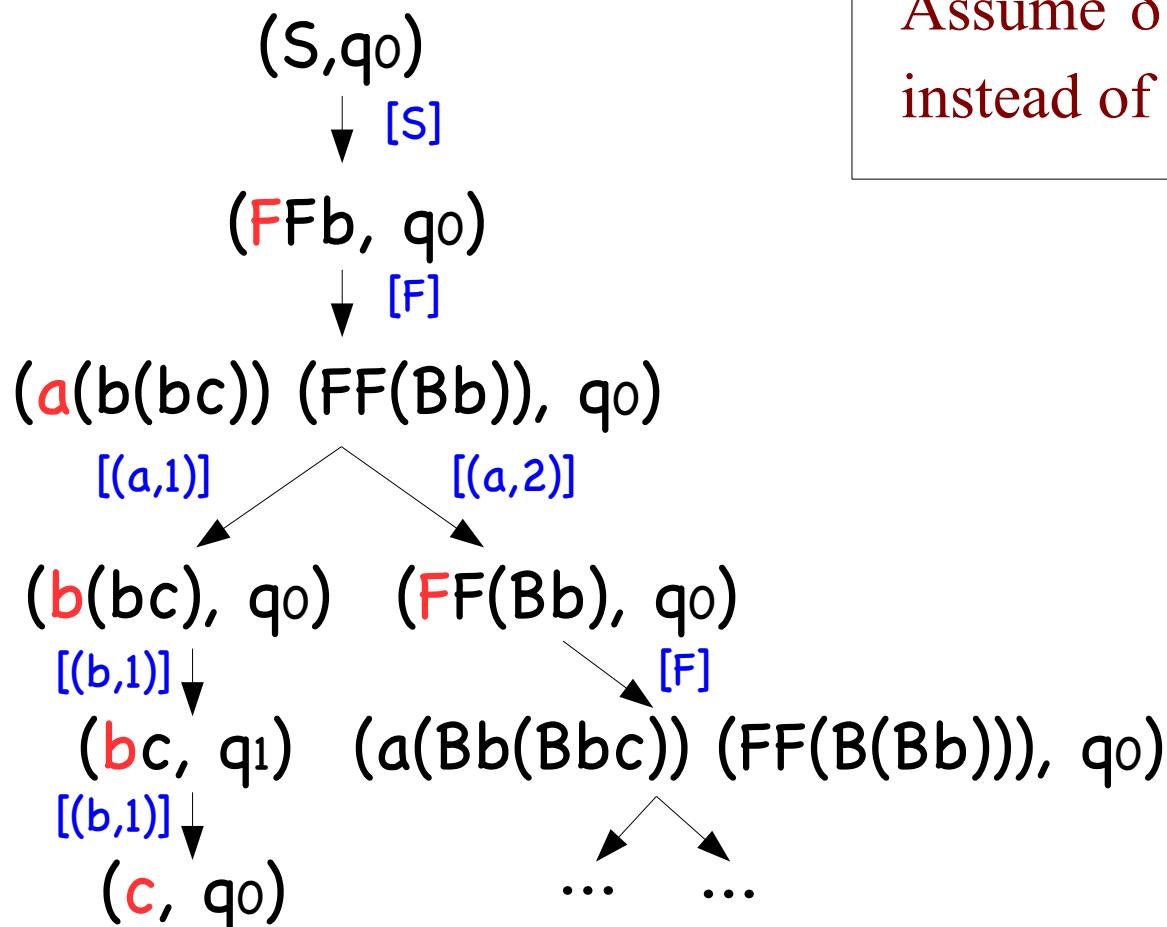
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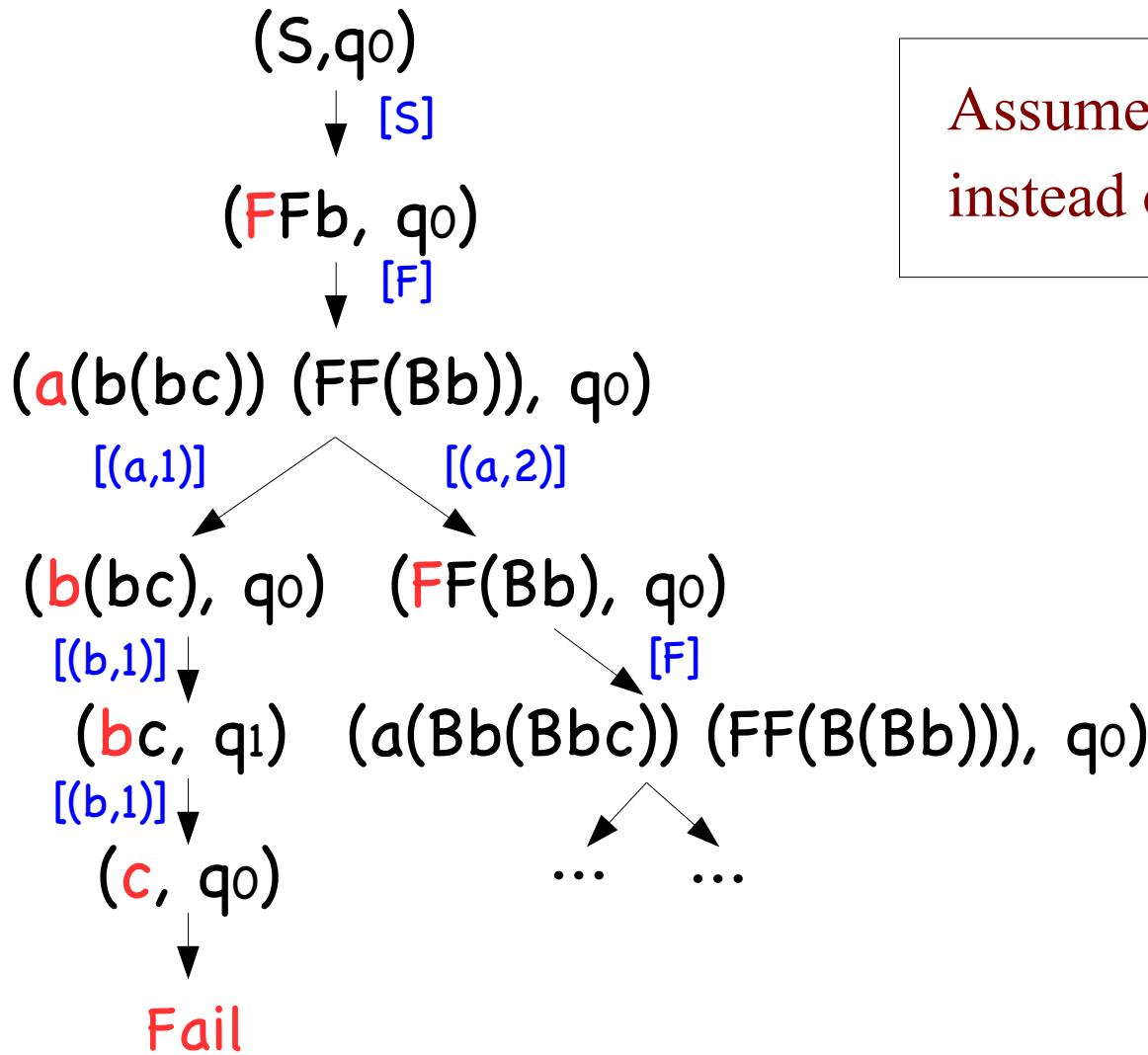


Assume $\delta(q_1, c) = \epsilon$
 instead of $\delta(q_0, c) = \epsilon$

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Restate μ HORS model checking

Given G : μ HORS

A : trivial tree automaton

(for describing safety properties)

Does configuration graph for G and A contain Fail?

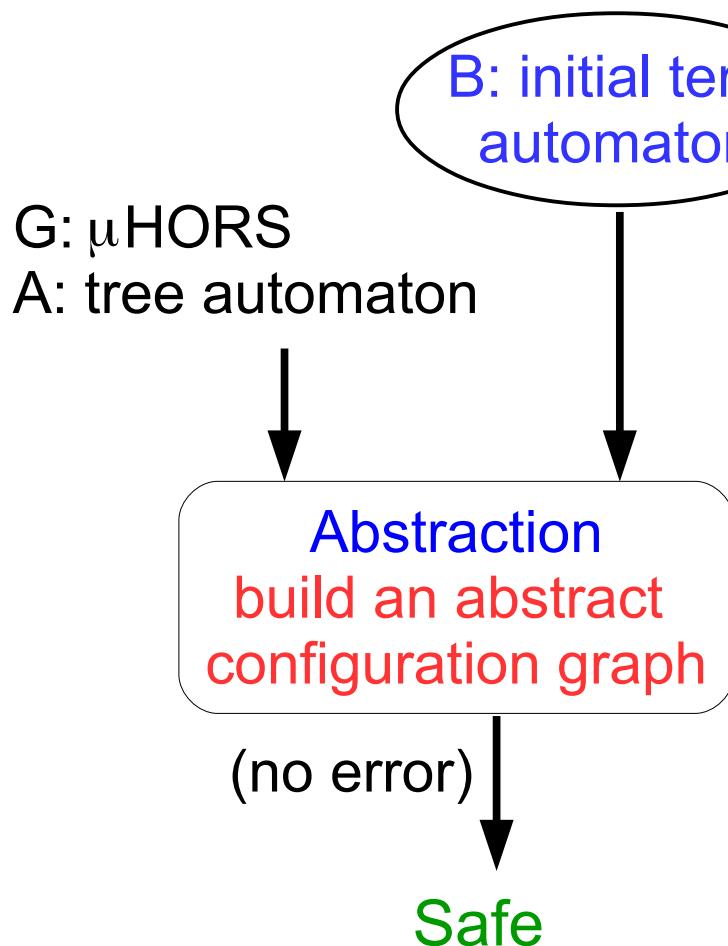
Theorem

A accepts Tree(G) \Leftrightarrow

Configuration graph for G and A does not contain Fail

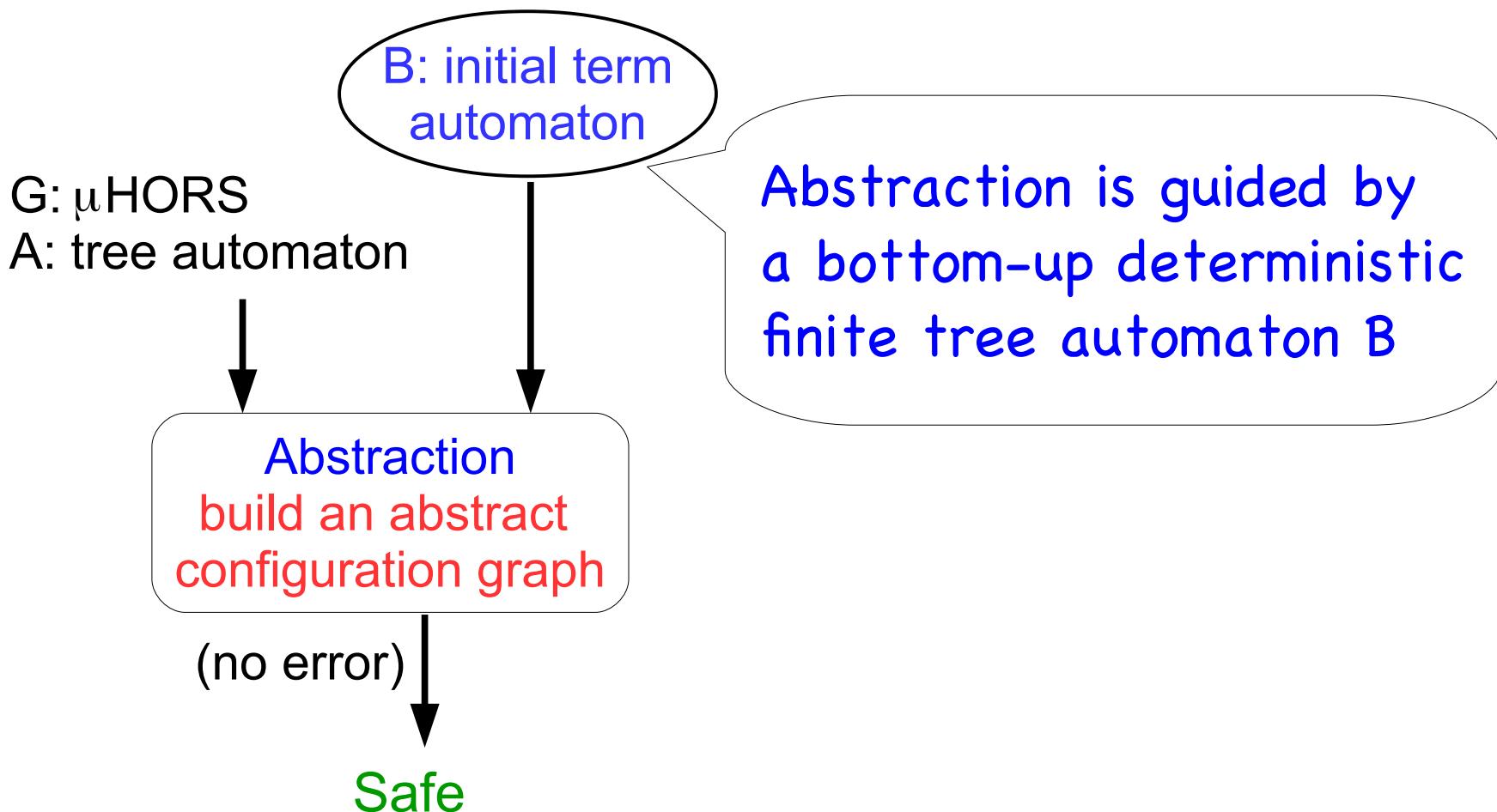
Our Approach: Overview

Construct a **finite abstract configuration graph** for approximating all reduction sequences of G and A



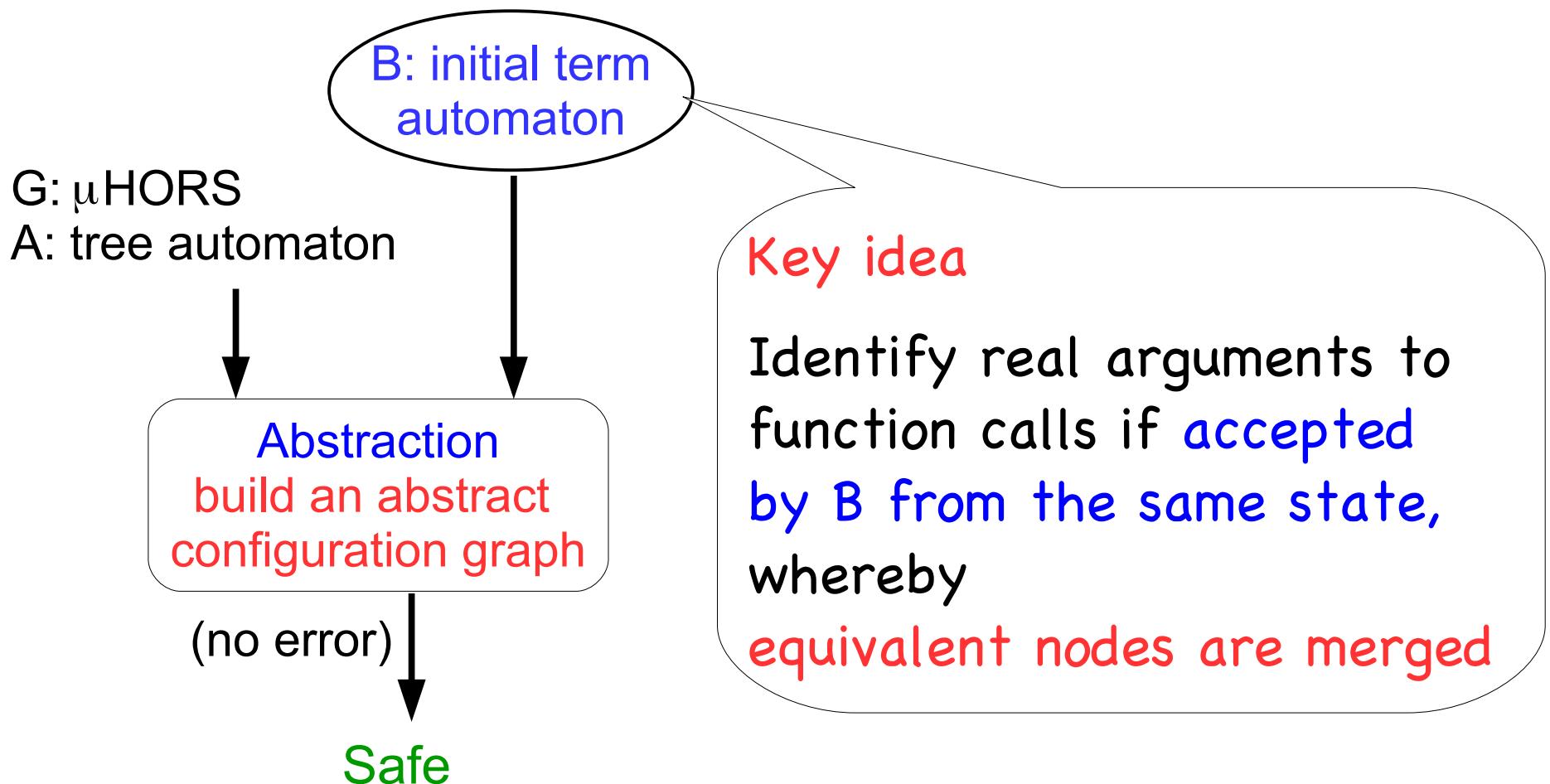
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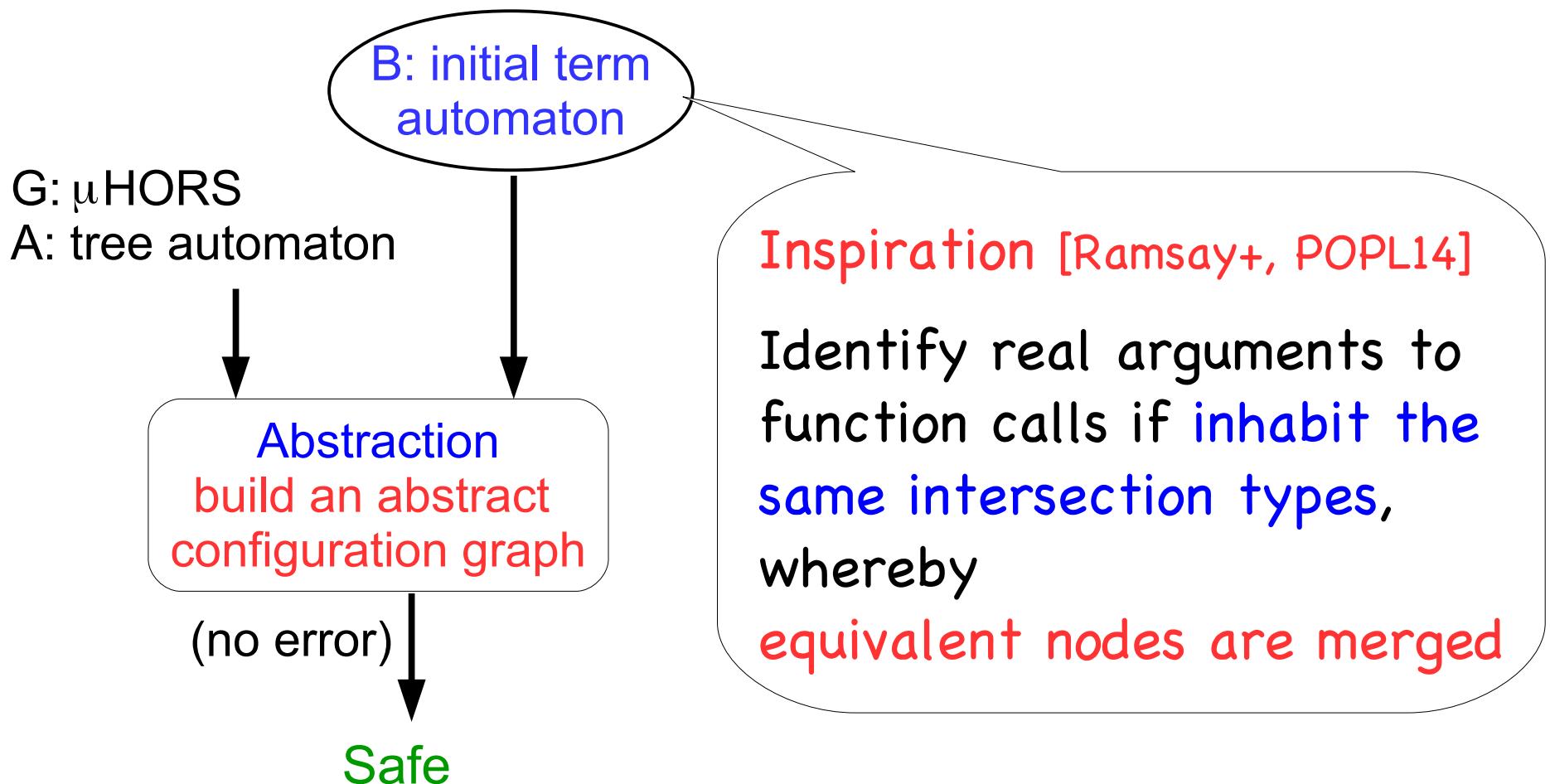
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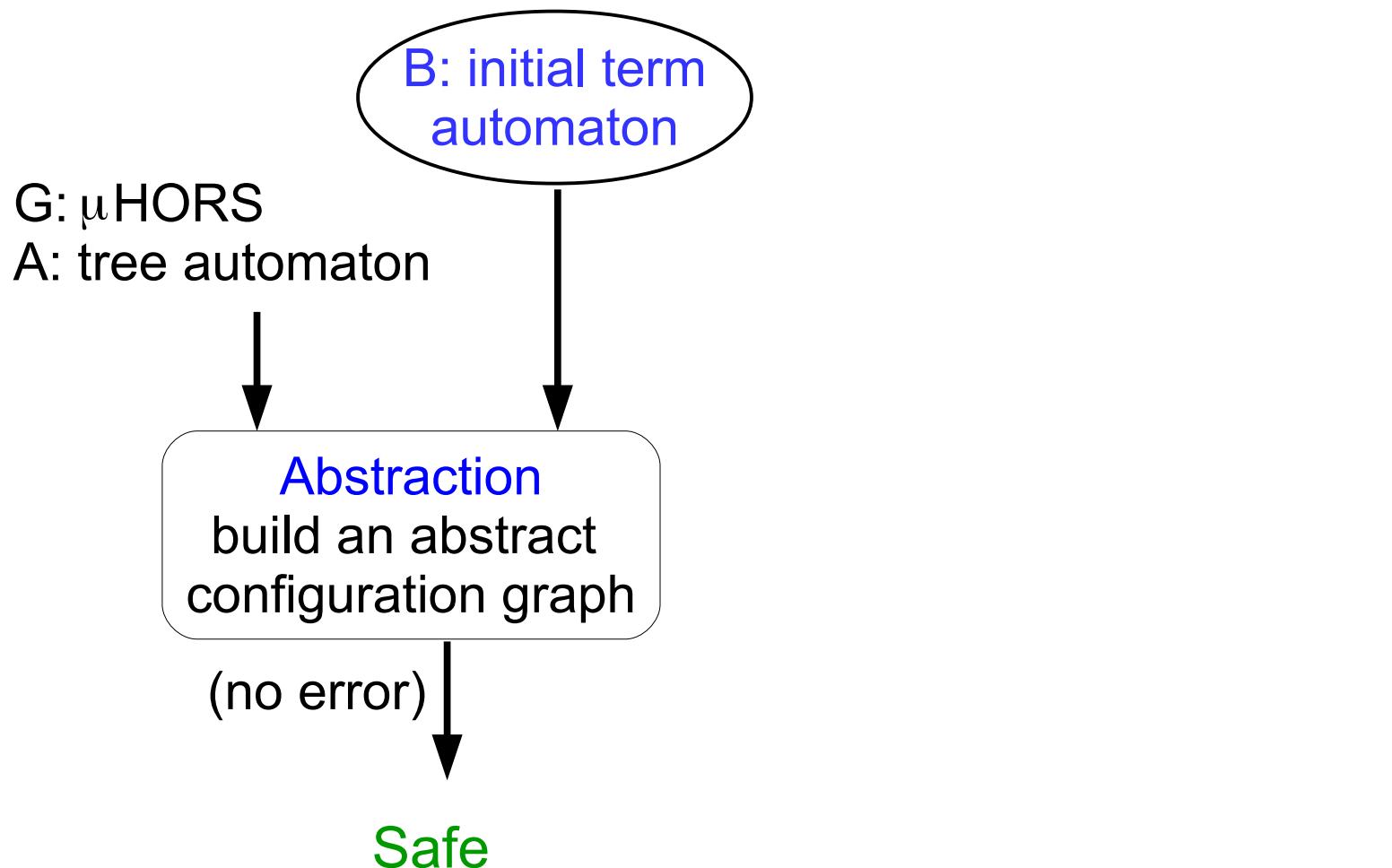


Our Approach: Overview

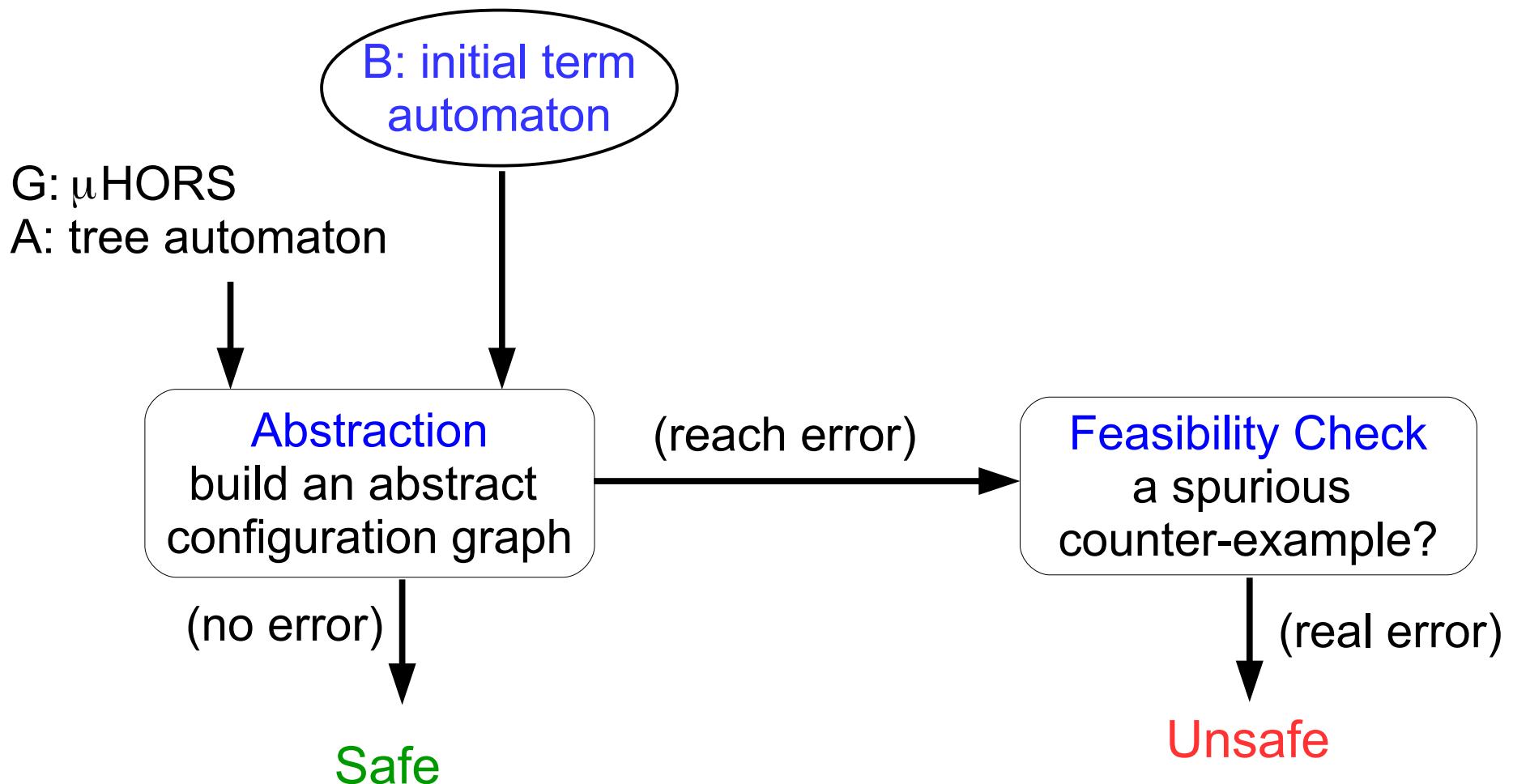
Construct a **finite abstract configuration graph** for approximating all reduction sequences of G and A



Our Approach: Overview

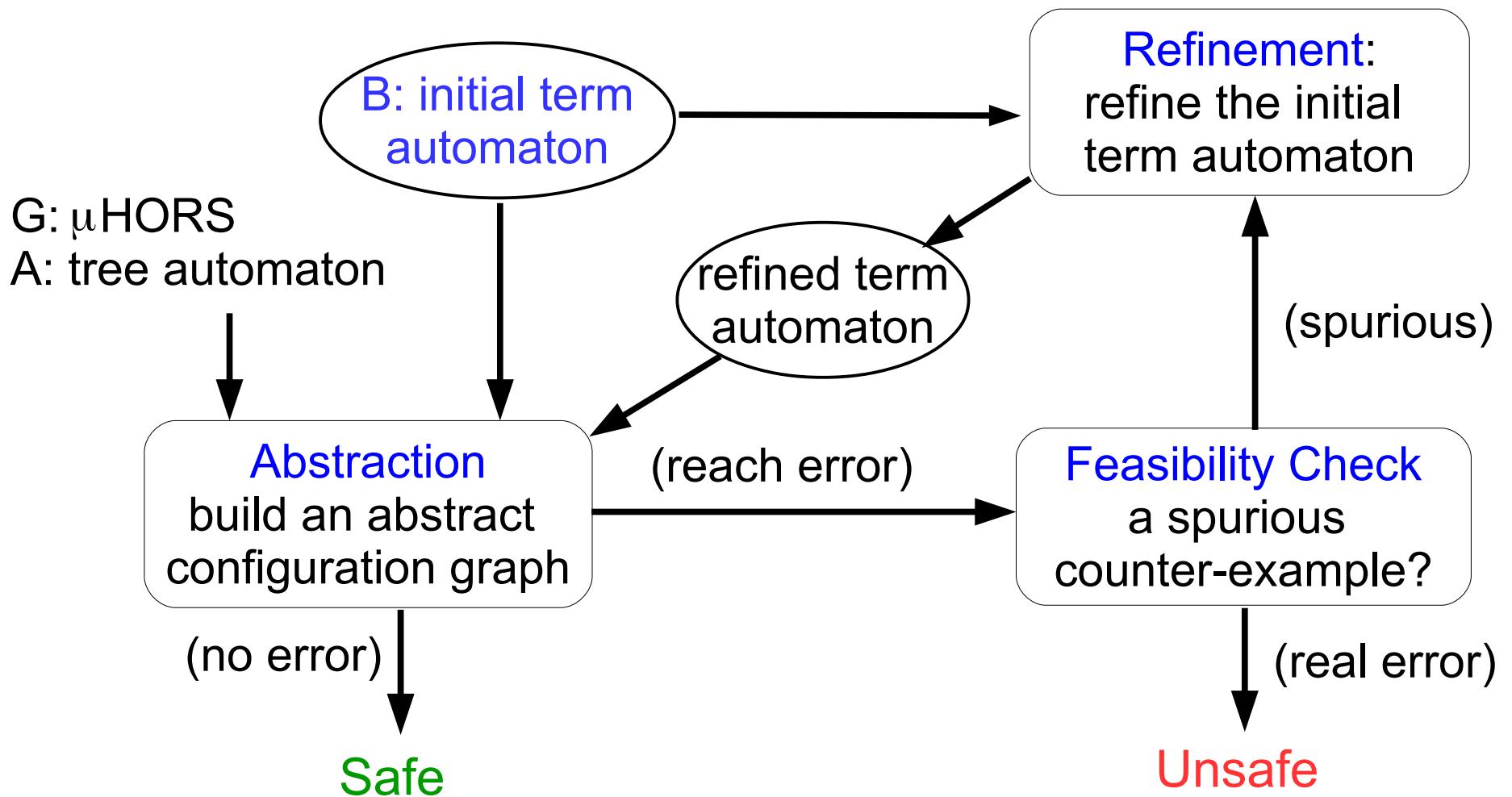


Our Approach: Overview



Our Approach: Overview

Refine abstraction by cloning states and transitions of B from which extract **a refined automaton**



Outline

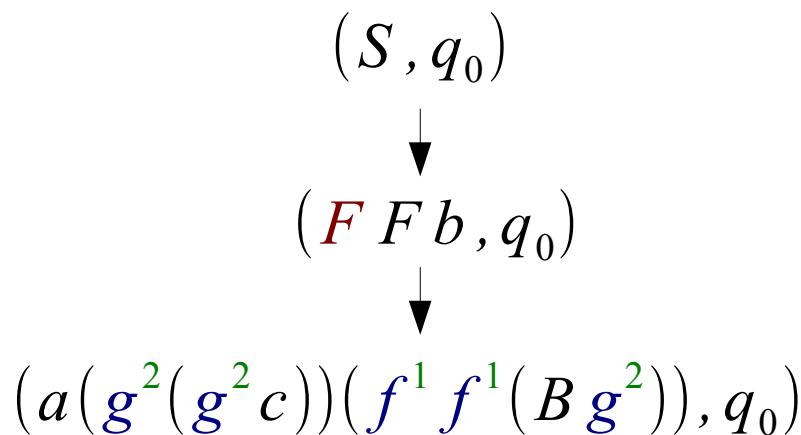
- Background
 - μ HORS model checking
 - Example: application to OO verification
- New model checking procedure for μ HORS
 - Overview and key ideas
 - Illustrating abstraction and refinement
 - Properties of the procedure
- Implementation and experiments
- Related work and conclusion

Example: Abstraction

$$\begin{array}{c} (S, q_0) \\ \downarrow \\ (\textcolor{red}{F} F b, q_0) \end{array}$$

$G:$	
$S \rightarrow F F b$	$B h x \rightarrow b(h x)$
	$F f g \rightarrow a(g(g c))(f f(B g))$
$A:$	
$\delta(q_0, a) = q_0$	$\delta(q_0, b) = q_1$
$\delta(q_1, a) = q_1$	$\delta(q_1, b) = q_0$
	$\delta(q_0, c) = \epsilon$

Example: Abstraction

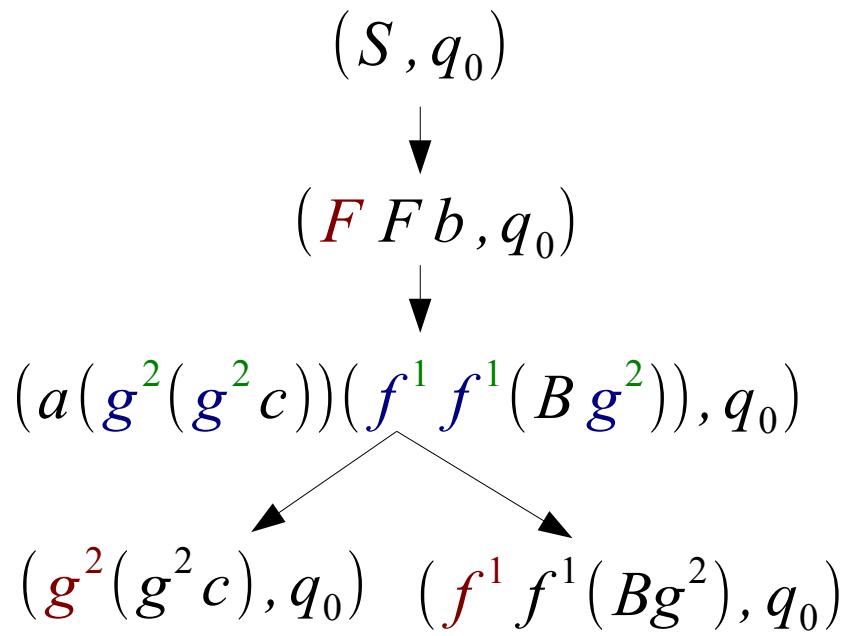


Bindings:

$$\begin{aligned} g^2 &\leftarrow b \\ f^1 &\leftarrow F \end{aligned}$$

$G:$	
$S \rightarrow F F b$	$B h x \rightarrow b(h x)$
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Example: Abstraction

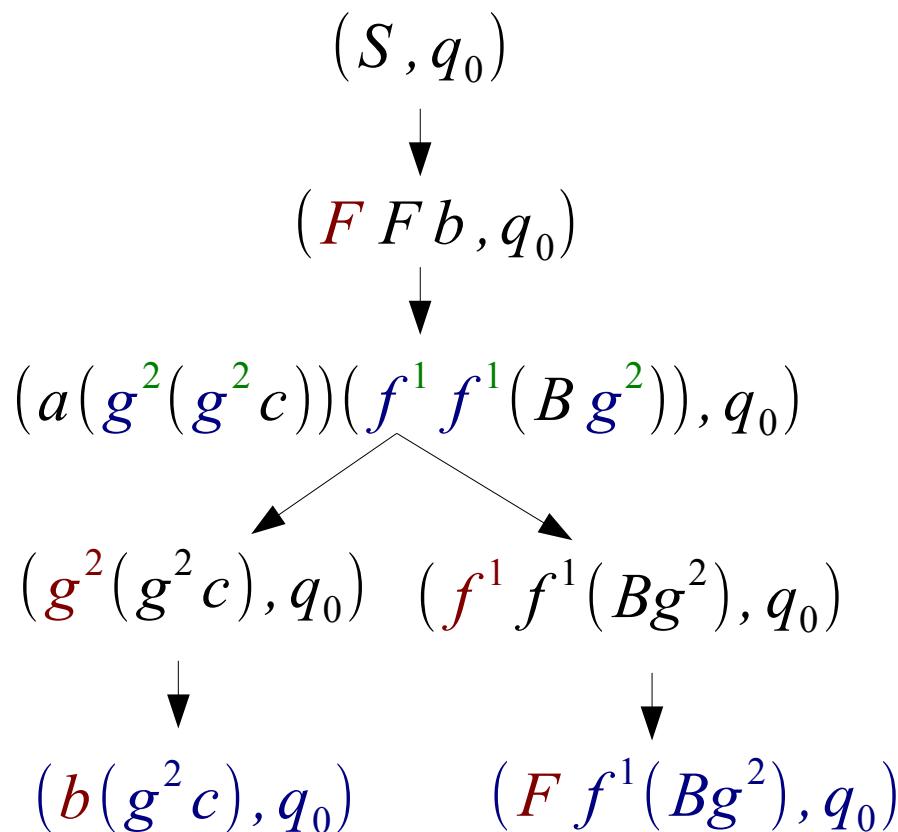


Bindings:

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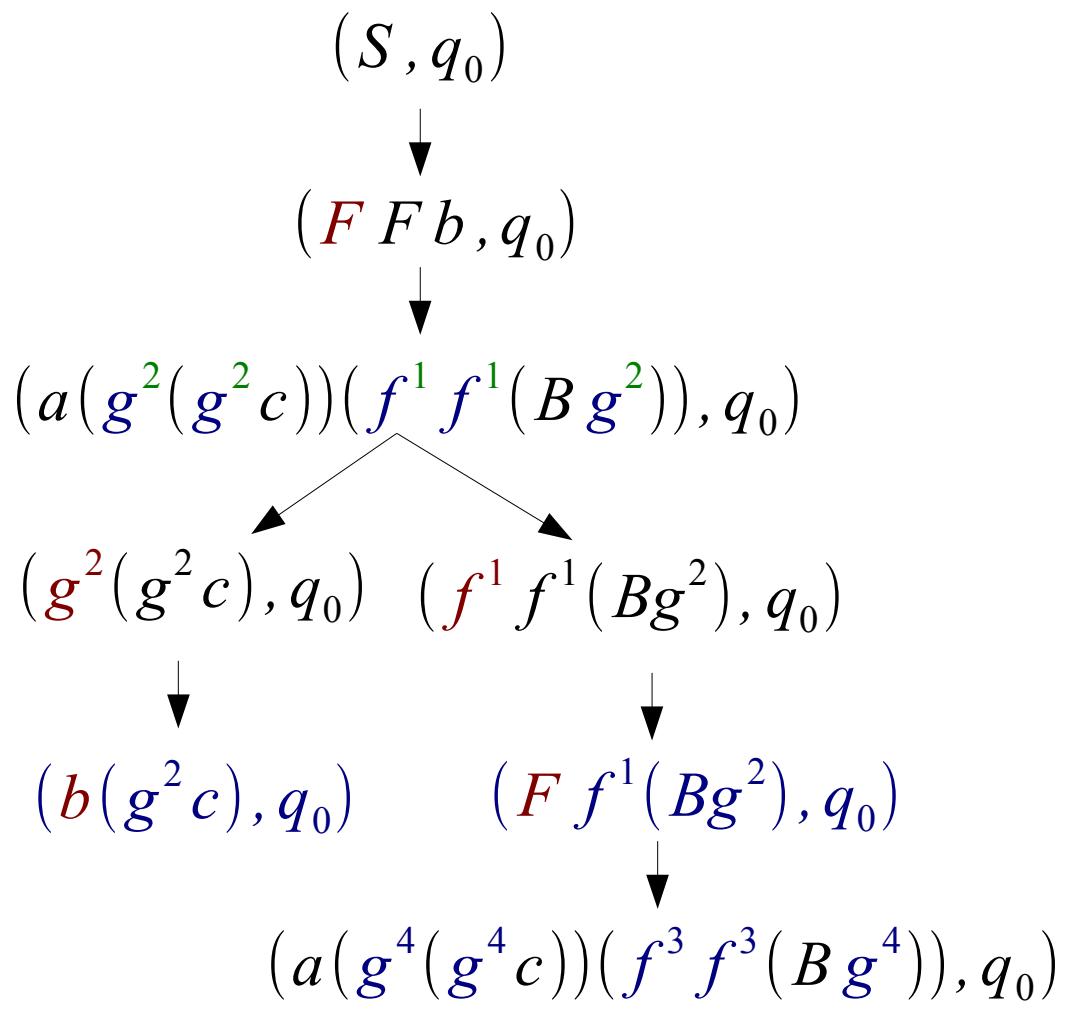


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	$\delta(q_0, c) = \epsilon$	

Example: Abstraction



Bindings:

$$\begin{aligned} g^2 &\leftarrow b \\ f^1 &\leftarrow F \\ f^3 &\leftarrow F \\ g^4 &\leftarrow B g^2 \end{aligned}$$

$G:$

$$S \rightarrow F F b \qquad B h x \rightarrow b(h x)$$

$$F f g \rightarrow a(g(g c))(f f(B g))$$

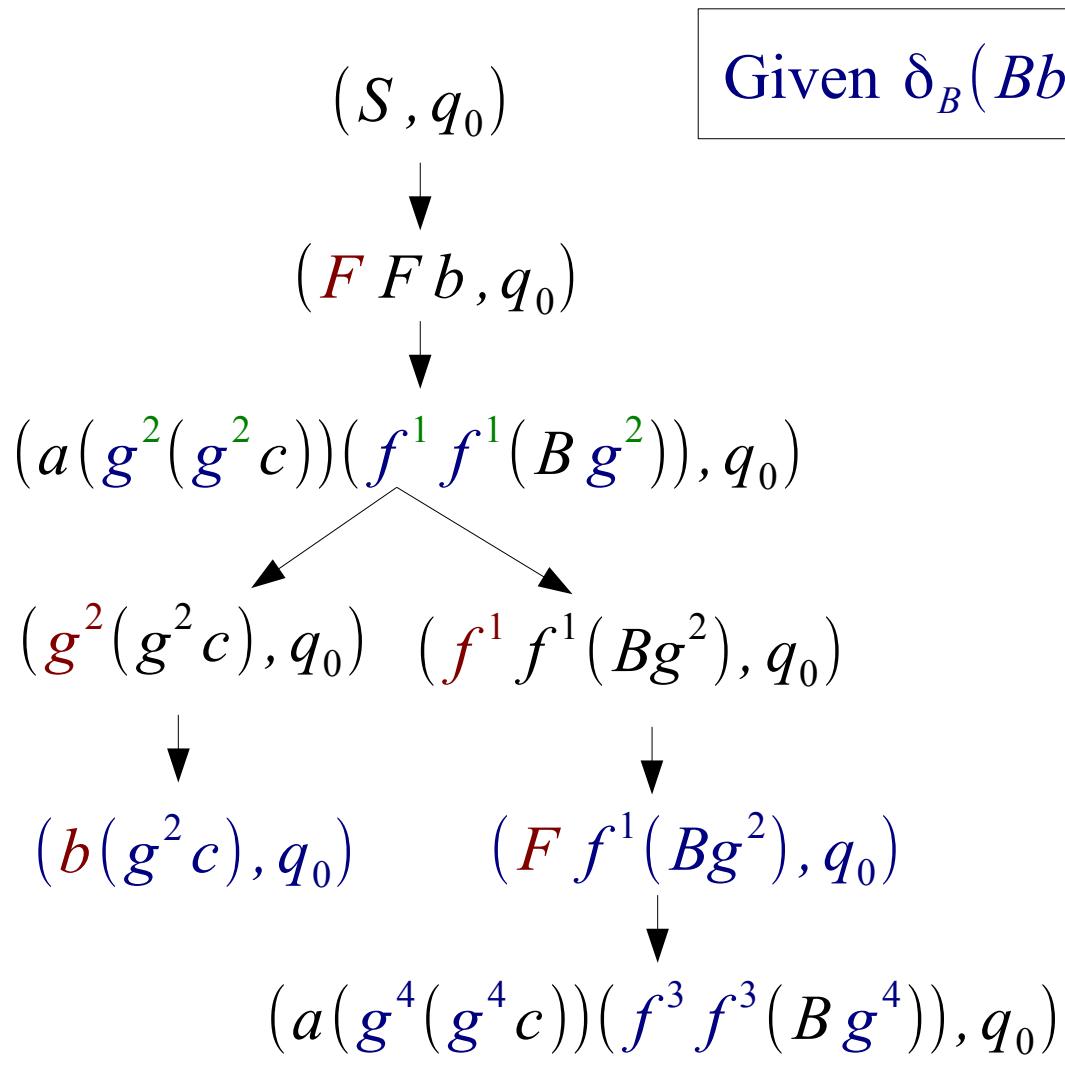
$A:$

$$\delta(q_0, a) = q_0 q_0 \qquad \delta(q_0, b) = q_1$$

$$\delta(q_1, a) = q_1 q_1 \qquad \delta(q_1, b) = q_0$$

$$\delta(q_0, c) = \epsilon$$

Example: Abstraction



Bindings:

$$\begin{aligned} g^2 &\leftarrow b \\ f^1 &\leftarrow F \\ f^3 &\leftarrow F \\ g^4 &\leftarrow Bg^2 \end{aligned}$$

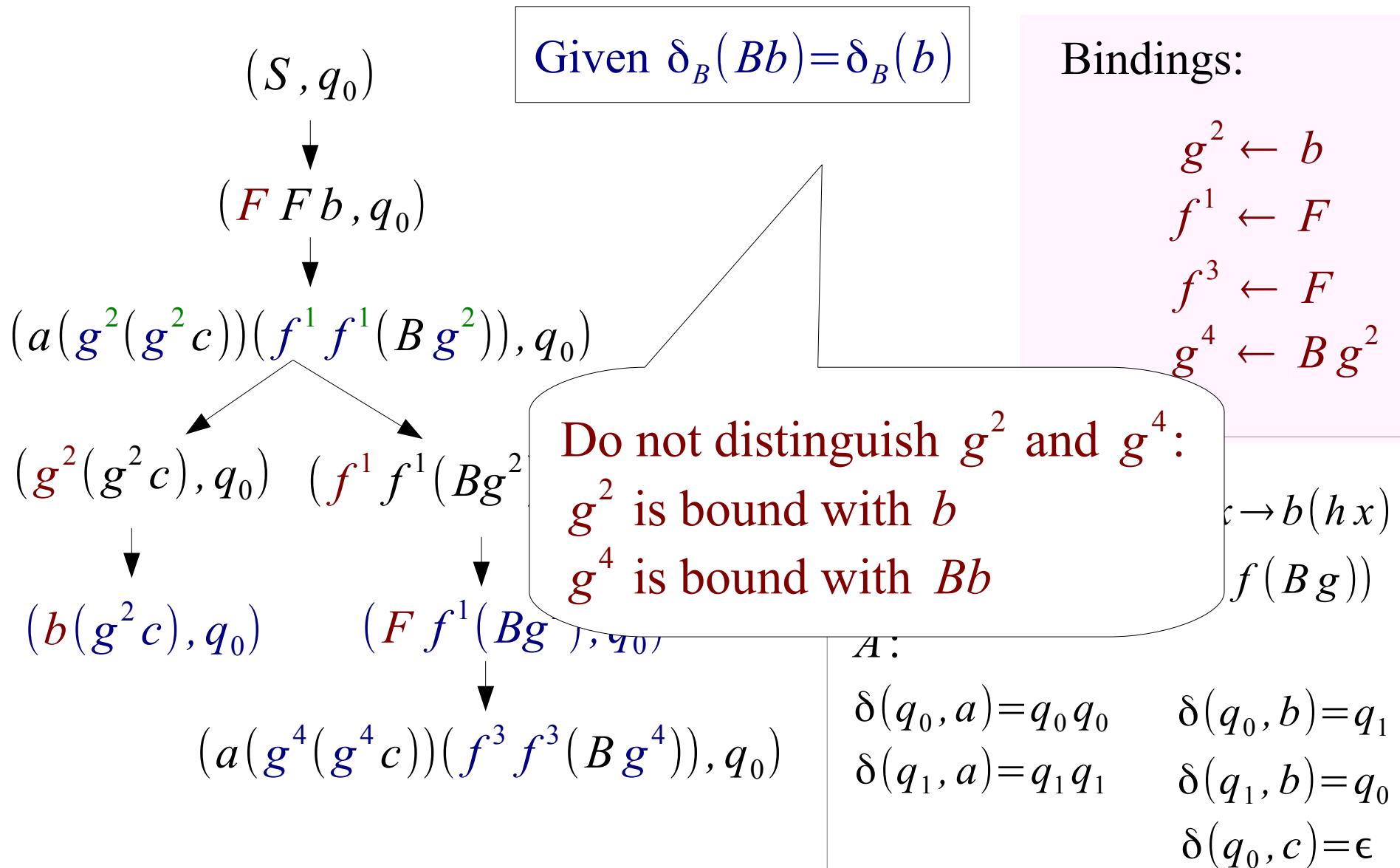
$G:$

$S \rightarrow FFb$	$Bhx \rightarrow b(hx)$
$Ffg \rightarrow a(g(gc))(ff(Bg))$	

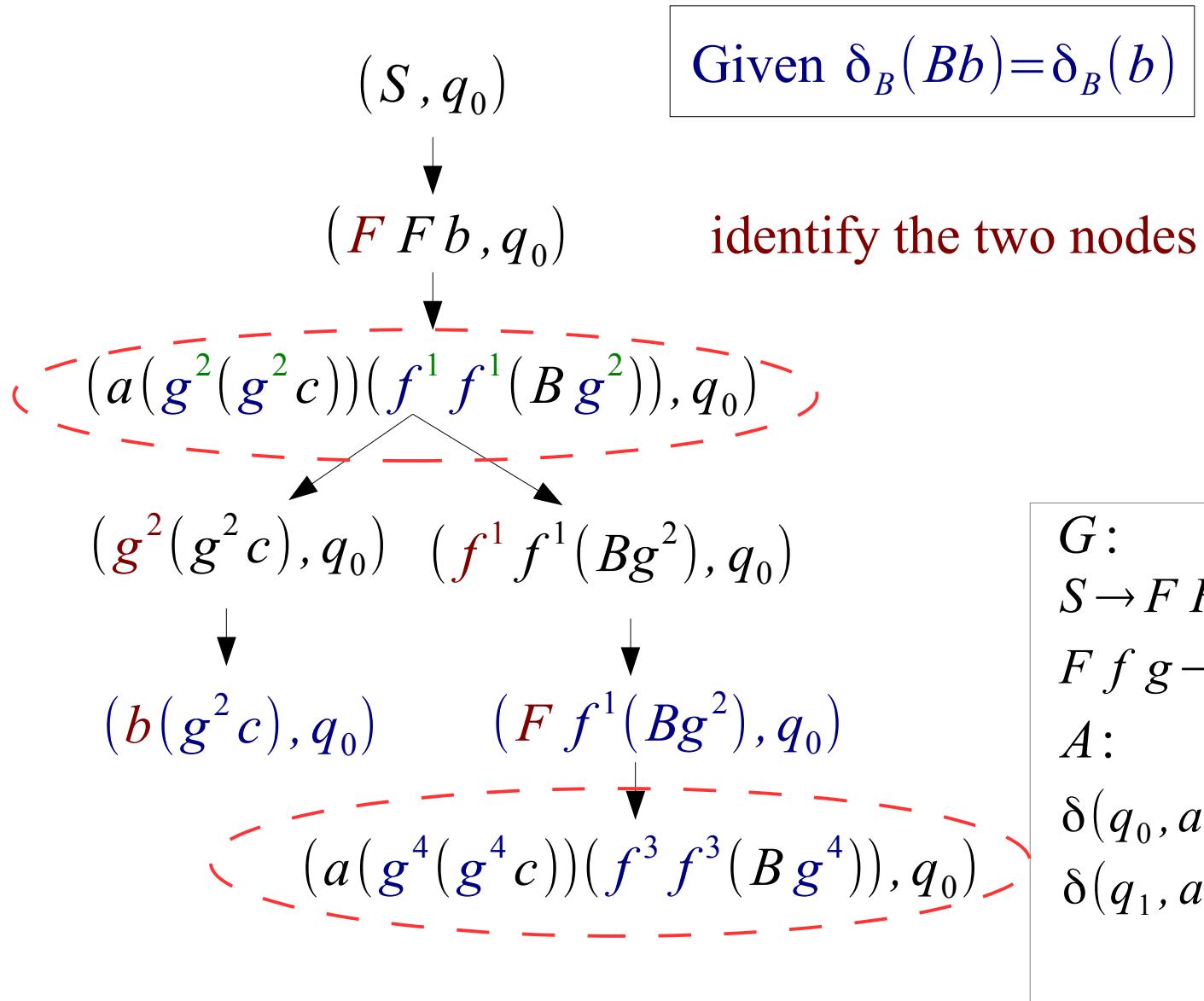
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Example: Abstraction



Example: Abstraction



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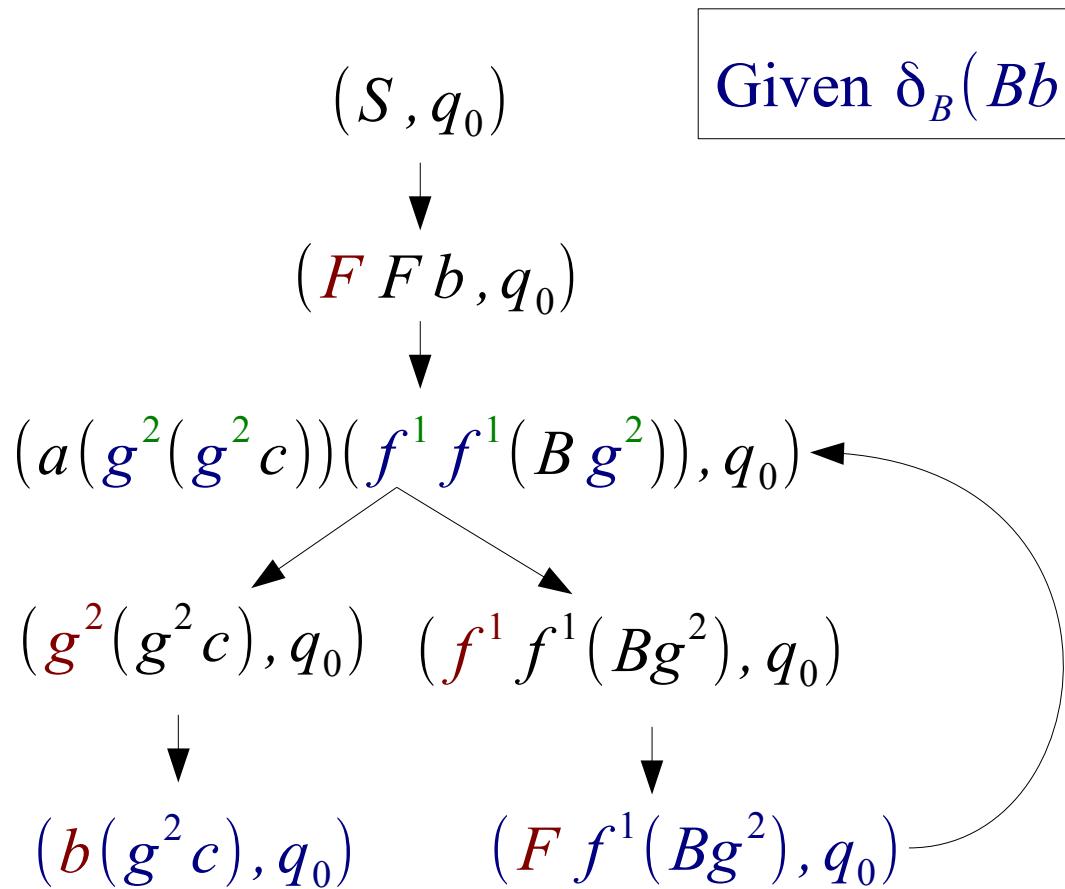
$G:$

$$\begin{array}{ll} S \rightarrow F F b & B h x \rightarrow b(h x) \\ F f g \rightarrow a(g(g c))(f f(B g)) & \end{array}$$

$A:$

$$\begin{array}{ll} \delta(q_0, a) = q_0 q_0 & \delta(q_0, b) = q_1 \\ \delta(q_1, a) = q_1 q_1 & \delta(q_1, b) = q_0 \\ \delta(q_0, c) = \epsilon & \end{array}$$

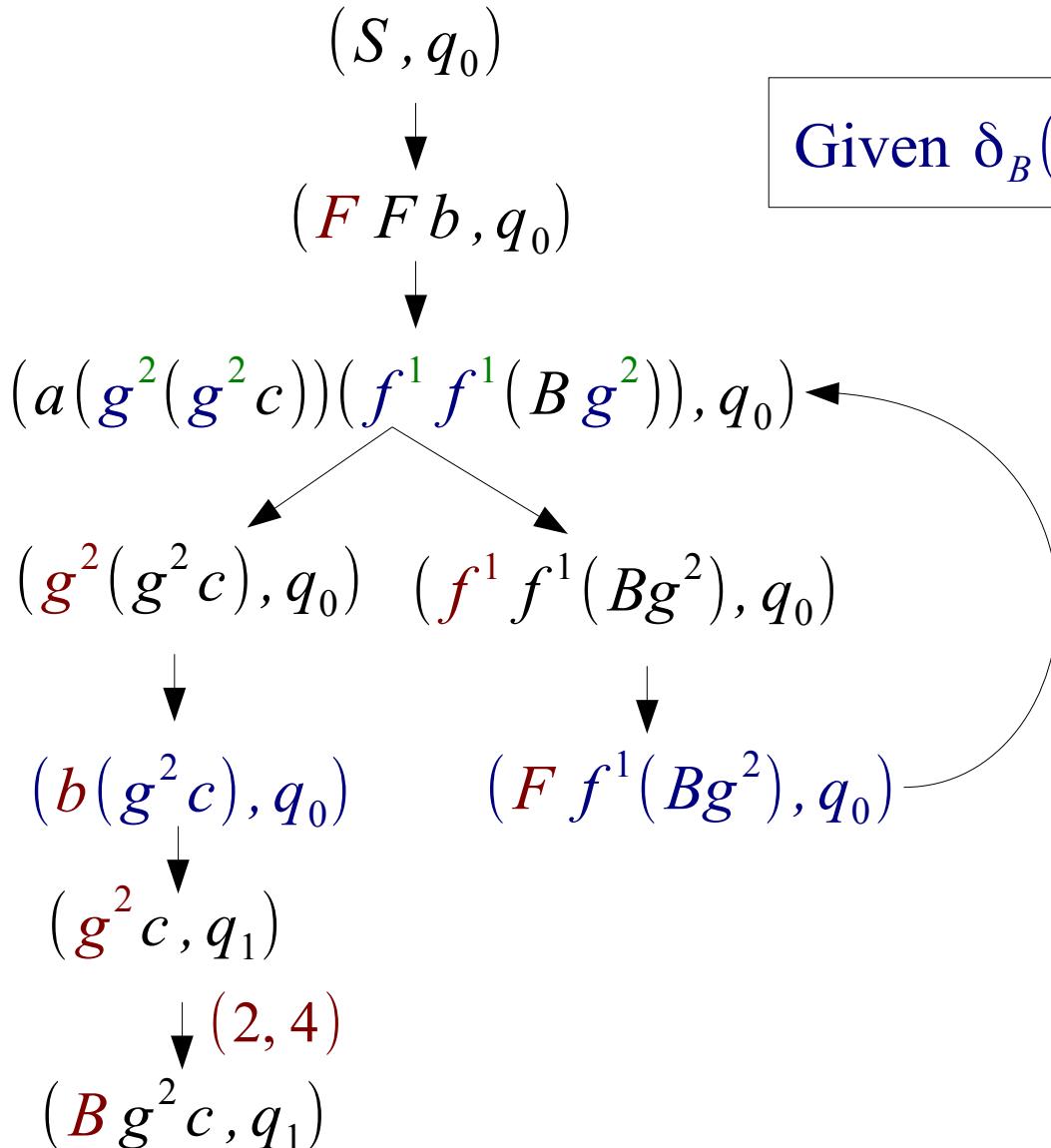
Example: Abstraction



Bindings:

$$\begin{aligned}
 g^2 &\leftarrow b \\
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 f^3 &\leftarrow F \\
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 \end{aligned}$$

Example: Abstraction



Bindings:

$$\begin{aligned}
 g^2 &\leftarrow b \\
 f^1 &\leftarrow F \\
 f^3 &\leftarrow F \\
 g^4 &\leftarrow B g^2 \\
 h^5 &\leftarrow g^2 \\
 x^6 &\leftarrow c
 \end{aligned}$$

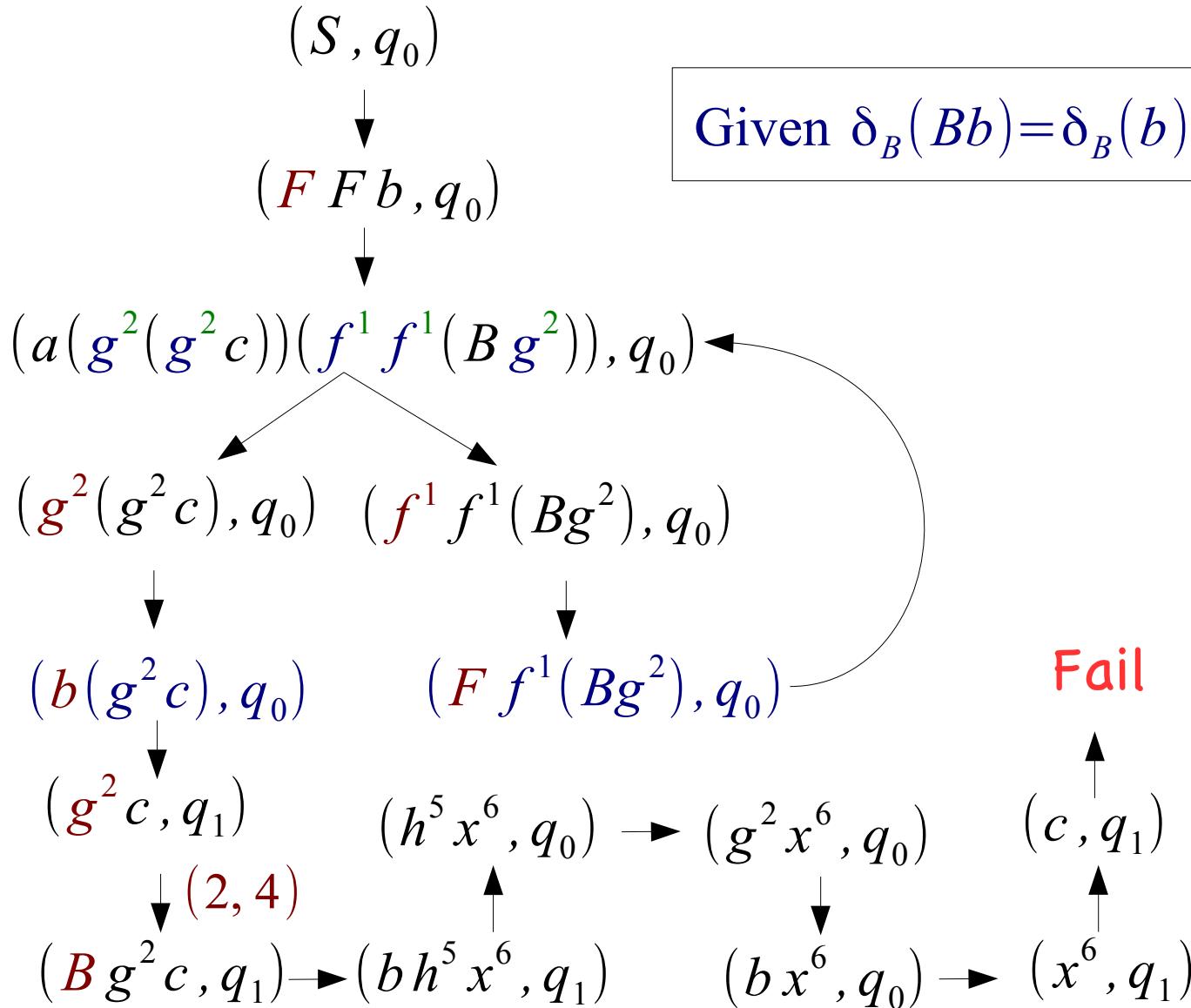
$G:$

$S \rightarrow F F b$	$B h x \rightarrow b(h x)$
$F f g \rightarrow a(g(g c))(f f(B g))$	

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Example: Abstraction



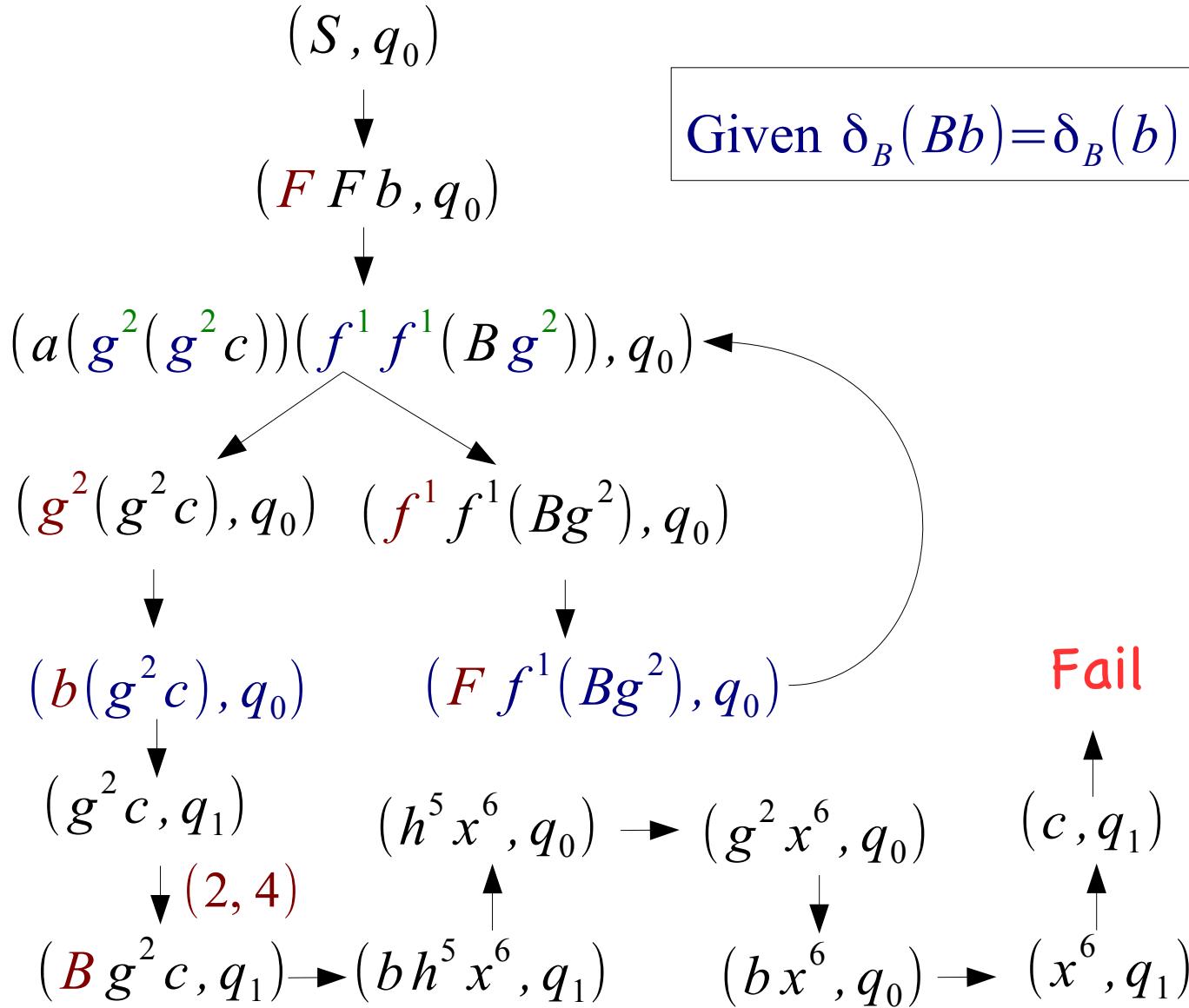
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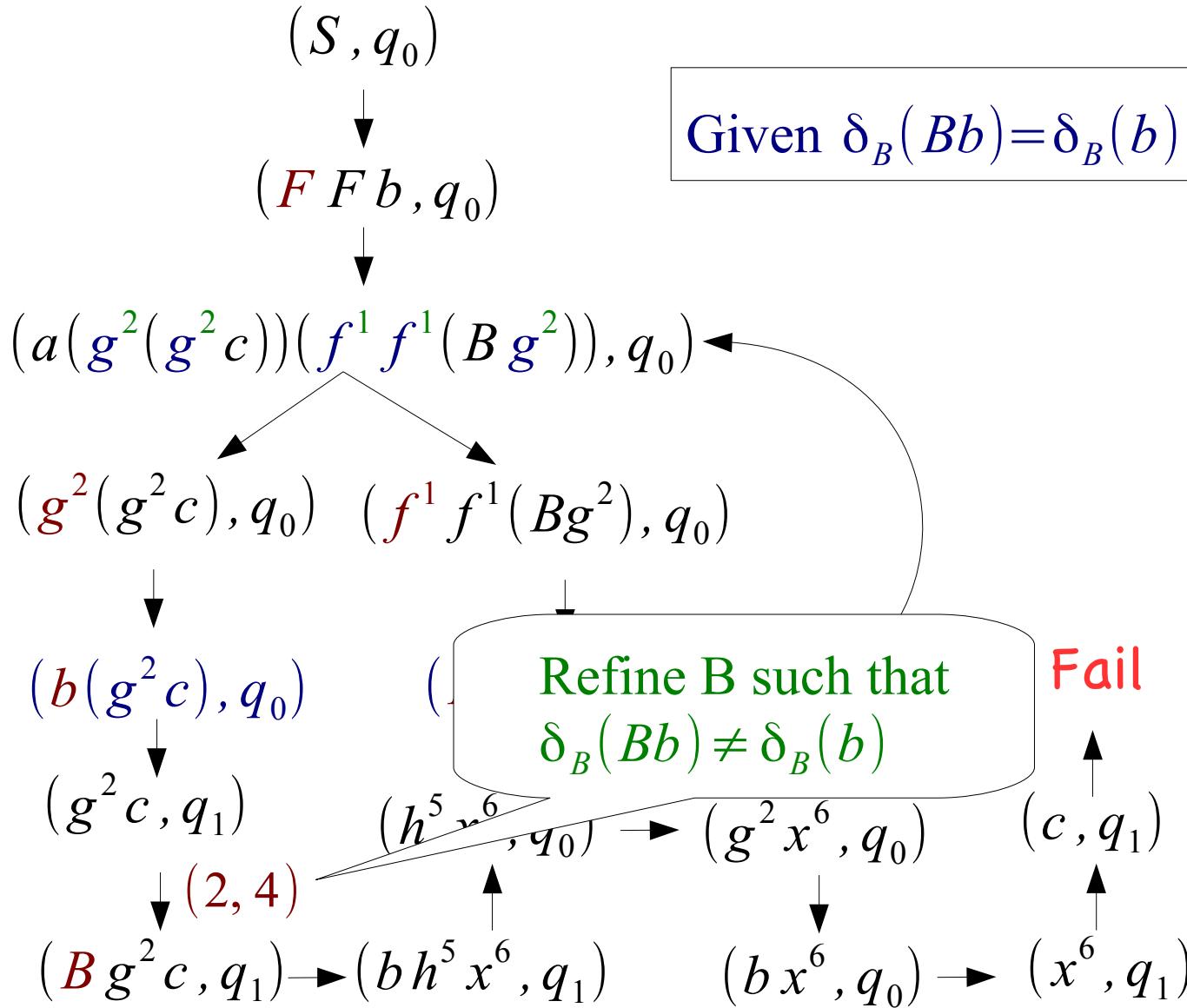
$A:$

$$\begin{aligned}
 \delta(q_0, a) &= q_0 q_0 \\
 \delta(q_1, a) &= q_1 q_1 \\
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 \delta(q_1, b) &= q_0 \\
 \delta(q_0, c) &= \epsilon
 \end{aligned}$$

How to Eliminate Counterexample



How to Eliminate Counterexample



Bindings:

$g^2 \leftarrow b$
 $f^1 \leftarrow F$
 $f^3 \leftarrow F$
 $g^4 \leftarrow Bg^2$
 $h^5 \leftarrow g^2$
 $x^6 \leftarrow c$

How to Refine Abstraction

1. Cloning (k -copies) states and transitions of B
2. Extract a refined B' satisfying the constraint
3. If failed, increase k to $k+1$ and go to Step 1

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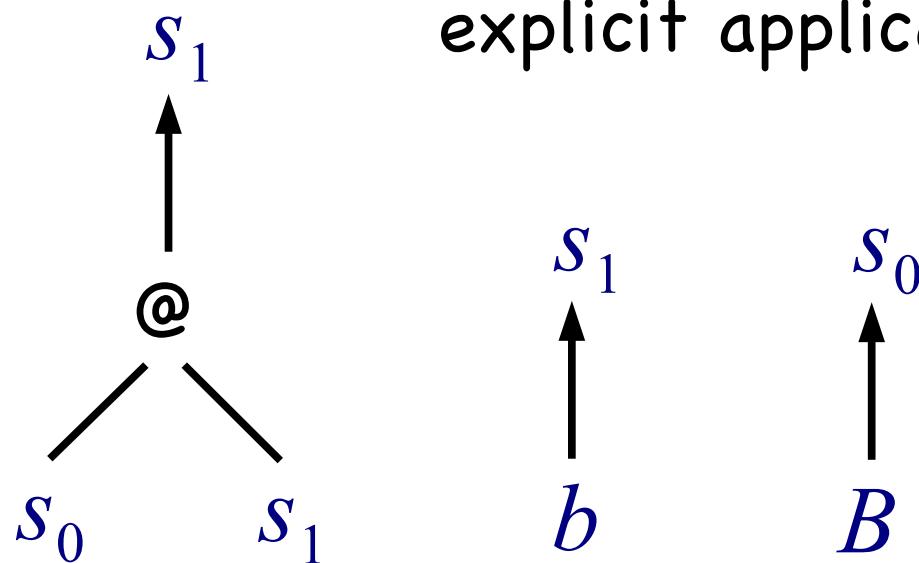
Reduced to SMT Solving for formulas
of uninterpreted functions

(not really do cloning, it's daunting...)

Example: Abstraction Refinement

```
@ s0 s1 →B s1 b →B s1 B →B s0
```

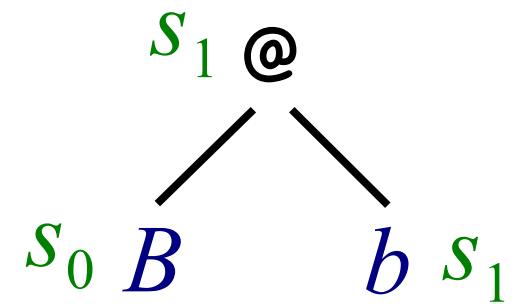
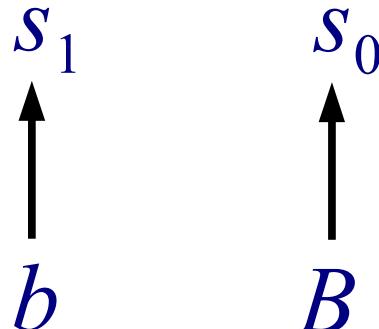
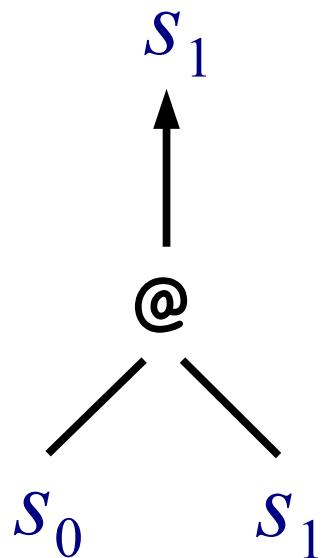
term trees are represented using an explicit application symbol “@”



Example: Abstraction Refinement

```
@ s0 s1 →B s1 b →B s1 B →B s0
```

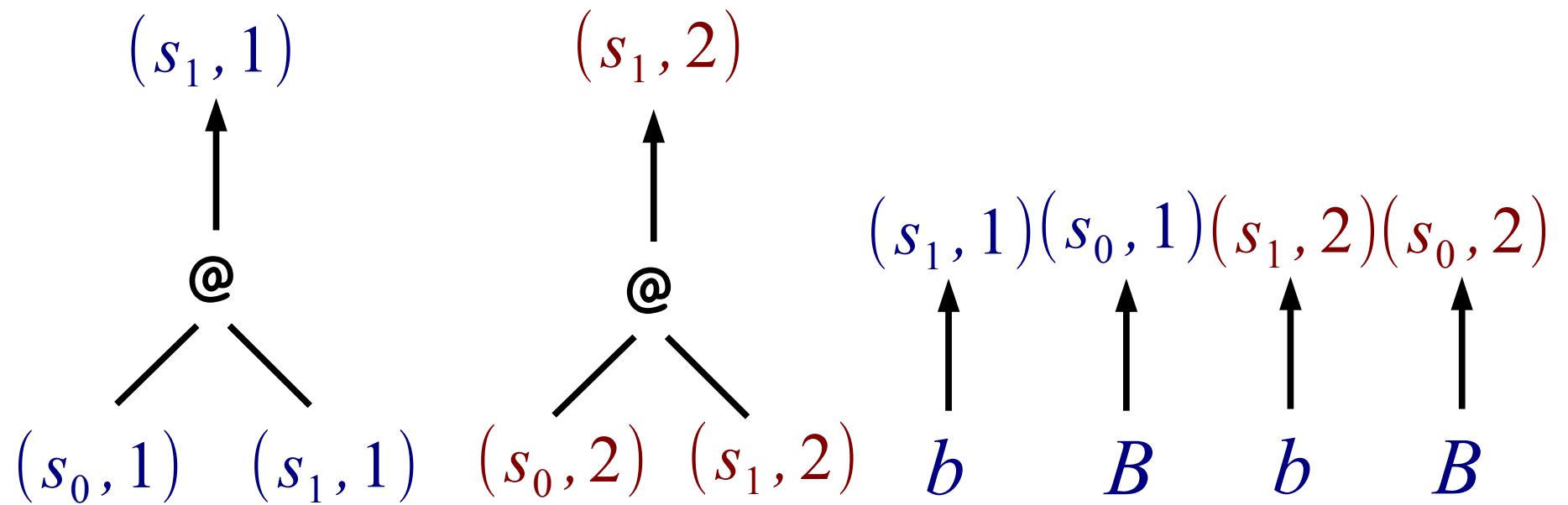
“Bb” is as “@Bb”



$$\delta_B(@Bb) = s_1$$

Example: Abstraction Refinement

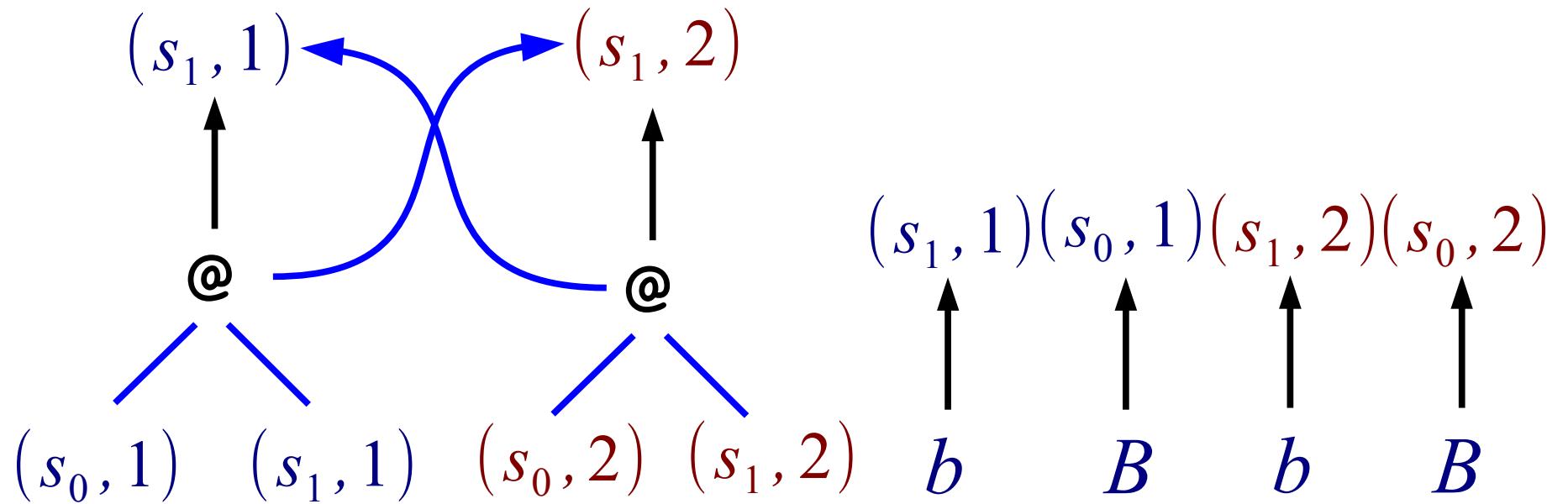
```
@ s0 s1 →B s1 b →B s1 B →B s0
```



Cloning (2-copies) states and transitions of B

Example: Abstraction Refinement

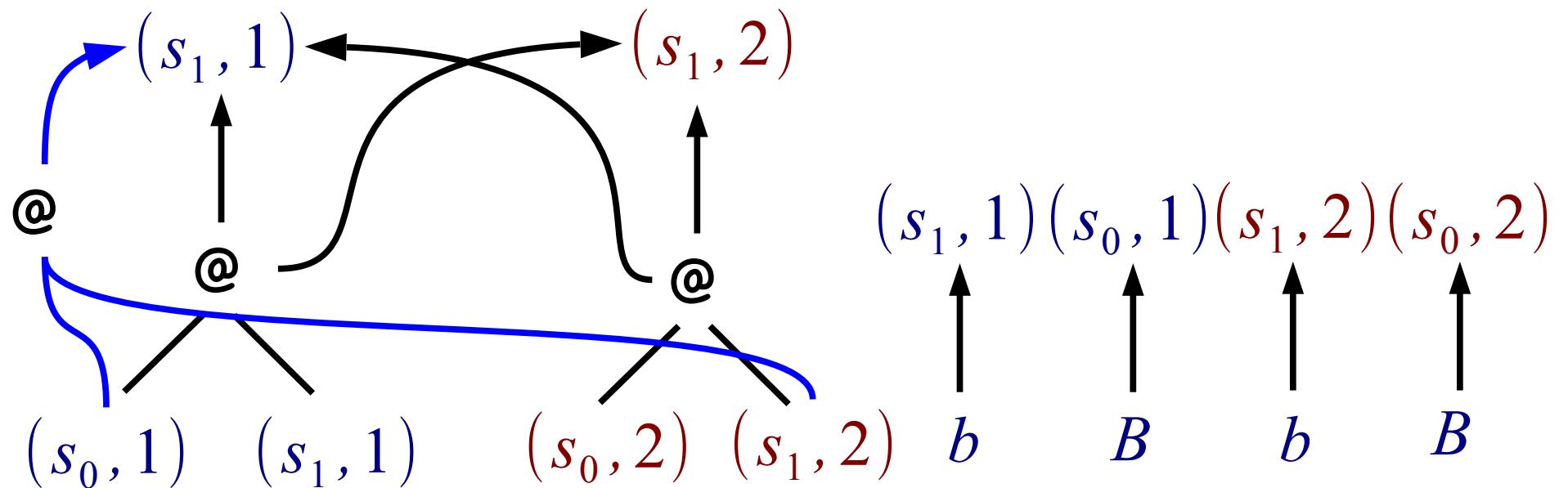
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```



Cloning (2-copies) states and transitions of B

Example: Abstraction Refinement

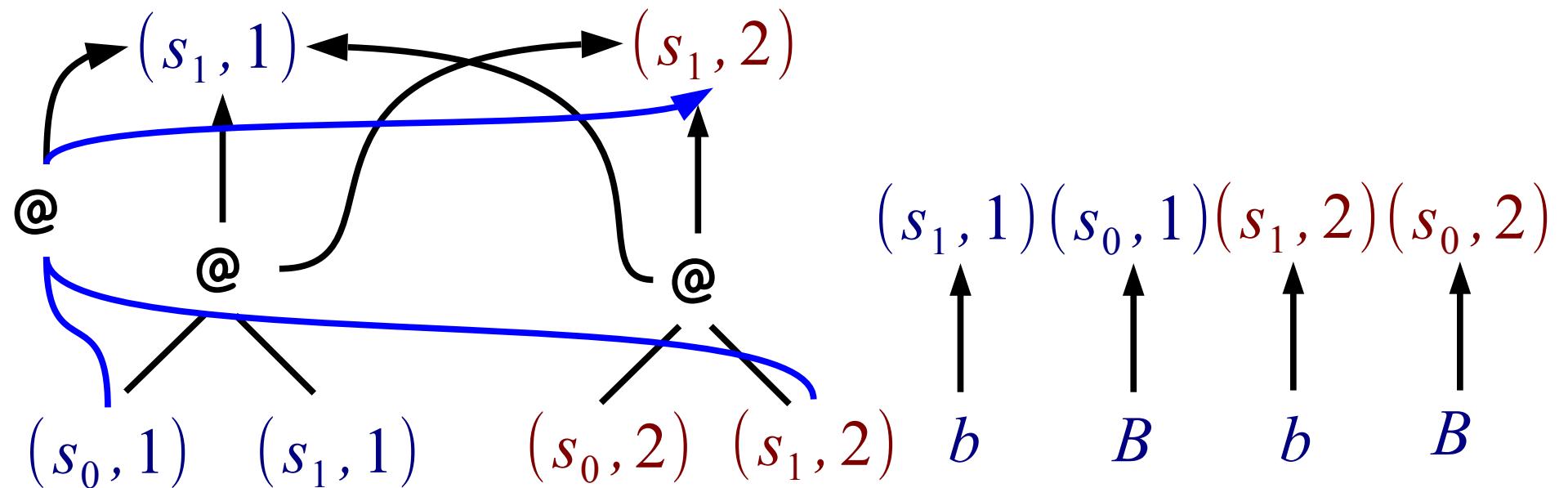
```
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```



Cloning (2-copies) states and transitions of B

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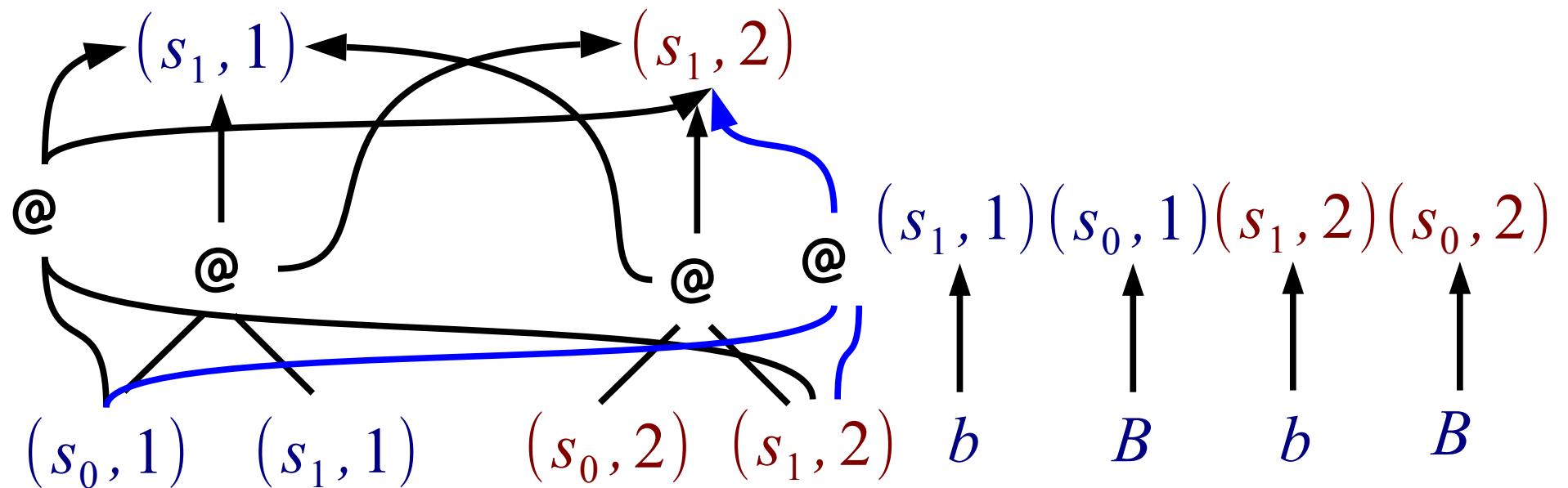
```
@ s0 s1 →B s1 b →B s1 B →B s0
```



Cloning (2-copies) states and transitions of B

Example: Abstraction Refinement

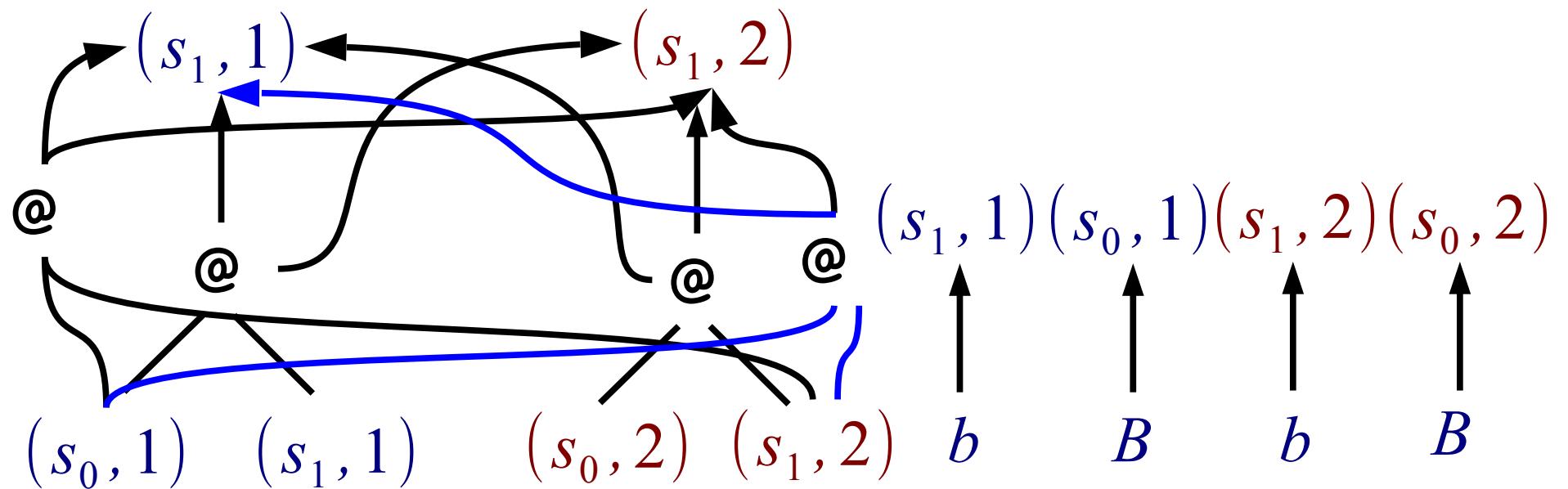
```
@ s0 s1 →B s1   b →B s1   B →B s0
```



Cloning (2-copies) states and transitions of B

Example: Abstraction Refinement

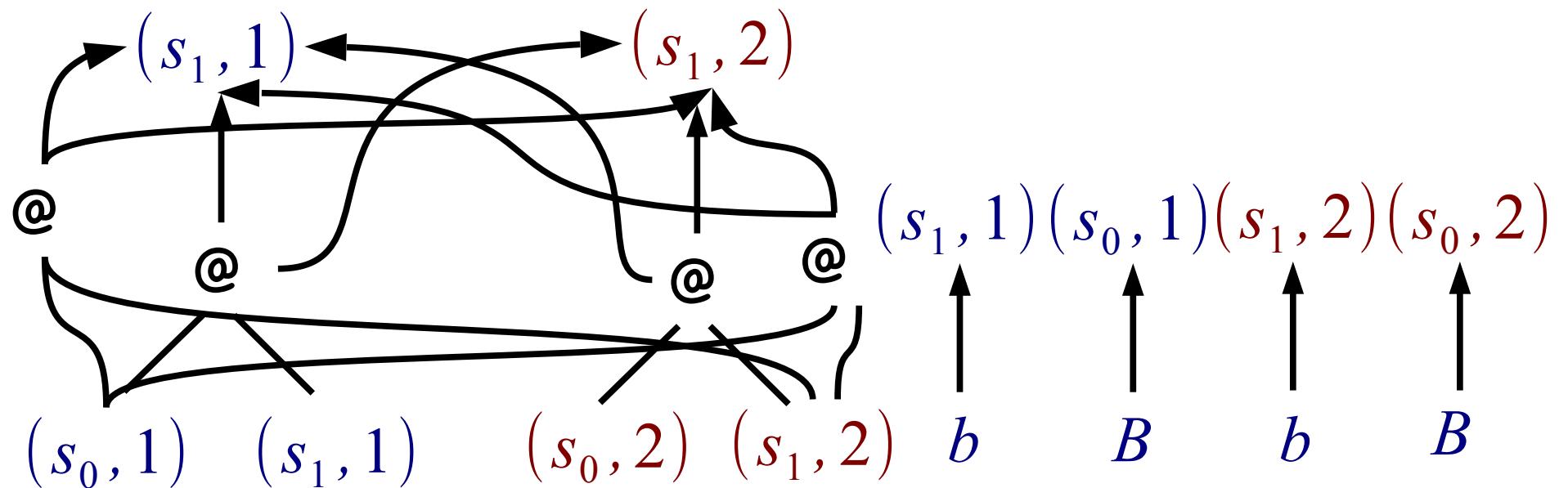
```
@ s0 s1 →B s1 b →B s1 B →B s0
```



Cloning (2-copies) states and transitions of B

Example: Abstraction Refinement

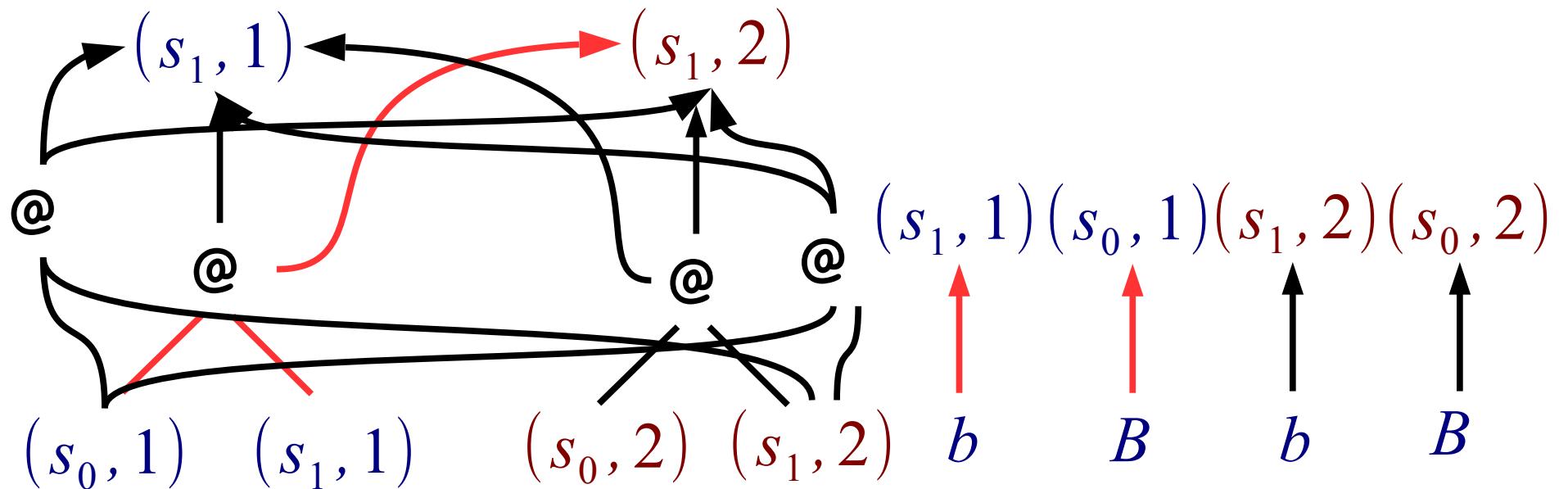
```
@ s0 s1 →B s1 b →B s1 B →B s0
```



Those transitions are candidates
for the refined automaton B'

Example: Abstraction Refinement

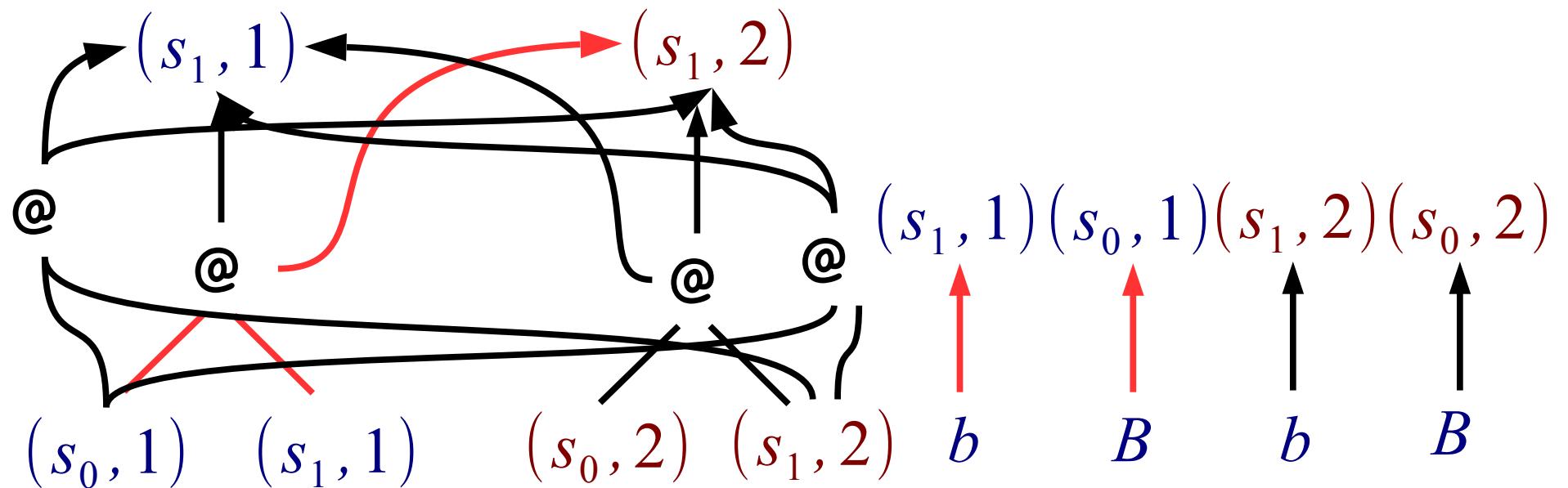
```
@ s0 s1 →B s1 b →B s1 B →B s0
```



```
@(s0, 1)(s1, 1) →B' (s1, 2) b →B' (s1, 1) B →B' (s0, 1)
```

Example: Abstraction Refinement

$$@\left(s_0, 1\right)\left(s_1, 1\right) \rightarrow_{B'} \left(s_1, 2\right) \quad b \rightarrow_{B'} \left(s_1, 1\right) \quad B \rightarrow_{B'} \left(s_0, 1\right)$$



The constraint is satisfied i.e., $\delta_{B'}(@Bb) \neq \delta_{B'}(b)$

How to Refine Abstraction

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3. If failed, increase k to $k+1$ and go to 1

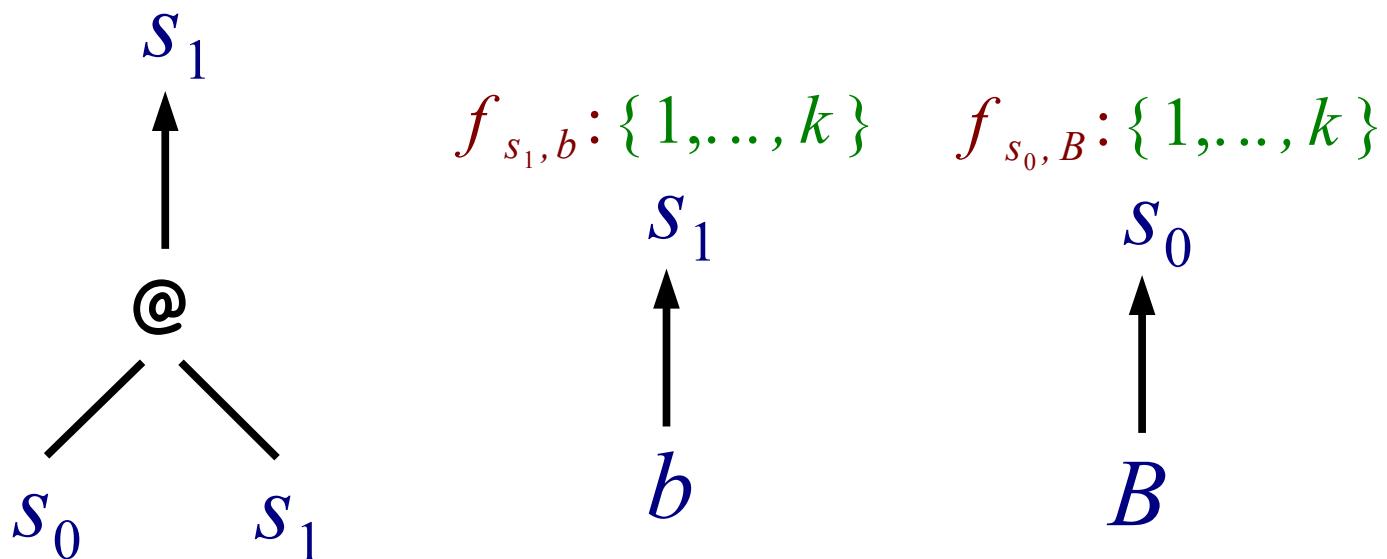


Reduced to SMT Solving for formulas
of uninterpreted functions

Example: Refinement by SMT Solving

$$b \rightarrow_B s_1 \quad B \rightarrow_B s_0 \quad @ \quad s_0 \ s_1 \rightarrow_B s_1$$

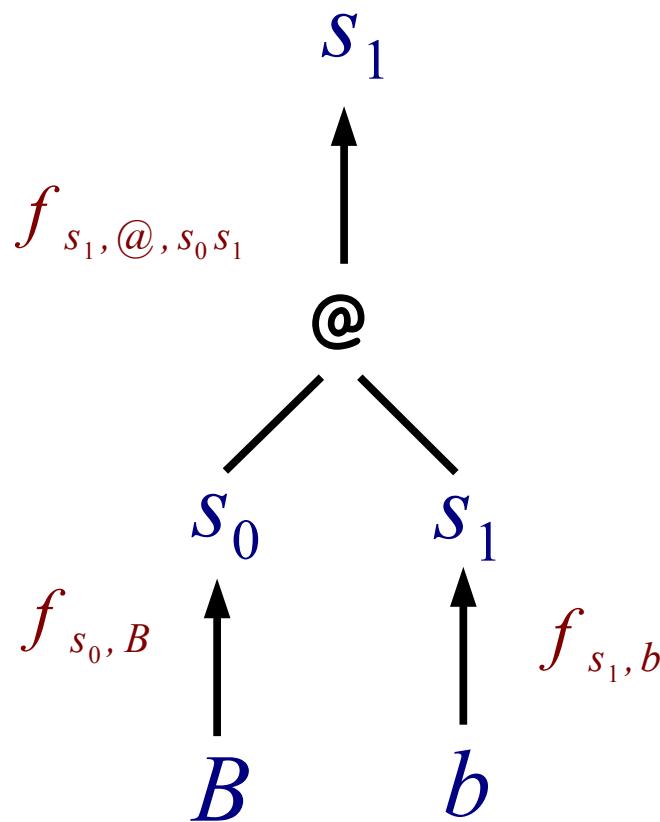
$$f_{s_0, @, s_1 s_2} : \{1, \dots, k\}^2 \rightarrow \{1, \dots, k\}$$



Generate an uninterpreted function on a finite domain $\{1, \dots, k\}$ for each transition of B

Example: Refinement by SMT Solving

$$b \rightarrow_B s_1 \quad B \rightarrow_B s_0 \quad @\ s_0\ s_1 \rightarrow_B s_1$$



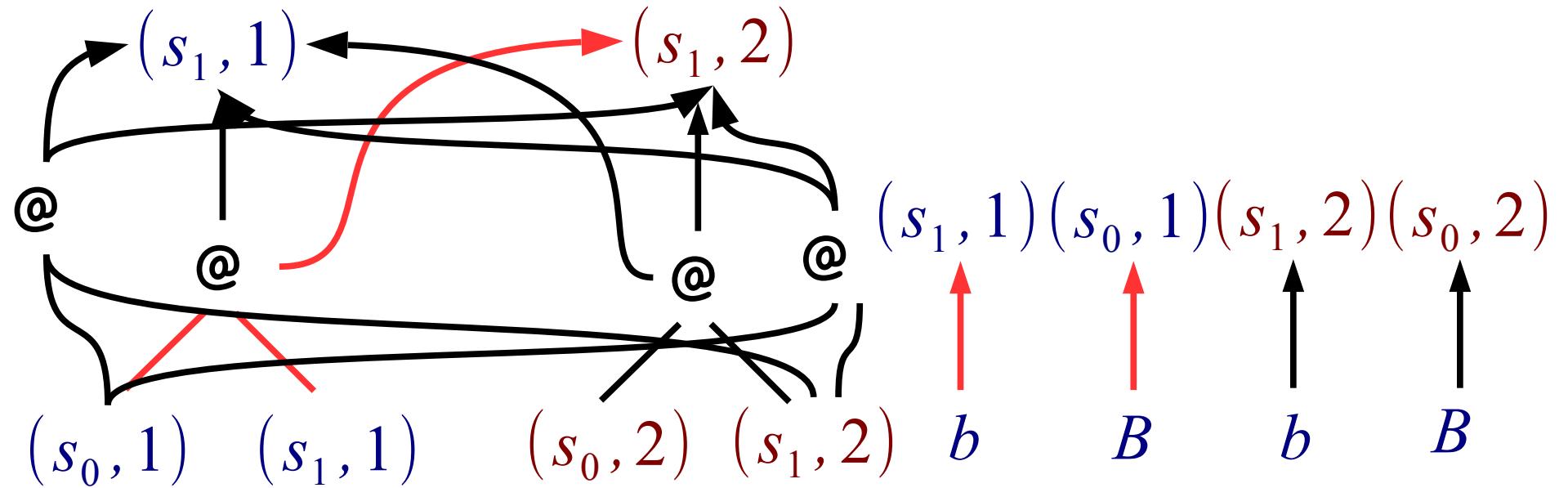
Refine B such that $\delta_B(@Bb) \neq \delta_B(b)$



SMT solving for the formula of
 $f_{s_1, @, s_0 s_1}(f_{s_0, B}, f_{s_1, b}) \neq f_{s_1, b}$

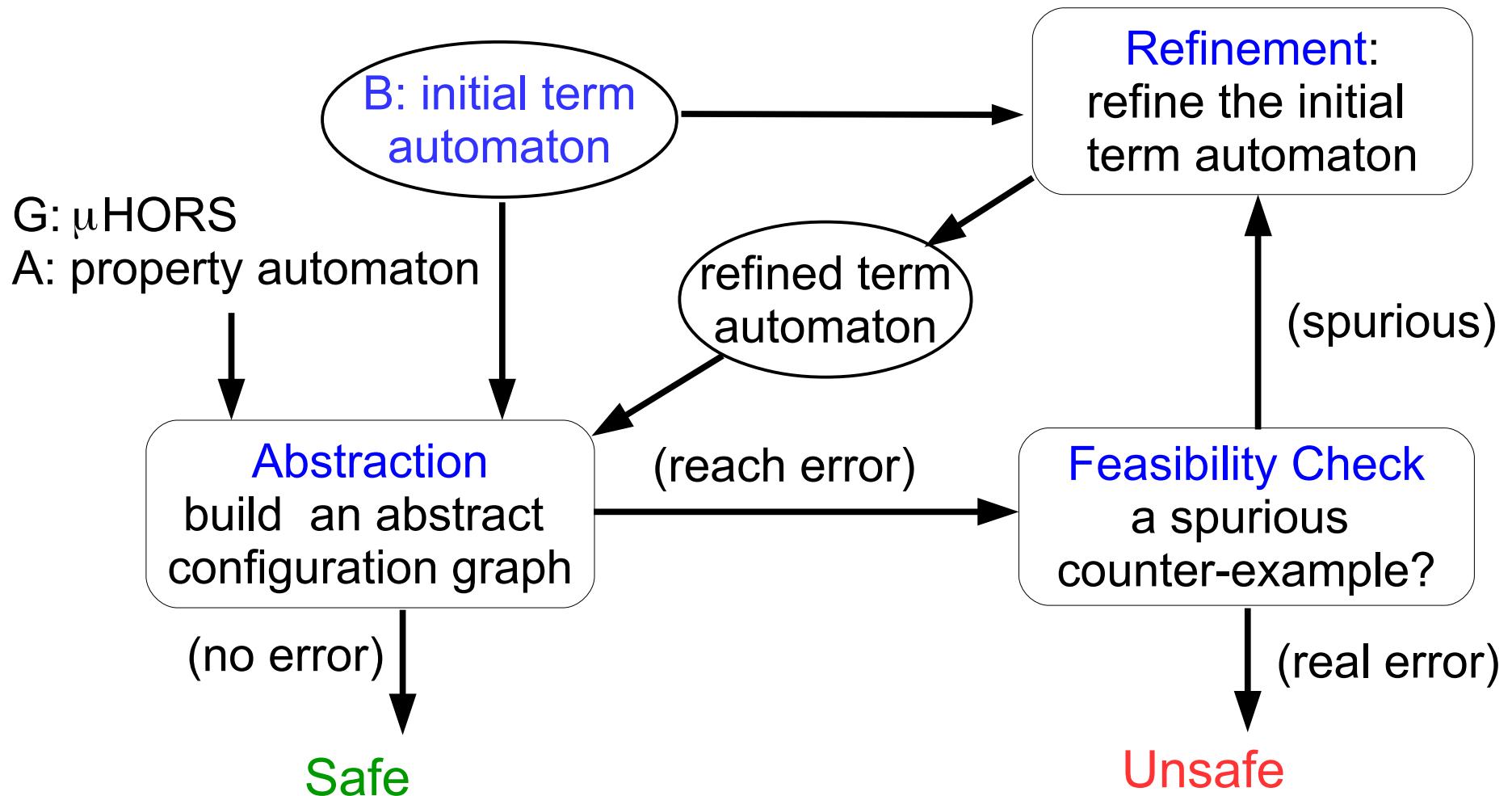
Example: Refinement by SMT Solving

$$f_{s_1, b} = 1 \quad f_{s_0, B} = 1 \quad f_{s_0, @, s_1 s_2}(1, 1) = 2 \quad f_{s_0, @, s_1 s_2}(i, j) = 1 (i \neq 1 \vee j \neq 1)$$



$$b \rightarrow_{B'} (s_1, f_{s_1, b}) \quad B \rightarrow_{B'} (s_0, f_{s_0, B}) \quad @ (s_0, i) (s_1, j) \rightarrow_{B'} (s_1, f_{s_0, @, s_1 s_2}(i, j))$$

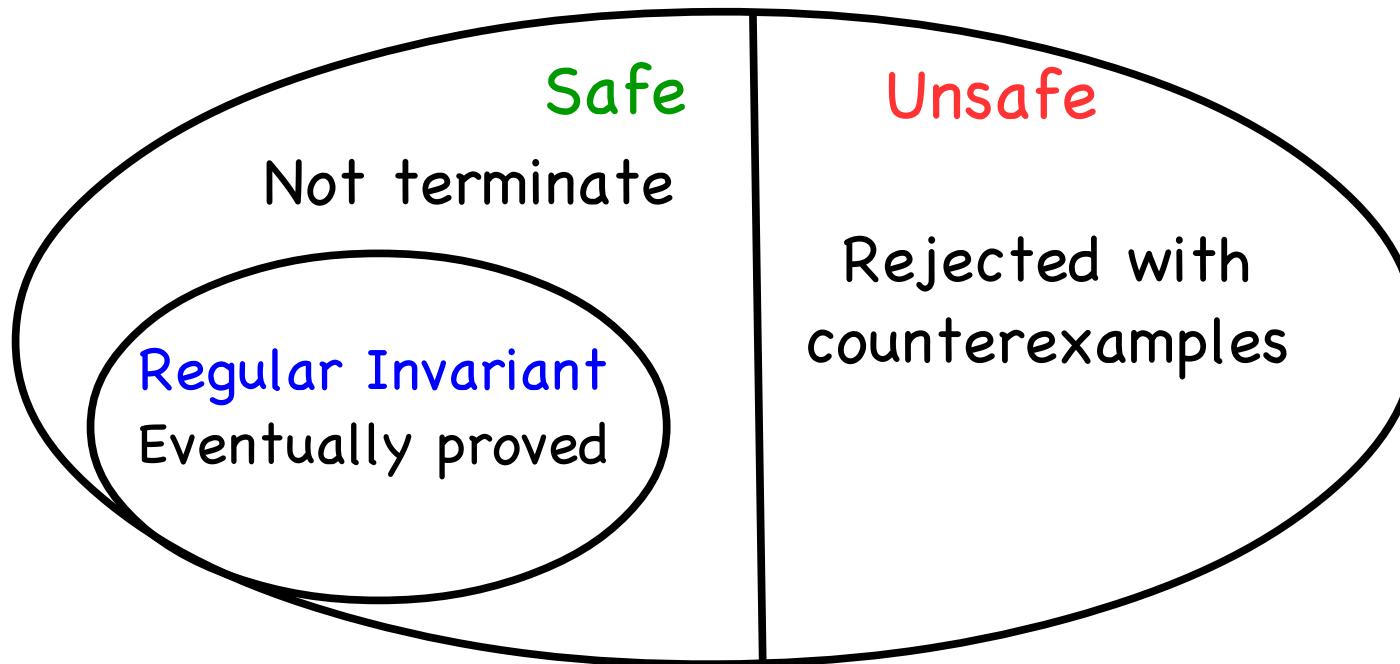
Our Approach: Summary of Key Ideas



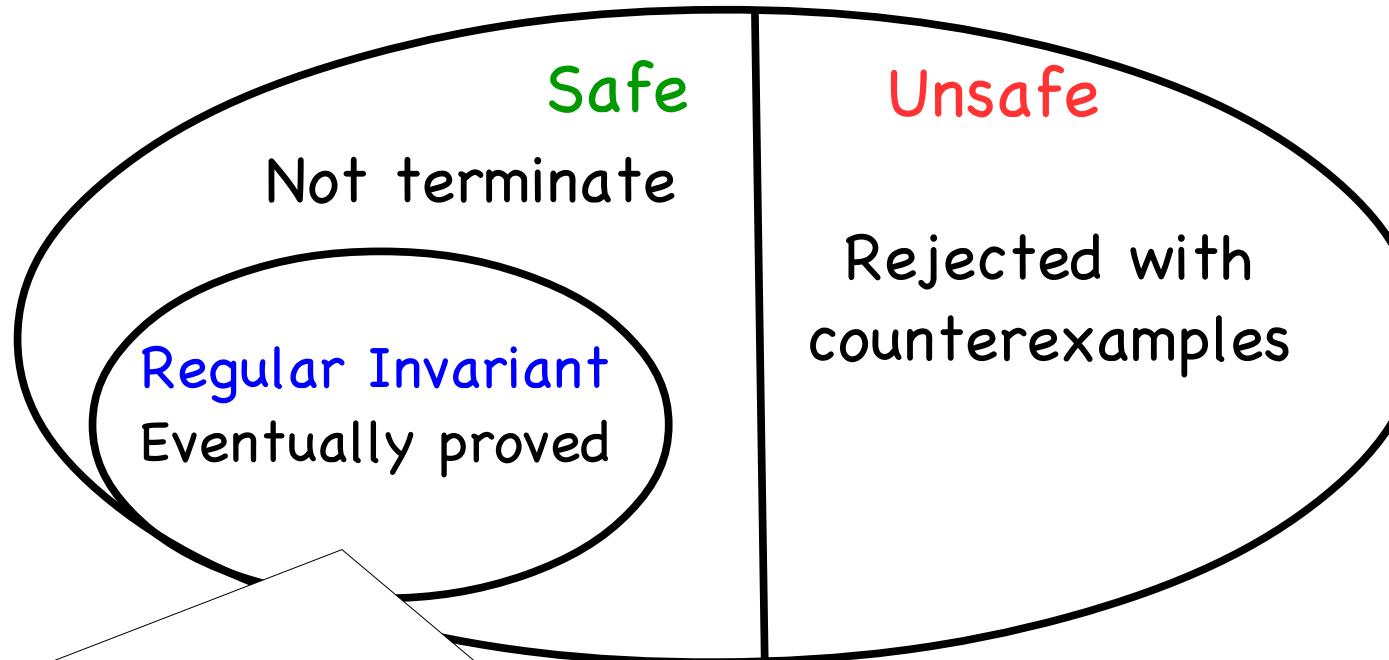
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 - Example for abstraction and refinement
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- Implementation and experiments
- Conclusion

Properties of Our Procedure



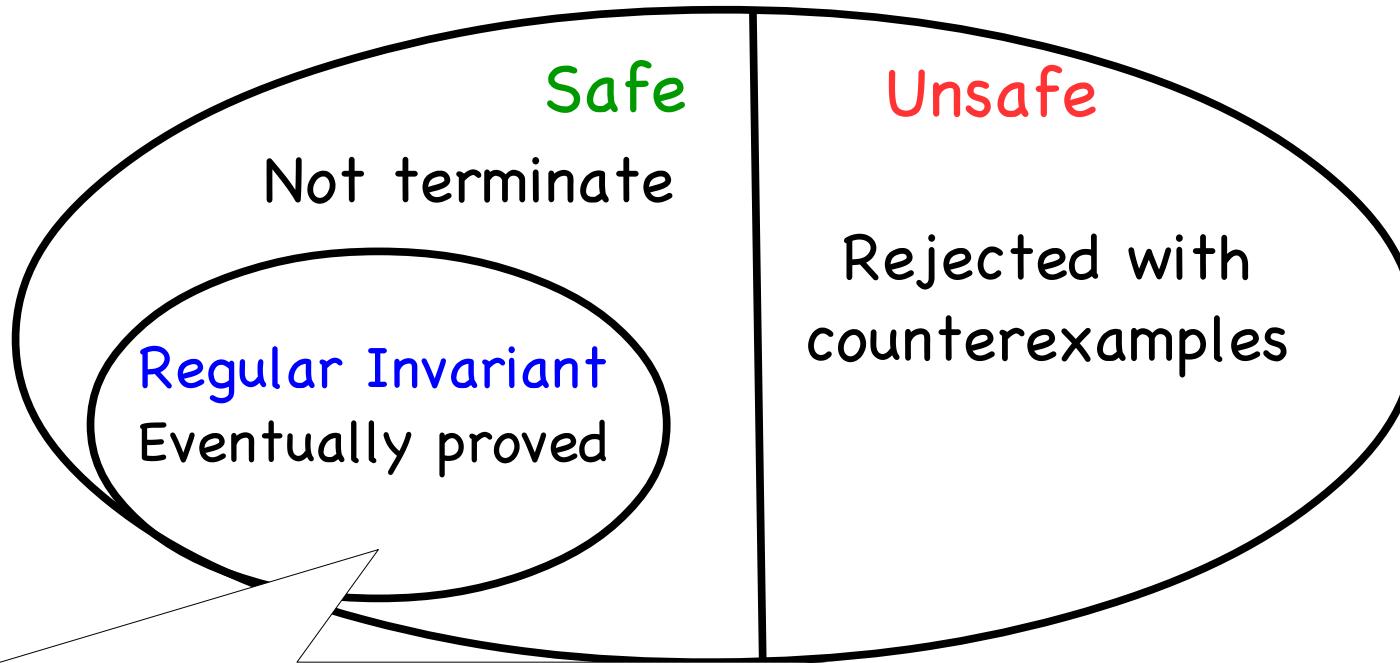
Properties of Our Procedure



Regular invariant I is a regular set of term trees satisfying:

1. $S \in I$
2. $t' \in I$ if $\exists t. t \rightarrow_G t' \wedge t \in I$
3. I contains no invalid term trees

Properties of Our Procedure



Relatively Complete:

A program P is proved safe \Leftrightarrow
There exists a regular invariant I

Incompleteness:

There exists a safe program with no regular invariants

Procedure

Safe

Not terminate

Unsafe

Rejected with counterexamples

Regular Invariant
Eventually proved

Relatively Complete:

A program P is proved safe \Leftrightarrow
There exists a regular invariant I

Outline

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- Related work and conclusion

Implementation

- MuHorSar: model checker for μ HORS by the automaton-based abstraction refinement
 - Z3 for SMT solving of uninterpreted functions
 - A translator from multi-threaded boolean programs with recursion to μ HORS
 - Examine ways of building the initial term automaton by Sorts and Horsat
 - HorSat (backward saturation-based procedure for simply-typed HORS model checking [B., K., CSL13])
- * Reuse the translator from Featherweight Java to μ HORS [K., I., ESOP13]

Example

Term Automata Built by Sorts

$S \rightarrow F F b$	$B h x \rightarrow b(hx)$
$F f g \rightarrow a(g(g c))(f f(Bg))$	
$S : o, B : (o \rightarrow o) \rightarrow o \rightarrow o$	
$F : \mu \alpha. \alpha \rightarrow (o \rightarrow o) \rightarrow o$	

If ζ_o is the initial state,
it accepts terms of sort o

$a \rightarrow_B \zeta_{o \rightarrow o \rightarrow o}$
 $b \rightarrow_B \zeta_{o \rightarrow o} \quad c \rightarrow_B \zeta_o$
 $B \rightarrow_B \zeta_{(o \rightarrow o) \rightarrow o \rightarrow o}$
 $F \rightarrow_B \zeta_\kappa \quad S \rightarrow_B \zeta_o$
where $\kappa = \mu \alpha. \alpha \rightarrow (o \rightarrow o) \rightarrow o$

$\text{@ } \zeta_\kappa \zeta_\kappa \rightarrow_B \zeta_{(o \rightarrow o) \rightarrow o}$
 $\text{@ } \zeta_{o \rightarrow o \rightarrow o} \zeta_o \rightarrow_B \zeta_{o \rightarrow o}$
 $\text{@ } \zeta_{(o \rightarrow o) \rightarrow o} \zeta_{o \rightarrow o} \rightarrow_B \zeta_o$
 $\text{@ } \zeta_{o \rightarrow o} \zeta_o \rightarrow_B \zeta_o$
 $\text{@ } \zeta_{(o \rightarrow o) \rightarrow o \rightarrow o} \zeta_{o \rightarrow o} \rightarrow_B \zeta_{o \rightarrow o}$

Implementation

- Multi-step model checking
 - 1. Run HorSat up to a bounded step of saturation
 - 2. Get a type environment that finitely represents a subset of terms reducible to invalid terms
 - 3. Build term automata from the type environment
- Building the initial term automaton (please see our paper) and Horsat
 - HorSat (backward saturation-based procedure for simply-typed HORS model checking [B., K., CSL13])
- * Reuse the translator from Featherweight Java to μ HORS [K., I., ESOP13]

Experimental Results

for verifying Benchmarks from [K.,I., ESOP13]

Bench	#G	#A	R	MuHORSAR (#Ar)	RTRECS
\mathcal{G}_1	2	2	Y	0.006	0.009
\mathcal{G}_2	3	2	Y	0.004	0.010
Thread	9	5	Y	0.013	0.181
Pred	15	1	Y	0.008	0.010
Ski1	22	1	N	0.008	0.005
Ski2	25	1	Y	0.008	0.010
L-append	30	1	Y	0.013	0.012
L-map	182	1	Y	0.561	0.189
L-app-map	212	1	Y	0.840	0.279
L-even	87	1	Y	0.077	0.021
L-filter	122	1	Y	1.454 (6)	0.429
L-risers	122	1	Y	1.450 (6)	0.431
Twofiles	21	5	Y	0.027	4.390

- #G: number of rules, #A: state size of tree automaton, #R: result
- Time excludes the translation from Featherweight Java to uHORS
- Mac OS X v.10.9.2, 1.7 GHz Intel Core i7 processor, 8GB RAM

Experimental Results

for verifying new Featherweight Java programs

Bench	#G	#A	R	MUHORSAR (#Ar)	RTRECS
stack	33	1	Y	0.040	0.207
		3		0.039	3.435
		5		0.044	23.292
stack-br	39	1	Y	0.396 (13)	-
		3		0.403 (13)	-
		5		0.397 (13)	-
queue	56	1	Y	0.169	0.143
		3		0.173	2.140
		5		0.164	12.633
queue-br	61	1	Y	0.249 (2)	-
		3		0.249 (2)	-
		5		0.249 (2)	-
queue-pc	104	1	Y	1.160	0.211
		3		1.218	0.642
		5		1.137	1.648
2stack-e	52	1	N	0.105	-
		5		0.105	-
2stack-pc	88	1	Y	4.202	0.498
		5		4.176	1.262
		7		4.182	2.132
nat	35	1	Y	17.810 (147)	0.288

"-": time out for 5 mins

* MuHorSar scales well as the size of the property automaton increases, but RTRecs does not

Experimental Results

for Multi-threaded boolean programs with recursion

Bench	#G	#A	R	MUHOR SAR (#Ar)	RTRECS
locks-e	103	5	N	0.160	-
dining-e	135	5	N	2.857 (28)	-
dining-sp-e	193	5	N	10.997 (90)	-
bluetooth	129	1	N	2.300 (25)	-
bluetooth-v	158	1	N	272.626 (326)	-
locks	95	5	Y	0.779	-
plotter	88	4	Y	0.195	1.189
peterson	74	2	Y	3.331 (2)	-
peterson-d	80	9	Y	-	-
dekker	94	2	Y	-	-
pc-monitor	71	5	Y	0.338	-
pc-sp	111	5	Y	2.250	-
dining-sp	303	5	Y	-	-

- * MuHorSar is effective in counterexample finding but RTRecs does not

Experimental Results

for Multi-threaded boolean programs with recursion

Bench	#G	#A	R	MuHORsar (#Ar)	RTRecs (#Ar)
locks-e	103	5	N	0.160	0.161
dining-e	135	5	N	2.857 (28)	0.582
dining-sp-e	193	5	N	10.997 (90)	0.961
bluetooth	129	1	N	2.300 (25)	1.693 (9)
bluetooth-v	158	1	N	272.626 (326)	4.223 (20)
locks	95	5	Y	0.779	0.247
plotter	88	4	Y	0.195	0.251
peterson	74	2	Y	3.331 (2)	0.467
peterson-d	80	9	Y	-	6.971 (5)
dekker	94	2	Y	-	0.473
pc-monitor	71	5	Y	0.338	0.217
pc-sp	111	5	Y	2.250	0.207
dining-sp	303	5	Y	-	18.963

- * MuHorSar is effective in counterexample finding but RTRecs does not

Outline

- Background
 - μ HORS model checking
 - Example: application to OO verification
- New model checking procedure for μ HORS
 - Overview and key ideas
 - Example for abstraction and refinement
 - Properties of the procedure
- Implementation and experiments
- Related work and conclusion

Related Work

- Inspired by two state-of-the-art procedures for ordinary (simply-typed) HORS
 - Preface: type-directed abstraction refinement [Ramsey+, POPL14]
 - HorSat: backward saturation-based procedure (not terminate for μ HORS) [Broadbent, Kobayashi, CSL13]
- Tree automata completion [Jacquemard, RTA96]
 - Reachability analysis of term rewriting systems
 - Applicable to μ HORS model checking, but no discussion on relative completeness condition

Conclusion

- A new model checking procedure for μ HORS based on automata-based abstraction refinement
 - ✓ Sound & relatively-complete w.r.t. regular invariants
 - ✓ Often scales better than RTRecs [K., I., ESOP13]
- Relative completeness by regular invariants is equivalent to that by typability (in a recursive intersection type system)
- Application to OO and multi-threaded boolean programs with recursion